

# A PARC. DERIVATAK A TELJES KÖRÜ-TÖL FÜGGENEK

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$$X: S \hookrightarrow G \subset \mathbb{R}^N, \quad Y: S \hookrightarrow H \subset \mathbb{R}^N$$

$Y_{x_i}, X_{y_j}$  left diff

$$T_{ydy} = \frac{\partial f}{\partial x} = \frac{\partial f}{\partial y} \frac{\partial y}{\partial x} = \frac{\partial f}{\partial y} \left[ \frac{\partial x}{\partial y} \right]^{-1}$$

$$E \text{ ofordyhat: } x_1 = y_1 \quad (\text{left } x_{i_0} = y_{j_0})$$

Egyek elemek ALTALBAN  $\frac{\partial f}{\partial x_1} \neq \frac{\partial f}{\partial y_1}$  HA  $X, Y$  *most szokatlan*

$$\frac{\partial f}{\partial x_1} = \left[ \frac{\partial f}{\partial x} \frac{\partial y}{\partial x} \cdot 1. \text{ tagja } \right] = \frac{\partial f}{\partial y_1} \frac{\partial y_1}{\partial x_1} + \frac{\partial f}{\partial y_2} \frac{\partial y_2}{\partial x_1} + \dots + \frac{\partial f}{\partial y_n} \frac{\partial y_n}{\partial x_1}$$

$$\underline{\underline{PE}} \quad X: \mathbb{R}^2 \hookrightarrow \mathbb{R}^2 \quad x_1 \left( \begin{smallmatrix} f \\ \eta \end{smallmatrix} \right) = f, \quad x_2 \left( \begin{smallmatrix} f \\ \eta \end{smallmatrix} \right) = \eta$$

$$Y: \mathbb{R}^2 \hookrightarrow \mathbb{R}^2 \quad y_1 \left( \begin{smallmatrix} f \\ \eta \end{smallmatrix} \right) = f, \quad y_2 \left( \begin{smallmatrix} f \\ \eta \end{smallmatrix} \right) = f + \eta \quad \begin{matrix} x_1 = y_1 \\ y_2 = x_1 + x_2 \end{matrix}$$

$$\frac{\partial f}{\partial x_1} = \frac{\partial f}{\partial y_1} \frac{\partial y_1}{\partial x_1} + \frac{\partial f}{\partial y_2} \frac{\partial y_2}{\partial x_1} = \frac{\partial f}{\partial y_1} \cdot 1 + \frac{\partial f}{\partial y_2} \cdot 1$$

$$f := x_2 \Rightarrow \frac{\partial f}{\partial x_1} = \frac{\partial x_2}{\partial x_1} = 0, \quad \frac{\partial f}{\partial y_1} = \frac{\partial f}{\partial x_1} - \frac{\partial f}{\partial y_2} = 0 - 1 = \underline{\underline{-1}}$$

$\begin{matrix} \parallel \\ y_2 = y_1 \end{matrix}$

Endlichkeit  $(X, d)$  metr. für  $\alpha \geq 0$

$$\text{vol}_{\alpha, \varepsilon} A := \inf \left\{ \sum_{k=1}^{\infty} (\text{diam } A_k)^\alpha : \bigcup_{k=1}^{\infty} A_k \supset A, \text{diam } A_k \leq \varepsilon \right\}$$

$$\text{vol}_{\alpha, \varepsilon} A \nearrow \underline{\text{vol}_{\alpha} A} \quad (\varepsilon > 0, A \subset X).$$

Hausdorff mittels  $\alpha$ -dimensionen (!)

$$1) \exists! \alpha (= \dim A) \quad \begin{aligned} \text{vol}_{\beta} A &= \infty \text{ für } \beta < \alpha \\ \text{vol}_{\beta} A &= 0 \text{ für } \beta > \alpha \end{aligned}$$

Be   $A_0 = \triangle_1$   $A_n = \triangle_{1/2^n}$   $A := \bigcap_{n=1}^{\infty} A_n$

$$\dim A : A_n = \bigcup \left\{ 3^n \text{ db } \frac{1}{2^n} \dim \Delta \right\}$$

$$\text{vol}_{\alpha, 1/2^n} A = 3^n \cdot (1/2^n)^\alpha = \begin{cases} \infty & 3/2^{\alpha} > 1 \\ 0 & 3/2^{\alpha} < 1 \end{cases}$$

$$\dim A = \left[ \alpha : 3^n / 2^{\alpha n} = 1 \right] = \underline{\underline{\frac{\log 3}{\log 2}}}$$

2) Carathéodory Hülle: A kompakt  $\Rightarrow A$   $\text{vol}_{\alpha}$ -messbar  
 $[\text{vol}_{\alpha} A = \text{vol}_{\alpha}(A \cap S) + \text{vol}_{\alpha}(A \setminus S) \quad \forall S \subset X]$

