Semidefinite programming

Péter Hajnal

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Péter Hajnal Semidefinite programming, SzTE, 2024

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SDP: Basics

General Formulation of Semidefinite Programming

Minimize	c [⊤] x-t
subject to	$\sum_{i=1}^{n} x_i A_i \preceq B$
	Dx = e,

where $c, x \in \mathbb{R}^n$, $A_i, B \in S^k = \{M \in \mathbb{R}^{k \times k} : M^T = M\} \subset \mathbb{R}^{k \times k}$, $D \in \mathbb{R}^{\ell \times n}$, and $e \in \mathbb{R}^{\ell}$.

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 S^n denotes the set of real symmetric $n \times n$ matrices, i.e., $M \in \mathbb{R}^{n \times n}$ belongs to S^n if and only if $M^T = M$. Specifically, $S^n \subset \mathbb{R}^{n \times n}$.

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Notation

SDP. Basics

 $A \leq B$ if and only if $A, B \in S^n$ and $0 \leq B - A$, i.e., B - A is positive semidefinite, denoted as $B - A \in S^n_+$.

$$\sum_{i=1}^{n} x_i A_i$$



SDP: Duality

$$\sum_{i=1}^{n} x_i A_i$$



Example

$$\begin{pmatrix} 2x_1 - 3x_2 + x_3 & 5x_1 + 2x_2 - x_3 & x_1 - x_2 + 8x_3 & 6x_1 + 5x_2 + x_3 \\ 5x_1 + 2x_2 - x_3 & -x_1 + 7x_2 - 2x_3 & 9x_1 - 3x_2 + x_3 & -2x_1 - x_2 + 4x_3 \\ x_1 - x_2 + 8x_3 & 9x_1 - 3x_2 + x_3 & 10x_1 - 2x_2 + 2x_3 & 8x_1 + x_2 + x_3 \\ 6x_1 + 5x_2 + x_3 & -2x_1 - x_2 + 4x_3 & 8x_1 + x_2 + x_3 & -11x_1 + 2x_2 - 3x_3 \end{pmatrix}$$

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Observation

The LP problem is a special case of an SDP problem.

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SDP: Basics	SDP: Duality
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$$\langle M, N \rangle = \operatorname{Tr}(M^{\mathrm{T}}N) = \sum_{j} (M^{\mathrm{T}}N)_{jj} = \sum_{i,j} M_{ji}^{\mathrm{T}}N_{ij} = \sum_{i,j} M_{ij}N_{ij}.$$

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An alternative: Let $vec : \mathbb{R}^{n \times n} \to \mathbb{R}^{n^2}$ be the vectorization of a matrix (i.e., stacking the columns of a table into a vector). Then $\langle M, N \rangle = vec(M)^T vec(N)$.

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Below we summarize the properties of the introduced inner product. Interested students can verify these properties themselves.

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Lemma
Let $M, N, P \in \mathcal{S}^n$
(i) $\langle M, N \rangle = \langle N, M \rangle$
(ii) $\langle MN, P \rangle = \langle M, PN \rangle$
(iii) $\langle M, M \rangle = \text{Tr} M^2 = \sum_{i=1}^n \lambda_i^2 \ge 0$

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Notation

 $||M||_F = \sqrt{\langle M, M \rangle}$, the Frobenius norm of a symmetric matrix M.

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(i) *M* is positive semidefinite, i.e., $x^{\mathsf{T}}Mx \ge 0$ for all $x \in \mathbb{R}^n$,

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- (iv) Every symmetric submatrix of M (obtained by deleting s rows and the corresponding s columns) has a nonnegative determinant.

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, then there exists $M^{\frac{1}{2}} \succeq 0$ such that $M = M^{\frac{1}{2}}M^{\frac{1}{2}}$.

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$$\Lambda = \begin{pmatrix} \lambda_1 & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}, \qquad \Lambda^{\frac{1}{2}} = \begin{pmatrix} \sqrt{\lambda_1} & 0 \\ & \ddots & \\ 0 & & \sqrt{\lambda_n} \end{pmatrix}$$

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• Choosing $M^{\frac{1}{2}} = Q\Lambda^{\frac{1}{2}}Q^{\mathsf{T}}$ proves the Lemma.

