

Complexity classes

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The *time complexity* of a Turing machine T on an ω input is $\ell := \text{TIME}(\omega, T)$ if its truncated run is $(\kappa_i)_{i=0}^{\ell}$, and ∞ if the run is an infinite loop (it does not reach the *STOP* state).

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Definition

The *space complexity* of a Turing-machine T on an input ω is $s := SPACE(\omega, T)$, if during its execution on ω the largest index of the cells under the work hand is s , or ∞ , if the working eye/hand moves arbitrarily far from the left border of the work tape.

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$$SPACE(\omega, T) \leq TIME(\omega, T)$$

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Definition: Decidable languages in polynomial time

$$\mathcal{P} := \bigcup_{p \in \mathbb{R}[x]} TIME(p(n)) = \bigcup_{a \in \mathbb{N}} TIME(an^a + a).$$

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The complete list of complexity classes is much longer
http://qwiki.stanford.edu/index.php/Complexity_Zoo.

Break



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$$\begin{array}{ccccccccccc}
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 & & \cup & & \cup & & & & & & \\
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Our goal is to prove that:

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$$\mathcal{SPACE}(s(n)) \subseteq \bigcup_{c \in \mathbb{N}} \mathcal{TIME}(c^{s(n) + \log(n+1)}).$$

The proof of the Lemma I

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The previous sentence is a characteristic first line in proofs on complexity. We introduce a spacial notation for that:
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Let $\kappa_0(\omega) \rightarrow \kappa_1(\omega) \rightarrow \kappa_2(\omega) \rightarrow \dots \rightarrow \kappa_\ell(\omega)$ be the run on input ω . This is a sequence of configurations of length $\ell \geq 1$, where the first one ($\kappa_0(\omega)$) is the initial configuration (specially the state is START) and the last configuration is ($\kappa_\ell(\omega)$) the first one, where the state is ACCEPT or REJECT.

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An upper bound on the answer is:

$$(n + 2) \cdot (s(n) + 1) \cdot |\Gamma|^{s(n)} \cdot |S| \leq \alpha_T(n + 1) \alpha_T^{s(n)} \leq \beta_T^{s(n) + \log(n+1)},$$

where α_T, β_T constants depending on T .

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Indeed: The number of the possible position of the input eye is $n + 2$. The number of the possible position of the work eye/pen is $s(n) + 1$. The number of the possible content of the work tape is $(|\Gamma| + 1)^{s(n)}$. Finally the state of the machine comes from $|S|$ possibilities.

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We know that this is not the case. So we get the bound claimed.

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\mathcal{P} is a robust class of languages.

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Similarly serious technical problems would be raised by the language class $\mathcal{E} := \{L(T) : T \in \cup_{a \in \mathbb{N}} \text{Time}(a^{n+a})\}$.

Break



The language PALINDROM

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Definition: PALINDROM language

$$PALINDROM = \{\omega = \omega_1, \dots, \omega_n : \text{where } \omega_i = \omega_{n+1-i} \\ \text{for all } i \in \{1, 2, \dots, n\}\}.$$

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Two Turing machines/algorithms are sketched. For simplicity we assume that $\Sigma = \{0, 1\}$.

First model: Single tape model

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- The first decision is to choose an alphabet for the work tape:
 $\Gamma = \{0, 1, 0^\vee, 1^\vee\}$.

First algorithm/TM: High level description

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- On the left, find the first unchecked bit.

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Mark it and remember its value.

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On the right, find the last unchecked bit and mark if it matches.

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If so, we continue the procedure, until we run out of unchecked bits.

First algorithm/TM: S , set of states

For the Turing machine's work so far, we used the following state set

$$S = \{\text{START, LEFT-MARK, RIGHT-FIND-0, RIGHT-FIND-1, RIGHT-TEST-0, RIGHT-TEST-1, LEFT-FIND, ACCEPT, REJECT}\}.$$

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$(\text{LEFT-FIND}, 0) \mapsto (\text{LEFT-FIND}, 0, L)$

$(\text{START}, 0) \mapsto \text{„Who cares?“}$

First algorithm/TG: The movement of the head, time

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Constants are not calculated. Also irrelevant, by increasing the number of states the running time can be reduced. For example, we could use states for examples RIGHT-TEST-000, RIGHT-TEST-001, RIGHT-TEST-010, RIGHT-TEST-011, ...

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The the eyes move in different directions and test the palindrom property.

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Second algorithm/TM: The time

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Observation

All ω input, the run length is at most $3|\omega| + 3 = \mathcal{O}(|\omega|)$.