3) Hausdorff Hülle:  $X = \mathbb{R}^N$   $\Delta = (\text{Eukl. TAU}) \Rightarrow$

$$\text{vol}_N A = \frac{\omega_N}{2^N} \underbrace{\text{Vol}_N A}_{\nearrow} \quad [\text{HAGGUNA/KWIK N-DIM TELEGRAPHIE}]$$

$$\omega_N = [N\text{-dim Euklidischer TERPOMASS}] =$$

$$= \frac{\pi^{N/2}}{\Gamma(1 + \frac{N}{2})}$$

$$\Gamma(z) = \int_{t=0}^{\infty} t^{z-1} e^{-t} dt \quad (\text{EULER})$$

$$\Gamma(n) = (n-1)! \quad (n=1, 2, \dots)$$

Integration  $S \subset X$ ,  $f: S \rightarrow \mathbb{R}$  ( $S$  kompakt,  $f$  FURT)

$$\int_{p \in S} f(p) \text{Vol}(dp) = \lim_{\substack{\bigcup_k A_k = S \\ \text{diam } A_k < \varepsilon \\ p_k \in A_k}} \sum_k f(p_k) \text{Vol}_N(A_k)$$

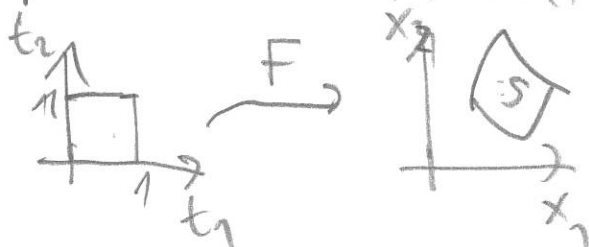
Teil  $X = \mathbb{R}^N$   $\lambda = (\text{Eukl})$

$$S = f([0,1]^N) \quad F: [0,1]^N \rightarrow S \subset \mathbb{R}^N \text{ bij}$$

$$\int_{p \in S} f(p) d\text{Vol}_N(p) = \int_{t_1=0}^1 \dots \int_{t_N=0}^1 f(F(t_1, \dots, t_N)) \cdot J_{qc}(F) \cdot dt_1 \dots dt_N$$

$$J_{qc}(F) : \begin{pmatrix} t_1 \\ \vdots \\ t_N \end{pmatrix} \mapsto \left[ \frac{\partial F_i}{\partial t_j} \right]_{i,j=1}^N \left[ \begin{pmatrix} t_1 \\ \vdots \\ t_N \end{pmatrix} \text{ NEURER} \right]$$

KOORD - INTERPRETATION:



$S$ -en KOORD:

$$T: p = F\left(\begin{pmatrix} t_1 \\ \vdots \\ t_N \end{pmatrix}\right) \mapsto \begin{pmatrix} t_1 \\ \vdots \\ t_N \end{pmatrix}$$

$$T = F^{-1}$$

$$\underline{\underline{I}} \quad J_{\text{sc}}(F) = \frac{\partial X}{\partial T} \quad \left( X = \begin{pmatrix} x_1 \\ \vdots \\ x_N \end{pmatrix} \quad x_k = \begin{pmatrix} x_{k1} \\ \vdots \\ x_{kN} \end{pmatrix} \mapsto f_k \right)$$

$$\underline{\underline{b}} \quad p \in S \sim \mathcal{M} \quad X(p) = \begin{bmatrix} x_1(p) \\ \vdots \\ x_N(p) \end{bmatrix} = \begin{bmatrix} F_1(t_1/p, \dots, t_N/p) \\ \vdots \\ F_N(t_1/p, \dots, t_N/p) \end{bmatrix}$$

$$\underline{\underline{KSV}} \quad \int_{p \in S} f(p) \text{Vol}_N(dp) = \int_{t \in [0,1]^N} {}^T f(t_1, \dots, t_N) \underbrace{\left( \frac{\partial X}{\partial T} \right)}_{dt_1 \dots dt_N} dt$$

FELDMAN-FORMULA

Einbettung  $\mathcal{A}$  ist:  $K \leq N$ ,  $F: [0,1]^K \rightarrow \mathbb{R}^N$  f.a. diff  
 $F: (0,1)^K \leftrightarrow S$   $\text{rank} \left[ \frac{\partial F_i}{\partial t_j} \right]_{i=1}^N \begin{smallmatrix} N \\ K \end{smallmatrix} = K \text{ (max)}$

$f: S \rightarrow \mathbb{R}$  fkt

$$\int_{p \in S} f(p) d\text{Vol}_K(p) = \int_{t_1=0}^1 \dots \int_{t_K=0}^1 f(F(t_1, \dots, t_K)) \underbrace{J_{\text{sc}}(F)}_{dt_1 \dots dt_K} dt_1 \dots dt_K$$

$$\underline{\underline{J_{\text{sc}} F}} := \sqrt{\det \left( \frac{\partial F}{\partial T} \right)^T \left( \frac{\partial F}{\partial T} \right)} \quad \frac{\partial F}{\partial T} = \left[ \frac{\partial F_i}{\partial t_j} \right]_{i=1}^N \begin{smallmatrix} N \\ K \end{smallmatrix}$$

Koord-vert  $\int_{p \in S} f(p) \text{Vol}_K(dp) = \int_{t \in [0,1]^K} {}^T f(t) \left\{ \det \left( \frac{\partial X}{\partial T} \right) \left| \frac{\partial X}{\partial T} \right|^T \right\}^{1/2} dt$

Messgerät Nehmen  $S = (0,1)^K$ , dann  $S = A \subset \mathbb{R}^K$  Wichtig

# INTEGRALS KOORDINATEN

(Bq)

$X: S \leftrightarrow \mathbb{R}^N$  beschreibt koord

d. TAVOLSAAT  $\rightarrow$  Vol<sub>k</sub> k-dim. TEFEGAT (totaal  $k \geq 0$ !!)

