On the minimization of Horn formulas

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- Horn formulas
- Horn minimization
- Horn minimization: Steiner version

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- directed hypergraphs
- hydra number

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- satisfiability in propositional logic is computationally hard
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- Poole Mackworth: Artificial Intelligence: Foundations of Computational Agents, 2010:
 - 'uses rational computational agents and Horn clause logic as unifying threads in this vast field'

Horn formulas, entailment

- Horn clause: at most one unnegated variable, e.g.
 C = ā ∨ b ∨ c, written as a, b → c, Body(C) = {a, b},
 Head(C) = c
- definite clause: exactly one unnegated variable
- (definite) formula: conjunction of (definite) Horn clauses

- Horn function: representable by a Horn formula
- ▶ entailment: $(a, b \rightarrow c) \land (c \rightarrow d) \models (a, b \rightarrow d)$
- implicate: $K \models C$
- prime implicate: no subclause is an implicate
- forward chaining efficient

optimization

- optimization
- learning and mining from data

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dynamic problems

Horn minimization

given a Horn formula φ and a number k, is there a Horn formula with at most k clauses equivalent to φ?

• $x_i \rightarrow y_j$, $y_1, \ldots, y_n \rightarrow x_i$ $n^2 + n$ clauses

▶ $x_i \rightarrow x_{i+1}$, $x_n \rightarrow y_i$, $y_1, \ldots, y_n \rightarrow x_1$ 2*n* clauses

Previous work: minimization

- Umans (2000): CNF minimization is Σ^p₂-complete
- Ausiello, D'Atri, Saccà (1986): Horn minimization is NP-complete
- Hammer, Kogan (1993): NP-complete if the number of literals is to be minimized; in P for quasi-acyclic formulas
- Maier (1983), Ausiello, D'Atri, Saccà (1986), Guigues, Duquenne (1986), Angluin, Frazier, Pitt (1992): minimization of the number of bodies can be done efficiently

 Boros, Čepek, Kogan (1997): iterative decomposition algorithm

Approximate minimization

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Theorem

Bhattacharya, DasGupta, Mubayi, T. (2010): if $NP \not\subseteq DTIME(n^{polylog(n)})$ then for every $0 < \delta < 1$ Horn minimization is not efficiently

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Theorem

Boros, Gruber (2011): if $P \neq NP$ then 3-Horn minimization is not efficiently

 $2^{(\log size(\varphi))^{1-o(1)}}$

approximable.

Introducing new variables

- Flögel, Kleine Büning, Lettmann (1993)
- $x_1/y_1, \ldots, x_n/y_n \to u$ 2^n clauses
- ▶ $x_i \rightarrow z_i$, $y_i \rightarrow z_i$, $z_1, \ldots, z_n \rightarrow u$ 2*n*+1 clauses
- same set of consequences over the original variables
- φ ~_R ψ, where R is a set of variables: same set of consequences over R
- co NP-complete even in rather restricted cases, so extension is too powerful

Steiner extension

introduce new variables in a restricted way

- ► $x_i \rightarrow y_j$, i = 1, ..., n, j = 1, ..., m nm clauses
- ► $x_i \rightarrow z, z \rightarrow y_j, i = 1, ..., n, j = 1, ..., m$ n + m clauses
- new variables can be heads, or singleton bodies with old heads

- φ ∼_R ψ, where variables new are introduced by Steiner extension: can be decided efficiently
- minimization is MAX-SNP-hard

Theorem There is an efficient

$$O\left(n \ \frac{\log \log n}{(\log n)^{1/4}}\right) \quad O\left(\frac{n}{\log n}\right)$$

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- $\sqrt{\log n}$ Horn minimization can be done efficiently
- find an equivalent Horn formula with the minimal number of bodies
- find a decomposition of the bipartite graph between heads and bodies

Decomposition of graphs

 given a graph, partition its edges into complete bipartite graphs

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minimize the sum of the number of vertices

Efficient decomposition

Theorem

There is an efficient algorithm for finding

► a decomposition of (a, b)-bipartite graphs (a ≥ b) into complete bipartite graphs with

$$O\left(\frac{ab}{\log a} + a\log b\right) + a$$

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vertices altogether.

Directed hypergraphs

• directed hyperedge $a, b \rightarrow c$



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- directed hyperedge $a, b \rightarrow c$
- directed hypergraph

• {
$$(a, b \rightarrow c), (a, c \rightarrow d), (d, e \rightarrow f)$$
}

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conjunctive normal forms

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- conjunctive normal forms
- propositional logic

Combinatorics meets logic

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- conjunctive normal forms
- propositional logic
- first-order logic

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 - ► mark vertices in *S*
 - ▶ while there is a hyperedge a, b → c such that a, b is marked and c is unmarked, mark c

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- closure cl_H(S) is the set of marked vertices
- vertex v is reachable from S if $v \in cl_H(S)$

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► directed hypergraph H = (V, F) represents undirected graph G = (V, E):

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•
$$(u, v) \in E$$
 implies $cl_H(u, v) = V$

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- motivation: special case of the minimization of Horn formulas

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cycles

complete binary tree on 7 vertices

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cycles

- complete binary tree on 7 vertices
- undirected graph G is single-headed if h(G) = |E|

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• $|E| \le h(G) \le 2|E|$, both are sharp for some graphs

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- if G has a single-headed connected spanning subgraph then it is single-headed

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- ▶ if G has a cut edge between with both halves having at least two vertices then G is not single-headed

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path cover number p(G): minimal number of paths needed to cover all vertices

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 $h(G) \leq |E(G)| + p(L(G'))$

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Theorem There are single-headed graphs G_k with $\Theta(k)$ edges such that $p(L(G')) = \Theta(k)$ for every connected spanning subgraph G'

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Theorem

a tree is single-headed iff it is a star

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Theorem

- a tree is single-headed iff it is a star
- h(T) = |E(T)| + 1 iff T is a caterpillar.

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Theorem

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Theorem

For the complete binary tree of depth d

$$\frac{13}{12}|E(B_d)| \le h(B_d) \le \frac{8}{7}|E(B_d)|.$$

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o(n) approximation algorithm for Horn formulas; subclasses?

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