SDP: Duality



 \mathcal{S}^n_+ Geometrically

Observation

 \mathcal{S}^n_+ is a cone in $\mathcal{S}^n \subset \mathbb{R}^{n \times n}$.

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The Set of Positive Semidefinite Matrices $\begin{pmatrix} \alpha \\ \beta \end{pmatrix}$



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SDP: Duality

Normal Forms of SDP

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SDP: I. Normal Form

Minimize	$\langle C, X angle$ -t	
subject to	$\langle A_i, X \rangle = b_i,$	$i=1,\ldots k$
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where $C, X, A_i \in S^n$ and $b \in \mathbb{R}^k$.

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SDP: II. Normal Form

Minimize	$c^{T}x$ -t
subject to	$\sum_{i=1}^n x_i A_i \preceq B$,

where $c, x \in \mathbb{R}^n$ and $A_i, B \in \mathcal{S}^k$.
Break



Duality (Lagrange Method)

We examine the primal problem in the first normal form:

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However, we cannot incorporate the positive semidefiniteness constraint into L, so we "constrain" the domain of L with this condition.

$$L(X,\mu) = \langle C,X \rangle + \sum \mu_i (\langle A_i,X \rangle - b_i), \quad \text{dom } L = \{X : X \succeq 0\}.$$

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Minimizing this function leads to the objective function of the dual problem.

$$\widehat{c}(\mu) = \inf_{X: X \succeq 0} L(X, y) = -\sum b_i \mu_i + \inf \left\langle C + \sum \mu_i A_i, X \right\rangle.$$

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We need to solve the optimization problem

$$\inf_{X\succeq 0} \langle M, X \rangle = ?.$$

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Lemma

M is positive semidefinite if and only if $\langle M, X \rangle \ge 0$ for all $X \succeq 0$.

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Auxiliary Lemma

Let $A \in \mathbb{R}^{k \times \ell}$ and $B \in \mathbb{R}^{\ell \times k}$. Then

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\operatorname{Tr}(AB) = \operatorname{Tr}(BA).
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SDP: Duality

Proof of the Lemma

• Let $M, X \succeq 0$.

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• Let $M, X \succeq 0$. Then

$$\begin{array}{lll} \langle M,X\rangle &=& {\rm Tr}\,(MX) = {\rm Tr}\,(M^{1/2}M^{1/2}X^{1/2}X^{1/2}) \\ &=& {\rm Tr}\,((M^{1/2}M^{1/2}X^{1/2})X^{1/2}) = {\rm Tr}\,(X^{1/2}(M^{1/2}M^{1/2}X^{1/2})) \\ &=& {\rm Tr}\,((X^{1/2}M^{1/2})(M^{1/2}X^{1/2})) \\ &=& {\rm Tr}\,((M^{1/2}X^{1/2})^{\rm T}(M^{1/2}X^{1/2})) \geq 0, \end{array}$$

since $M^{1/2}$ and $X^{1/2}$ are symmetric.

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since $M^{1/2}$ and $X^{1/2}$ are symmetric.

• Conversely, assume that $\langle M, X \rangle \ge 0$ for all $X \succeq 0$ matrices. Let $x \in \mathbb{R}^n$ be arbitrary. Apply our assumption to the positive semidefinite matrix $X = xx^{\mathsf{T}}$:

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• Let $M, X \succeq 0$. Then

$$\begin{array}{lll} \langle M,X\rangle &=& {\rm Tr}\,(MX)={\rm Tr}\,(M^{1/2}M^{1/2}X^{1/2}X^{1/2}) \\ &=& {\rm Tr}\,((M^{1/2}M^{1/2}X^{1/2})X^{1/2})={\rm Tr}\,(X^{1/2}(M^{1/2}M^{1/2}X^{1/2})) \\ &=& {\rm Tr}\,((X^{1/2}M^{1/2})(M^{1/2}X^{1/2})) \\ &=& {\rm Tr}\,((M^{1/2}X^{1/2})^{\rm T}(M^{1/2}X^{1/2})) \geq 0, \end{array}$$

since $M^{1/2}$ and $X^{1/2}$ are symmetric.