$$\int_{p \in A} f(p) \text{Vol}_N(dp) = \int_{\begin{pmatrix} x_1 \\ \vdots \\ x_N \end{pmatrix} \in A} f(x_1, \dots, x_N) dx_1 \dots dx_N$$

$\underline{\text{I}}$   $Y: A \leftrightarrow G \subset \mathbb{R}^N$  beschreibt A-w

$$\int_{p \in A} f(p) \text{Vol}_N(dp) = \int_{\begin{pmatrix} y_1 \\ \vdots \\ y_N \end{pmatrix} \in G} Y f(y_1, \dots, y_N) \left| \det \frac{\partial X}{\partial Y} \right| dy_1 \dots dy_N$$

pe  $\mathcal{I} := \int_{x=-\infty}^{\infty} e^{-x^2} dx$  KIAAN/TAFIT

$$\mathcal{I}^2 = \int_{x=-\infty}^{\infty} e^{-x^2} dx \int_{y=-\infty}^{\infty} e^{-y^2} dy = \int_{(x,y) \in \mathbb{R}^2} e^{-(x^2+y^2)} dx dy$$

$P = \begin{pmatrix} r \\ \varphi \end{pmatrix}$  polinkoord  $x = r \cos \varphi, y = r \sin \varphi$   $\frac{\partial X}{\partial P} = \begin{pmatrix} \cos \varphi & -r \sin \varphi \\ \sin \varphi & r \cos \varphi \end{pmatrix}$

$$\mathcal{I}^2 = \int_{p \in \mathbb{R}^2} e^{-(X+Y)(P)} \text{Vol}_2(dp) = \int_{\substack{r > 0 \\ -\pi < \varphi < \pi}} e^{-r^2} \underbrace{\left| \det \frac{\partial X}{\partial P} \right|}_r d\tau d\varphi =$$

$$= 2\pi \int_{r=0}^{\infty} e^{-r^2} \cdot r dr = 2\pi \int_{\substack{s=r^2 \\ ds=2rdr}}^{\infty} e^{-s} \cdot \frac{1}{2} ds = \underline{\underline{\pi}}$$

$\mathcal{I} = \sqrt{\pi}$

K-dim Felder K-dim TERNULAT

(24)

$X: \mathbb{R}^N \leftrightarrow \mathbb{R}^N$  ternulater D-koord  $X = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} = \text{Id}$

d ternulater TAU  $\mathbb{R}^N$ -a

$S \subset \mathbb{R}^N$  K-dim Felder

$$S = \left\{ F \begin{pmatrix} t_1 \\ \vdots \\ t_k \end{pmatrix} : \begin{pmatrix} t_1 \\ \vdots \\ t_k \end{pmatrix} \in G \right\} \quad F: G \leftrightarrow S$$

$F^{-1}: S \leftrightarrow G$  K-dim KOORD F TERNULAT

$$\begin{bmatrix} F_1(t_1, \dots, t_k) \\ \vdots \\ F_N(t_1, \dots, t_k) \end{bmatrix}$$

$x_1, \dots, x_N | S$  ternulater N-dim koord fgr

I  $f: S \rightarrow \mathbb{R}$   $f \circ F$  folgt DIFF

$f_i = F(x_i | S)$  folgt diff,  $\frac{\partial X}{\partial F} = \left[ \frac{\partial F_i}{\partial t_j} \right]_{i=1, j=1}^{N, k}$  folgt  $1346=k$

$$\int_{p \in S} f(p) dV_{\mathbb{R}^N_k}(p) =$$

$$= \int_{\substack{F \begin{pmatrix} t_1, \dots, t_k \end{pmatrix} \\ \begin{pmatrix} t_1, \dots, t_k \end{pmatrix}^T \in G}} f(t_1, \dots, t_k) \left\{ \det \left( \left[ \frac{\partial X}{\partial F} \right]^T \left[ \frac{\partial X}{\partial F} \right] \right) \right\}^{1/2} dt_1 \dots dt_k$$

Messung vernul  $X|S$  ternulater is, nicht  
"Ternulater KORDINATN'EN"

pe GEMITRAGOMATIS TERNULAT

(Naggen nen tnu)

Gegenbb f-nd GEMB



$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} \cos \theta_0 \\ \sin \theta_0 \cos \phi_0 \\ \sin \theta_0 \sin \phi_0 \end{bmatrix}$$

$$\begin{bmatrix} \cos \theta \\ \sin \theta \cos \phi \\ \sin \theta \sin \phi \end{bmatrix} \cdot \begin{bmatrix} \cos \theta_0 \\ \sin \theta_0 \cos \phi_0 \\ \sin \theta_0 \sin \phi_0 \end{bmatrix} = 1$$

$$\begin{aligned} 0 &= \cos \theta_0 \cos \theta + \sin \theta_0 \cos \phi_0 \sin \theta \cos \phi + \sin \theta_0 \sin \phi_0 \sin \theta \sin \phi = \\ &= \cos \theta_0 \cos \theta + \sin \theta_0 \sin \theta [\cos \phi_0 \cos \phi + \sin \phi_0 \sin \phi] = \\ &= \cos \theta_0 \cos \theta + \sin \theta_0 \sin \theta \cos(\phi - \phi_0) \end{aligned}$$

$$0 < \phi < \pi \quad \text{FIXED}$$

$$\theta = \theta(\phi) \quad \cos \theta_0 \cos \theta(\phi) + \sin \theta_0 \sin \theta(\phi) \cos(\phi - \phi_0) = 0$$