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This result is sharp in terms of magnitude.

Break



The one-tape model is bad

Theorem

If T is a Turing machine that decides in the single-tape model the *PALINDROM* language, then $\forall n, \exists \omega \in \Sigma^n$:

$$TIME(\omega, T) \geq \alpha_T |\omega|^2,$$

for some positive constant α_T .

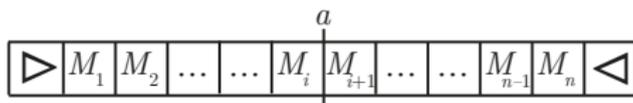
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The common boundary of two adjacent cells on the input tape is called *door*. The cells of the (input) tape can be imagined as an infinite series of rooms. We can say, that the head can only move through the doors.

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The cells M_i and M_{i+1} and the door a between them.

A run of T

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Consider the truncated run of the Turing machine T on ω input:

$$\kappa_0(\omega) \rightarrow \kappa_1 \rightarrow \kappa_2 \rightarrow \dots \rightarrow \kappa_\ell,$$

where

$$\ell := \min\{n \mid \text{state of } \kappa_n \text{ is ACCEPT or REJECT.}\}$$

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Definition: $\sigma(a, \omega)$

Now take those κ_j, κ_{j+1} configurations, in which the input eye is over M_i/M_{i+1} . Let s_j be the state of the Turing machine when passing through the a door separating the cells.

The sequence of these s_j states is denoted by $\sigma(a, \omega)$.

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We cannot know how long the eye was a right but as soon as it crosses the door (and as long as it remains on the left) we are able to describe the run of T .

Corollary of the Observation

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Let $\omega, \omega' \in \Sigma^n$ be arbitrary inputs and a be a door. Suppose $\sigma(a, \omega) = \sigma(a, \omega')$ and Turing machine T has the same result on the two inputs.

Then T outputs the same on the input $\tilde{\omega} = \left(\omega \begin{smallmatrix} a \\ | \end{smallmatrix}\right) \left(\begin{smallmatrix} a \\ | \end{smallmatrix} \omega'\right)$.

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Suppose that $3|n$. Let

$$I_0 := \{\alpha 0^{\frac{n}{3}} \overleftarrow{\alpha} : \alpha \in \Sigma^{\frac{n}{3}}\} \subseteq \text{PALINDROM} \cap \Sigma^n.$$

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Let $\omega, \omega' \in I_0$ be distinct words and a be a middle door (i.e. one of the doors separating the middle $n/3$ zeros). Then $\sigma(a, \omega) \neq \sigma(a, \omega')$.

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Let $\omega, \omega' \in l_0$ be distinct words and a be a middle door (i.e. one of the doors separating the middle $n/3$ zeros). Then $\sigma(a, \omega) \neq \sigma(a, \omega')$.

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A Lemma

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Observation

The number of state sequences shorter than t

$$1 + |S| + \dots + |S|^{t-1} = \frac{|S|^t - 1}{|S| - 1} < |S|^t - 1 < |S|^t.$$

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Lemma

If $|I_0| = |\Sigma|^{\frac{n}{3}} \geq |S|^t$, then $\exists \omega \in I_0$ such that $\sigma(a, \omega)$ has length at least t , where a is a middle door.

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If $|I_0| = |\Sigma|^{\frac{n}{3}} \geq |S|^t$, then $\exists \omega \in I_0$ such that $\sigma(a, \omega)$ has length at least t , where a is a middle door.

We have $|I_0| = |\Sigma|^{\frac{n}{3}} \geq |S|^t$ in the case when $t \sim \beta_T \cdot n$.

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Let a be an arbitrary middle door. Assume that $|I_0| \geq 2|S|^t$. There exists at least $|I_0|/2$ inputs in I_0 for which $|\sigma(a, \omega)| \geq t$.

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Let denote the set of inputs in the Corollary by $I_1(a)$, i.e.

$$I_1(a) = \{\omega \in I_0 : |\sigma(a, \omega)| \geq t\} \subseteq I_0.$$

We also know that $t \sim \gamma_T \cdot n$ is a suitable choice to guarantee $|I_1| \geq |I_0|/2$.

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After division by $|l_0|$:

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After division by $|l_0|$:

$$\frac{1}{|l_0|} \sum_{\omega \in l_0} \text{TIME}(\omega, T) \geq \frac{\gamma T}{6} \cdot n^2.$$

This is the end!

Thank you for your attention!