• Conversely, assume that $\langle M, X \rangle \ge 0$ for all $X \succeq 0$ matrices. Let $x \in \mathbb{R}^n$ be arbitrary. Apply our assumption to the positive semidefinite matrix $X = xx^{\mathsf{T}}$:

$$0 \leq \langle M, X \rangle = \operatorname{Tr} (M(xx^{\mathsf{T}})) = \operatorname{Tr} ((Mx)x^{\mathsf{T}}) = \operatorname{Tr} (x^{\mathsf{T}}(Mx))$$

= $\operatorname{Tr} (x^{\mathsf{T}}Mx) = x^{\mathsf{T}}Mx.$

Thus, M is positive semidefinite.

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It follows from the lemma that

$$\inf\langle M,X
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• Indeed, if $M \succeq 0$, then by the lemma $\langle M, X \rangle$ cannot be negative, but M = 0 shows it can be 0.

• Similarly, by the lemma, if $M \not\geq 0$, then $\langle M, X \rangle$ can be negative. Multiplying X by a positive scalar, we can make it arbitrarily large in absolute value and negative.

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Definition

The dual of a cone $K \subseteq \mathbb{R}^N$ is:

$$K^* = \{x \in \mathbb{R}^N : x^{\mathrm{T}}k \ge 0 \ \forall k \in K\}.$$

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Then our proved lemma can be stated as follows:

Lemma

(i) S_{+}^{n} is a cone. (ii) S_{+}^{n} is self-dual, $(S_{+}^{n})^{*} = S_{+}^{n}$.

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Dual Problem

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Dual Problem

As a result of the detour, we obtain that

$$\inf_{X \succeq 0} L(X, \mu) = \begin{cases} -\sum b_i \mu_i, & C + \sum \mu_i A_i \succeq 0\\ -\infty, & \text{otherwise} \end{cases}$$

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Thus, we find the dual of the starting SDP (primal) problem.

Maximize	$-\sum b_i \mu_i$ -t
subject to	$-\sum \mu_i A_i \preceq C$

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Maximize	$-\sum b_i \mu_i$ -t
subject to	$-\sum \mu_i A_i \preceq C$

Equivalently,

Minimize	$\sum b_i \mu_i$ -t
subject to	$C + \sum \mu_i A_i = S,$
	$S \succeq 0.$

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Weak Duality

If p^* is the optimum of the primal SDP and d^* is the optimum of the dual SDP, then $d^* \leq p^*$.

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Let $X \in \mathcal{L}_P$ be a feasible solution of the primal problem and $(\mu, S) \in \mathcal{L}_D$ be a feasible solution of the dual.

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Claim

$$\langle C, X \rangle \geq -b^{\mathsf{T}} \mu.$$

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Weak Duality Theorem

Weak Duality

If p^* is the optimum of the primal SDP and d^* is the optimum of the dual SDP, then $d^* \leq p^*$.

Assume $p^* < \infty$, $d^* > -\infty$.

Let $X \in \mathcal{L}_P$ be a feasible solution of the primal problem and $(\mu, S) \in \mathcal{L}_D$ be a feasible solution of the dual.

Claim

 $\langle C, X \rangle \geq -b^{\mathsf{T}}\mu.$

The claim states that any primal objective value is at least as large as any dual objective value. From this, the theorem trivially follows.

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Proof of Weak Duality

We have seen that the product of two positive semidefinite matrices is nonnegative. Hence,

$$0 \leq \langle X, S \rangle = \langle X, C + \sum \mu_i A_i \rangle = \langle X, C \rangle + \sum \mu_i \langle A_i, X \rangle$$
$$= \langle C, X \rangle + \sum \mu_i b_i = \langle C, X \rangle + b_i^{\mathsf{T}} \mu_i.$$

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$$= \langle C, X \rangle + \sum \mu_i b_i = \langle C, X \rangle + b_i^{\mathsf{T}} \mu_i.$$

From this, the claim follows by rearrangement.