$$1 + \tan \theta_0 \tan \theta(\phi) \cos(\phi - \phi_0) = 0$$

$$\tan \theta(\phi) = \frac{\tan \theta_0}{\cos(\phi - \phi_0)}$$

$$T: \begin{bmatrix} \theta \\ \phi \end{bmatrix} \mapsto \begin{bmatrix} \cos \theta \\ \sin \theta \cos \phi \\ \sin \theta \sin \phi \end{bmatrix}$$

$$\frac{\partial X}{\partial T} = \begin{bmatrix} -\sin \theta & 0 \\ \cos \theta \cos \phi & -\sin \theta \sin \phi \\ \cos \theta \sin \phi & \sin \theta \cos \phi \end{bmatrix}$$

$$\left[ \frac{\partial X}{\partial T} \right]^T \left[ \frac{\partial X}{\partial T} \right] = \begin{bmatrix} 1 & 0 \\ 0 & \sin^2 \theta \end{bmatrix}$$

$$A_{\pi_5} = \int_0^\pi \int_0^\phi \sin \theta \, d\theta \, d\phi = \int_0^\pi [\cos \theta(\phi) - 1] \, d\phi =$$

$$\left. \begin{array}{c} \phi=0 \quad \theta=0 \\ \sin \theta - \tan \theta \cos \phi \end{array} \right|_{\phi=0}^{\phi=\pi} = \int_0^\pi \frac{d\phi}{\sqrt{1 + \frac{\tan^2 \theta_0}{\cos^2(\phi - \phi_0)}}} = \frac{(\sum \text{stokes}) - \pi}{\dots}$$

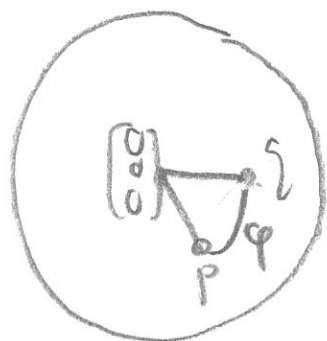
$$S := \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : x^2 + y^2 + z^2 = 1 \right\} = (x^2 + y^2 + z^2 = 1),$$

gheel  $X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} : \mathbb{R}^3 \hookrightarrow \mathbb{R}^3$  ALAPKARD  $X \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$  STB.

als tusschen  $S$ -en :

$$d_S(p, q) := \left[ \text{legste afstand p tot q via S} \right] =$$

S-bel: gorte hoes



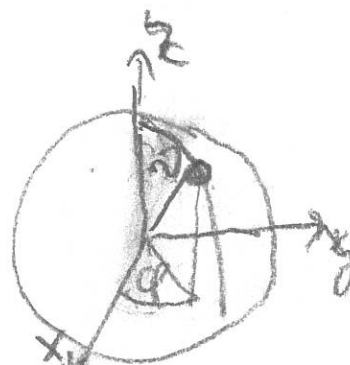
$$= \arccos \langle X(p), X(q) \rangle =$$

$$= \arccos [x(p)x(q) + y(p)y(q) + z(p)z(q)]$$

M NER TRIV  $\uparrow$

Euler woord

$$E = \begin{bmatrix} \cos \theta \\ \sin \theta \cos \varphi \\ \sin \theta \sin \varphi \end{bmatrix} \mapsto \begin{bmatrix} \theta \\ \varphi \end{bmatrix}$$



$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mapsto \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$\frac{\partial X}{\partial E} = \begin{bmatrix} \partial x / \partial \theta & \partial x / \partial \varphi \\ \partial y / \partial \theta & \partial y / \partial \varphi \\ \partial z / \partial \theta & \partial z / \partial \varphi \end{bmatrix}$$

$$\frac{\partial X}{\partial E} = \begin{bmatrix} -\sin \theta & 0 \\ \cos \theta \cos \varphi & -\sin \theta \sin \varphi \\ \cos \theta \sin \varphi & \sin \theta \cos \varphi \end{bmatrix}$$

# N-DIR POLARKOORD

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Euklidische

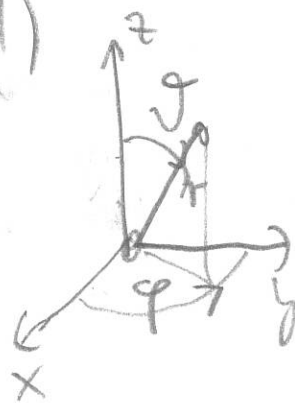
$$X: S \xleftrightarrow{\text{slk}} \mathbb{R}^2 \text{ DESCARTES KOORD}$$

$$P: S \setminus X^{-1}(\{(-\infty, 0] \times \{0\}\}) \rightarrow \mathbb{R}_{++}^2 \times (-\pi, \pi)$$

$$\begin{aligned} x &= r \cos \varphi \\ y &= r \sin \varphi \end{aligned}$$

$$P = \begin{pmatrix} r \\ \varphi \end{pmatrix}$$

3D (Euler-Koord)



$$x = [r \sin \varphi] \cdot \sin \vartheta$$

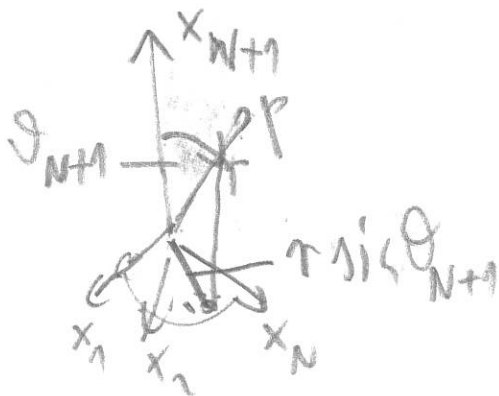
$$y = [r \cos \varphi] \sin \vartheta$$

$$z = r \cos \vartheta$$

$$0 < \vartheta < \pi, -\pi < \varphi < \pi$$

Konstruktion

N-dir  $\rightarrow$  (N+1)-dir polarkoord



$$x_{N+1} = r \cos \vartheta_{N+1} \quad -47$$

$$\begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} = (\sin \vartheta_{N+1}) \cdot \begin{bmatrix} \text{RECI} \\ \text{KOORD} \\ \text{N-DIR} \end{bmatrix}$$

Rekursion

$\rightarrow$  4D-bei

$$x_1 = r \sin \vartheta_4 [\sin \vartheta_3 \cos \varphi]$$

$$x_2 = r \sin \vartheta_4 [\sin \vartheta_3 \sin \varphi]$$

$$x_3 = r \sin \vartheta_4 [\cos \vartheta_3]$$

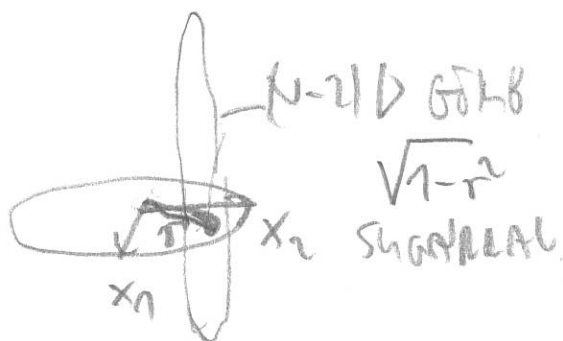
$$x_4 = r \cos \vartheta_4$$

5D-ban

$$\begin{aligned}
 x_1 &= r \cdot \sin \vartheta_5 [\sin \vartheta_4 (\sin \vartheta_3 \cdot \cos \varphi)] \\
 x_2 &= r \cdot \sin \vartheta_5 [\sin \vartheta_4 (\sin \vartheta_3 \cdot \sin \varphi)] \\
 x_3 &= r \cdot \sin \vartheta_5 [\sin \vartheta_4 (\cos \vartheta_3)] \\
 x_4 &= r \cdot \sin \vartheta_5 [\cos \vartheta_4] \\
 x_5 &= r \cdot \cos \vartheta_5
 \end{aligned}$$

Főbb Lemma:  $(\cos \varphi, \sin \varphi)$  helyett  $(\sin \vartheta_2, \cos \vartheta_2)$   
 Vagy  $\sin \vartheta_h \leftrightarrow \cos \vartheta_h$  cseré - GPS kódd.

Az N-DIM GÖMB TERFOGATA  $\omega_N$



$$\omega_N = \int_{\vartheta \in (2D \text{ gömb})} \text{Vol}_{N-2}(\sqrt{1-r^2} \text{ sz. } (N-2)D \text{ gömb}) \text{Vol}_N(d\vartheta) =$$

$$= \int_{r=0}^1 \int_{\varphi=-\pi}^{\pi} \omega_{N-2} \cdot \sqrt{1-r^2}^{N-2} \underbrace{r d\varphi dr}_{dx_1 dx_2} = \int_{s=1-r^2}^1 \frac{ds}{ds=2r dr} \quad \text{Itt } r \text{ helyére}$$

$$= 2\pi \cdot \int_{s=1}^0 \omega_{N-2} \cdot s^{\frac{N-2}{2}} \cdot \left(-\frac{1}{2} ds\right) =$$

$$= \pi \omega_{N-2} \int_{s=0}^1 s^{\frac{N-2}{2}} ds = \frac{\pi}{N/2} \cdot \omega_{N-2}$$

Rekurzió:  $\omega_0 = 2, \omega_1 = \pi, \pi_3 = \frac{\pi}{2} \cdot \omega_1 = \frac{4\pi}{3}, \pi_4 = \frac{\pi}{2} \cdot \omega_2 = \frac{\pi^2}{2}$

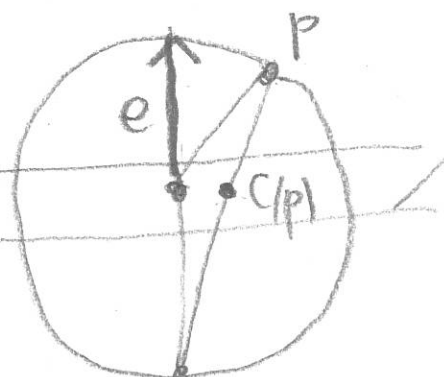
$$S = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 : x_1^2 + x_2^2 + x_3^2 = 1 \right\} \subset \mathbb{R}^3$$

$$X: \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mapsto \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad (1) \quad \text{D-Wort} \quad \tilde{x}_k = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mapsto x_k$$

$$e = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad C: S \times \mathbb{R} \leftrightarrow \mathbb{R}^2$$

$$p \mapsto \begin{bmatrix} p+e \\ 1+\langle p|e \rangle \end{bmatrix}$$

$$(3. \text{Wort} \equiv 0)$$



$$\underline{T} \quad t \mapsto p_1(t), t \mapsto p_2(t) \quad (-\varepsilon, \varepsilon) \rightarrow S \quad \text{C-Driftung,}$$

$$p \mapsto x_k(p(t)) \quad \text{FURT DIFF, } p_1(0) = p_2(0) = p_0 \quad \text{kurzer Punkt}$$

$$q_1(t) := C(p_1(t)), q_2(t) := C(p_2(t)) \quad , \quad \dot{p}_j, \dot{q}_j, \frac{d}{dt} p_j, \frac{d}{dt} q_j$$

$$\text{C-Wort} \quad \nabla (\dot{p}_1(0), \dot{p}_2(0)) = \nabla (\dot{q}_1(0), \dot{q}_2(0))$$