Minimize	<i>x</i> ₁₂ -t
subject to	$\left(\begin{array}{ccc} 0 & x_{12} & 0 \\ x_{12} & x_{22} & 0 \\ 0 & 0 & 1+x_{12} \end{array}\right) \succeq 0$

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To dualize the problem, we first bring the problem to the standard form of semidefinite programming I:

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SDP: Basics

To dualize the problem, we first bring the problem to the standard form of semidefinite programming I:

We introduce the following variable matrix:

$$X = \begin{pmatrix} x_{11} & x_{12} & x_{13} \\ x_{12} & x_{22} & x_{23} \\ x_{13} & x_{23} & x_{33} \end{pmatrix}$$

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The matrix in the original form is $\begin{pmatrix} 0 & x_{12} & 0 \\ x_{12} & x_{22} & 0 \\ 0 & 0 & 1 + x_{12} \end{pmatrix}$.

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The matrix in the original form is
$$\begin{pmatrix} 0 & x_{12} & 0 \\ x_{12} & x_{22} & 0 \\ 0 & 0 & 1+x_{12} \end{pmatrix}.$$

This is equivalent to setting $x_{11} = 0$, $x_{13} = 0$, $x_{23} = 0$, $x_{33} = 1 + x_{12}$.

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Rewriting these constraints in the standard form:

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Rewriting these constraints in the standard form:

• Setting
$$x_{11} = 0$$
: $\left\langle \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, X \right\rangle = 0$ (this equality

constraint corresponds to the dual variable μ_1).

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• Setting
$$x_{13} = 0$$
: $\left\langle \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, X \right\rangle = 0$ (this equality

constraint corresponds to the dual variable μ_2).

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Rewriting these constraints in the standard form:

• Setting
$$x_{11} = 0$$
: $\left\langle \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, X \right\rangle = 0$ (this equality

constraint corresponds to the dual variable μ_1).

• Setting
$$x_{13} = 0$$
: $\left\langle \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, X \right\rangle = 0$ (this equality

constraint corresponds to the dual variable μ_2).

• Setting
$$x_{23} = 0$$
: $\left\langle \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, X \right\rangle = 0$ (this equality

constraint corresponds to the dual variable μ_3).

Rewriting these constraints in the standard form:

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constraint corresponds to the dual variable μ_1).

• Setting
$$x_{13} = 0$$
: $\left\langle \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, X \right\rangle = 0$ (this equality

constraint corresponds to the dual variable μ_2).

• Setting
$$x_{23} = 0$$
: $\left\langle \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, X \right\rangle = 0$ (this equality

constraint corresponds to the dual variable μ_3).

• Setting
$$x_{33} = 1 + x_{12}$$
: $\left\langle \begin{pmatrix} 0 & -\frac{1}{2} & 0 \\ -\frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, X \right\rangle = 1$ (this

equality constraint corresponds to the dual variable μ_4).

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The Example in Normal Form

The new form of our problem:

Minimize

$$\left\langle \begin{pmatrix} 0 & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, X \right\rangle$$
-t

 subject to
 $\left\langle \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, X \right\rangle = 0, \left\langle \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, X \right\rangle = 0,$
 $\left\langle \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}, X \right\rangle = 0, \left\langle \begin{pmatrix} 0 & -\frac{1}{2} & 0 \\ -\frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, X \right\rangle = 1.$
 $X \succeq 0$

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Example: Dualization

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Example: Dualization

$$\begin{array}{ll} \text{Maximize} & -\mu_4\text{-t} \\ \text{subject to} & \begin{pmatrix} 0 & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \mu_1 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \mu_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} + \\ & \mu_3 \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} + \mu_4 \begin{pmatrix} 0 & -\frac{1}{2} & 0 \\ -\frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \succeq 0. \end{array}$$

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Example: Dualization

$$\begin{array}{ll} \text{Maximize} & -\mu_4\text{-t} \\ \text{subject to} & \begin{pmatrix} 0 & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \mu_1 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \mu_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} + \\ & \mu_3 \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} + \mu_4 \begin{pmatrix} 0 & -\frac{1}{2} & 0 \\ -\frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \succeq 0. \end{array}$$