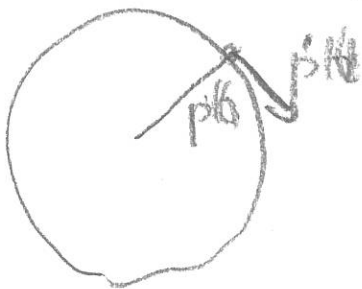
$$\underline{b} \quad \nabla(u, v) = \frac{\langle u|v \rangle}{\|u\| \cdot \|v\|} \quad \mathbb{R}^2, \mathbb{R}^3 \text{ - Ort} \quad \|u\|^2 = \langle u|u \rangle = \langle u \rangle^2$$

$$\text{Beziehung: } \frac{\langle \dot{p}_1(0), \dot{p}_2(0) \rangle}{\langle \dot{p}_1(0), \dot{p}_1(0) \rangle^{1/2} \langle \dot{p}_2(0), \dot{p}_2(0) \rangle^{1/2}} = [\text{u} \in \text{p-Driftung} \quad 2\text{-Wort}]$$

$$q(t) := C(p(t)), p(t) \in S$$

$$\begin{aligned} \left[ \dot{q}_0(t) \right] &= \frac{d}{dt} \left[ \frac{p(t)+e}{1+\langle p(t)|e \rangle} \right] = \frac{\dot{p}(t)}{1+\langle p(t)|e \rangle} - \frac{p(t)+e}{(1+\langle p(t)|e \rangle)^2} \langle \dot{p}(t)|e \rangle \\ &= \frac{(1+\langle p(t)|e \rangle) \dot{p}(t) - \langle \dot{p}(t)|e \rangle (p(t)+e)}{(1+\langle p(t)|e \rangle)^2} \end{aligned}$$

$$\begin{bmatrix} \dot{q}/4 \\ 0 \end{bmatrix} = \frac{(1 + \langle p_0 | e \rangle) \dot{p}/0 - \langle \dot{p}/0 | e \rangle (p_0 + e)}{(1 + \langle p_0 | e \rangle)^2}$$



$$\text{Enrolled: } \dot{p}(t) \perp p(t)$$

$$[\text{viz: } \frac{d}{dt} \langle p(t) | p(t) \rangle = \frac{d}{dt} 1 = 0 \\ 2 \langle \dot{p}(t) | p(t) \rangle]$$

$$p \rightsquigarrow p_1, p_2 \quad q \rightsquigarrow q_1, q_2$$

$$\langle \dot{p}_i/0 | \dot{q}_j/0 \rangle = \frac{\langle (1 + \langle p_0 | e \rangle) \dot{p}_i/0 - \langle \dot{p}_i/0 | e \rangle (p_0 + e) | u e \pm i \hat{e} \rangle}{(1 + \langle p_0 | e \rangle)^4}$$

$$\dot{p}_1/0, \dot{p}_2/0 \perp p_0 = p_1/0 = p_2/0$$

$$[\langle \dot{p}_i/0 | \dot{q}_j/0 \rangle - \text{statistical}] =$$

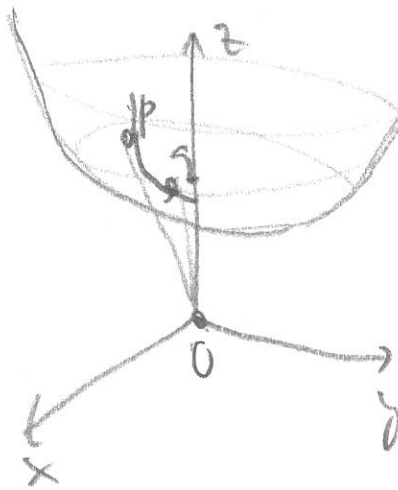
$$= \langle (1 + \langle p_0 | e \rangle) \dot{p}_i/0 - \langle \dot{p}_i/0 | e \rangle (p_0 + e) | (1 + \langle p_0 | e \rangle) \dot{p}_j/0 - \langle \dot{p}_j/0 | e \rangle (p_0 + e) \rangle =$$

$$= (1 + \langle p_0 | e \rangle)^2 \langle \dot{p}_i/0 | \dot{p}_j/0 \rangle + \langle \dot{p}_i/0 | e \rangle \langle \dot{p}_j/0 | e \rangle \langle p_0 + e \rangle^2 - \\ - (1 + \langle p_0 | e \rangle) [\langle \dot{p}_i/0 | e \rangle \langle p_0 + e \rangle + \langle \dot{p}_j/0 | e \rangle \langle p_0 + e \rangle] = \\ = (1 + \langle p_0 | e \rangle)^2 \langle \dot{p}_i/0 | \dot{p}_j/0 \rangle$$

$$\frac{\langle \dot{p}_i/0 | \dot{p}_j/0 \rangle}{[\langle \dot{p}_i/0 | \dot{p}_i/0 \rangle]^{1/2} [\langle \dot{p}_j/0 | \dot{p}_j/0 \rangle]^{1/2}} = \frac{(1 + \langle p_0 | e \rangle)^2 \langle \dot{p}_i/0 | \dot{p}_j/0 \rangle}{(1 + \langle p_0 | e \rangle)^2 [\langle \dot{p}_i/0 | \dot{p}_i/0 \rangle]^{1/2} [\langle \dot{p}_j/0 | \dot{p}_j/0 \rangle]^{1/2}} \\ \Rightarrow \frac{\langle \dot{p}_i/0 | \dot{p}_j/0 \rangle}{\|\dot{p}_i/0\| \cdot \|\dot{p}_j/0\|} = \frac{\langle \dot{p}_i/0 | \dot{p}_j/0 \rangle}{\|\dot{p}_i/0\| \cdot \|\dot{p}_j/0\|} \quad \text{Q.E.D.}$$

# HYPERBOLIC GEOMETRIA

(30)



$$S = \{ (z^2 - (x^2 + y^2) = 1, z \geq 0) \}$$

$$= \{ p \in \mathbb{R}^3 : z(p)^2 - x(p)^2 - y(p)^2 = 1, z(p) \geq 0 \}$$

$$(p, \gamma) \in S \text{ EGGENERE} =$$

$$= [0, p, \gamma] \text{ s/k} \cap S$$

Major GÖNBI GEOM-NEU:  $S = \{ (z^2 + (x^2 + y^2) = 1) \}$  velt,

$$(p, \gamma) \text{ EGGENERE} = [0, p, \gamma] \text{ s/k} \cap S$$

Euler-koord:



$$z(p) = \cos \vartheta(p)$$

$$x(p) = \sin \vartheta(p) \cos \varphi(p)$$

$$y(p) = \sin \vartheta(p) \sin \varphi(p)$$

}  $p \in S$

$$(p, \gamma) \text{ TÄNNENKAT} = [p, \gamma - \text{WURDE } (x, y, z) \text{ NACH } \gamma] =$$

$$= \text{Diagram} = \vartheta(p, \gamma) (\text{RAD}) = \arccos \langle p, \gamma \rangle$$

Hip-geom

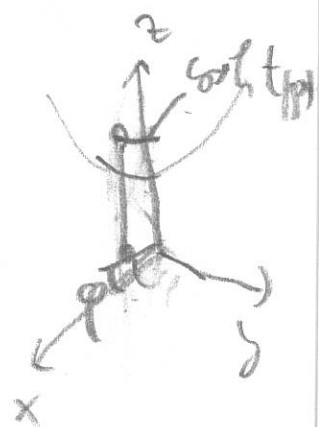
Minkowski-koord (~ Euler geom)

$$z(p) = \cosh t(p)$$

$$x(p) = \sinh t(p) \cdot \cos \varphi(p)$$

$$y(p) = \sinh t(p) \cdot \sin \varphi(p)$$

}  $p \in S$



(3)

$$[p]_{\mathbb{R}^3 \text{ TAUKIA/GA}} = [p, \zeta - \text{lokus } S - a] = \langle p | \zeta \rangle_M$$

skala nam 24 m

$$= \operatorname{arccosh} \langle p | \zeta \rangle_M = \operatorname{arccosh} \langle p | \zeta \rangle_M$$

Az 70 Az  
dimensi

L. HINKOWSKI

$$\langle p | \zeta \rangle_M = z(p) z(\zeta) - (x(p) x(\zeta) + y(p) y(\zeta))$$

$$= \left\langle \begin{pmatrix} \xi_1 \\ \eta_1 \\ \zeta_1 \end{pmatrix} \middle| \begin{pmatrix} \xi_2 \\ \eta_2 \\ \zeta_2 \end{pmatrix} \right\rangle_M = \zeta_1 \zeta_2 - (\xi_1 \xi_2 + \eta_1 \eta_2) \quad (\xi_i, \eta_i, \zeta_i \in \mathbb{R})$$

$$\langle p | p \rangle_M = 1 \quad (p \in S) \quad \text{set } S = \{p \in \mathbb{R}^3 : \langle p | p \rangle_M = 1, z(p) > 0\}$$

M AREA  $\alpha$ -thick:

$(y^2 - x^2 = 1) \Rightarrow (y = \sqrt{1+x^2})$

$\operatorname{arcsinh} \alpha = \text{AREA} \cdot 2$

$$\int_{x=0}^{\alpha} \sqrt{1+x^2} dx = \int_{t=0}^{\operatorname{arcsinh} \alpha} \cosh^2 t dt = \infty$$