So,

Maximize
$$-\mu_4$$
-tsubject to $\begin{pmatrix} \mu_1 & \frac{1-\mu_4}{2} & \mu_2 \\ \frac{1-\mu_4}{2} & 0 & \mu_3 \\ \mu_2 & \mu_3 & \mu_4 \end{pmatrix} \succeq 0.$

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Minimize	<i>x</i> ₁₂ -t	
1.5	$\begin{pmatrix} 0 & x_{12} & 0 \\ & 0 & 0 \end{pmatrix}$	
subject to	$\left(\begin{array}{ccc} x_{12} & x_{22} & 0 \\ 0 & 0 & 1 + x_{12} \end{array}\right) \succeq 0$	

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Minimize	<i>x</i> ₁₂ -t	
subject to	$ \left(\begin{array}{ccc} 0 & x_{12} \\ x_{12} & x_{22} \end{array}\right) $	$\begin{pmatrix} 0 \\ 0 \end{pmatrix} \succeq 0$
	$\begin{pmatrix} 0 & 0 \end{pmatrix}$	$1 + x_{12}$

If there exists an $X \in \mathcal{L}$, then the upper-left 2×2 principal minor of the matrix in the example's condition must be positive semidefinite. Thus, the product of its eigenvalues (determinant) must be greater than zero.

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If there exists an $X \in \mathcal{L}$, then the upper-left 2×2 principal minor of the matrix in the example's condition must be positive semidefinite. Thus, the product of its eigenvalues (determinant) must be greater than zero.

In our case,
$$-x_{12}^2 \ge 0$$
, so $x_{12} = 0$. Hence $p^* = 0$.

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Maximize	$-\mu_4$ -t
subject to	$\left(\begin{array}{ccc} \mu_1 & \frac{1-\mu_4}{2} & \mu_2 \\ \frac{1-\mu_4}{2} & 0 & \mu_3 \\ \mu_2 & \mu_3 & \mu_4 \end{array}\right) \succeq 0.$

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 $\begin{array}{l} d^*\colon \text{Based on the previous considerations, it must hold that} \\ \det \left(\begin{array}{c} \mu_1 & \frac{1-\mu_4}{2} \\ \frac{1-\mu_4}{2} & 0 \end{array} \right) \geq 0. \end{array}$

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This only holds for $\mu_4 = 1$. So, $d^* = -1$.

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Thus, indeed the weak duality theorem holds, so $p^* \ge d^*$ (0 ≥ -1).

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This only holds for $\mu_4 = 1$. So, $d^* = -1$.

Thus, indeed the weak duality theorem holds, so $p^* \ge d^*$ (0 ≥ -1).

However, there is no strong duality.

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Notation

 $X \in \mathcal{L}_{P}^{+}$ if and only if $\langle A_{i}, X \rangle = b_{i}, i = 1, \dots, \ell$ and $X \succ 0$ (i.e., X is positive definite).

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 $X \in \mathcal{L}_{P}^{+}$ if and only if $\langle A_{i}, X \rangle = b_{i}, i = 1, ..., \ell$ and $X \succ 0$ (i.e., X is positive definite).

Similarly defined is \mathcal{L}_D^+ .

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Strong Duality

If
$$\mathcal{L}_P^+, \mathcal{L}_D^+ \neq \emptyset$$
, then $p^* = d^*$.

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Strong Duality

If $\mathcal{L}_P^+, \mathcal{L}_D^+ \neq \emptyset$, then $p^* = d^*$.

Moreover, the set of optimal points is nonempty and compact.

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If $\mathcal{L}_P^+, \mathcal{L}_D^+ \neq \emptyset$, then $p^* = d^*$.

Moreover, the set of optimal points is nonempty and compact.

Strong duality holds even with slightly weakened conditions.

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Strong Duality

Notation

 $X \in \mathcal{L}_P^+$ if and only if $\langle A_i, X \rangle = b_i, i = 1, ..., \ell$ and $X \succ 0$ (i.e., X is positive definite).

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Strong Duality

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Strong Duality

If $\mathcal{L}_P^+, \mathcal{L}_D \neq \emptyset$, then $p^* = d^*$.

We won't prove the theorems here.

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This is the End!

Thank you for your attention!

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