$$x = \sinh t \quad \cosh^2 t - \sinh^2 t = 1$$

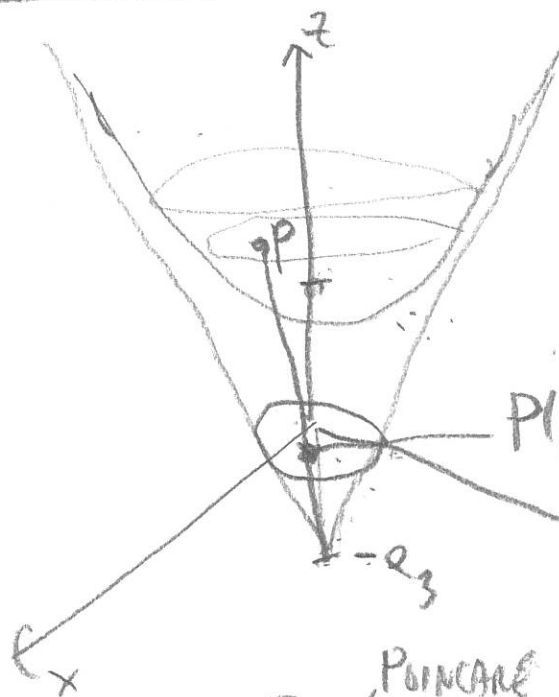
$$dx = \cosh t dt$$

$$\int_{t=0}^{\operatorname{arcsinh} \alpha} \frac{1}{2} (1 + \cosh 2t) dt = \frac{1}{2} \operatorname{arcsinh} \alpha + \frac{1}{4} \sinh(2 \operatorname{arcsinh} \alpha) =$$

$$= \frac{1}{2} \operatorname{arcsinh}(\alpha) + \frac{1}{4} \cdot 2 \sinh(\operatorname{arcsinh} \alpha) \cosh(\operatorname{arcsinh} \alpha) =$$

$$= \frac{1}{2} \operatorname{arcsinh}(\alpha) + \frac{1}{2} \alpha \sqrt{1+\alpha^2}$$

# Poincaré térkép



$$P(p) = [p - e_3]_{\text{norm}} \cap x_y \text{ sík} =$$

$$= \left[ \frac{p + e_3}{\cosh t(p) + 1} - e_3 \right]_{\text{word}}$$

$$p = \begin{bmatrix} x_p \\ y_p \end{bmatrix} \quad \text{POINCARÉ}$$

$$\left. \begin{aligned} x_p &= \frac{\sinh t \cdot \cosh \varphi}{1 + \cosh t} \\ y_p &= \frac{\sinh t \sinh \varphi}{1 + \cosh t} \end{aligned} \right\}$$

$$\underline{\underline{\mathbb{I}}} \quad P(S) = [\text{NYITÓT EGYSÉGSZÖR}] = \{z \in \mathbb{R}^2 : x_1^2 + y_1^2 < 1\}$$

$$P(\text{EGYSÉGSZÖR}) = \text{EGYSÉGSZÖR} \perp \text{KÖR}(1/2)$$

# KOMPLEX KOORD C-N

M Vorfaktor "komplexifizierte Koordinat"

$$X = \begin{bmatrix} x \\ y \end{bmatrix} : \mathbb{C} \leftrightarrow \mathbb{R}^2 \quad \left. \begin{array}{l} x(f+ig) = f \\ y(f+ig) = g \end{array} \right\} \quad d(p, q) = |p - q| \quad \text{T.A.V.}$$

$$z := x + iy \quad \bar{z} := x - iy \quad \bar{z} : \begin{bmatrix} z \\ \bar{z} \end{bmatrix} : \mathbb{C}^2 \leftrightarrow \mathbb{C}^2$$

Beispiel: Folgerungen  $\frac{\partial}{\partial z} z^k \bar{z}^l = k z^{k-1} \bar{z}^l$

oder  $P(x, y)$  polynom  $\frac{\partial}{\partial \bar{z}} z^k \bar{z}^l = l z^k \bar{z}^{l-1}$   
 $\tilde{P}(z, \bar{z})$  gilt  
 $x = (z + \bar{z})/2 \quad y = (z - \bar{z})/(2i)$

Lehrs-E

$$\frac{\partial f}{\partial z} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial z} = \frac{\partial f}{\partial x} \left( \frac{\partial z}{\partial x} \right)^{-1} \quad \text{Achtung!}$$

$$\frac{\partial f}{\partial z} = \left[ \frac{\partial f}{\partial x} \quad \frac{\partial f}{\partial y} \right] \quad \text{Klammersystem } x, y \text{ -mal}$$

$$\frac{\partial z}{\partial x} = \begin{bmatrix} \partial z / \partial x & \partial z / \partial y \\ \partial \bar{z} / \partial x & \partial \bar{z} / \partial y \end{bmatrix} = \begin{bmatrix} 1 & i \\ 1 & -i \end{bmatrix}$$

$$\left( \frac{\partial z}{\partial x} \right)^{-1} = \frac{1}{(-2i)} \begin{bmatrix} -i & -i \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 \\ i/2 & -i/2 \end{bmatrix}$$

$$\text{Folgt: } \frac{\partial f}{\partial \bar{z}} = \begin{bmatrix} \partial (\frac{1}{2}z + \frac{1}{2}\bar{z}) / \partial z & \partial (\frac{1}{2}z + \frac{1}{2}\bar{z}) / \partial \bar{z} \\ \partial (\frac{1}{2i}z - \frac{1}{2i}\bar{z}) / \partial z & \partial (\frac{1}{2i}z - \frac{1}{2i}\bar{z}) / \partial \bar{z} \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 \\ -i/2 & i/2 \end{bmatrix}$$

$$\boxed{\begin{array}{l} \frac{\partial f}{\partial z} = \frac{1}{2} \frac{\partial f}{\partial x} - \frac{i}{2} \frac{\partial f}{\partial y} \quad \frac{\partial f}{\partial \bar{z}} = \frac{1}{2} \frac{\partial f}{\partial x} + \frac{i}{2} \frac{\partial f}{\partial y} \end{array}}$$