

SECOND-ORDER DIFFERENTIAL INCLUSIONS WITH ALMOST CONVEX RIGHT-HAND SIDES

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ABSTRACT. We study the existence of solutions of a boundary second order differential inclusion under conditions that are strictly weaker than the usual assumption of convexity on the values of the right-hand side.

1. INTRODUCTION

The existence of solutions for second order differential inclusions of the form $\ddot{u}(t) \in F(t, u(t), \dot{u}(t)) (t \in [0, 1])$ with boundary conditions, where $F : [0, 1] \times E \times E \rightrightarrows E$ is a convex compact multifunction, Lebesgue-measurable on $[0, 1]$, upper semicontinuous on $E \times E$ and integrably compact in finite and infinite dimensional spaces has been studied by many authors see for example [1],[7]. Our aim in this article is to provide an existence result for the differential inclusion with two-point boundary conditions in a finite dimensional space E of the form

$$(P_F) \begin{cases} \ddot{u}(t) \in F(u(t), \dot{u}(t)), & a.e. \ t \in [a, b], \ (0 \leq a < b < +\infty) \\ u(a) = u(b) = v_0, \end{cases}$$

where $F : E \times E \rightrightarrows E$ is an upper semicontinuous multifunction with almost convex values, i.e., the convexity is replaced by a strictly weaker condition.

For the first order differential inclusions with almost convex values we refer the reader to [5].

After some preliminaries, we present a result which is the existence of $\mathbf{W}_E^{2,1}([a, b])$ -solutions of (P_F) where F is a convex valued multifunction. Using this convexified problem we show that the differential inclusion (P_F) has solutions if the values of F are almost convex. As an example of the almost convexity of the values of the right-hand side, notice that, if $F(t, x, y)$ is a convex set not containing the origin then the boundary of $F(x, y)$, $\partial F(x, y)$, is almost convex.

2. NOTATION AND PRELIMINARIES

Throughout, $(E, \|\cdot\|)$ is a real separable Banach space and E' is its topological dual, $\bar{\mathbf{B}}_E$ is the closed unit ball of E and $\sigma(E, E')$ the weak topology on E . We denote by $\mathbf{L}_E^1([a, b])$ the space of all Lebesgue-Bochner integrable E valued mappings defined on $[a, b]$.

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Let $\mathbf{C}_E([a, b])$ be the Banach space of all continuous mappings $u : [a, b] \rightarrow E$ endowed with the sup-norm, and $\mathbf{C}_E^1([a, b])$ be the Banach space of all continuous mappings $u : [a, b] \rightarrow E$ with continuous derivative, equipped with the norm

$$\|u\|_{\mathbf{C}^1} = \max\left\{\max_{t \in [a, b]} \|u(t)\|, b \max_{t \in [a, b]} \|\dot{u}(t)\|\right\}.$$

Recall that a mapping $v : [a, b] \rightarrow E$ is said to be scalarly derivable when there exists some mapping $\dot{v} : [a, b] \rightarrow E$ (called the weak derivative of v) such that, for every $x' \in E'$, the scalar function $\langle x', v(\cdot) \rangle$ is derivable and its derivative is equal to $\langle x', \dot{v}(\cdot) \rangle$. The weak derivative \dot{v} of v when it exists is the weak second derivative.

By $\mathbf{W}_E^{2,1}([a, b])$ we denote the space of all continuous mappings in $\mathbf{C}_E([a, b])$ such that their first derivatives are continuous and their second weak derivatives belong to $\mathbf{L}_E^1([a, b])$.

For a subset $A \subset E$, $co(A)$ denotes its convex hull and $\overline{co}(A)$ its closed convex hull.

Let X be a vector space, a set $K \subset X$ is called almost convex if for every $\xi \in co(K)$ there exist λ_1 and λ_2 , $0 \leq \lambda_1 \leq 1 \leq \lambda_2$, such that $\lambda_1 \xi \in K$, $\lambda_2 \xi \in K$.

Note that every convex set is almost convex.

3. THE MAIN RESULT

We begin with a lemma which summarizes some properties of some Green type function. It will after be used in the study of our boundary value problems (see [1], [7] and [3]).

Lemma 3.1. *Let E be a separable Banach space, $v_0 \in E$ and $G : [a, b] \times [a, b] \rightarrow \mathbb{R}$ ($0 \leq a < b < \infty$) be the function defined by*

$$G(t, s) = \begin{cases} -\frac{1}{b}(b-t)(s-a) & \text{if } a \leq s \leq t \leq b, \\ -\frac{1}{b}(t-a)(b-s) & \text{if } a \leq t \leq s \leq b. \end{cases}$$

Then the following assertions hold.

(1) *If $u \in \mathbf{W}_E^{2,1}([a, b])$ with $u(a) = u(b) = v_0$, then*

$$u(t) = v_0 + \frac{b}{b-a} \int_a^b G(t, s) \ddot{u}(s) ds, \quad \forall t \in [a, b].$$

(2) *$G(\cdot, s)$ is derivable on $[a, b[$ for every $s \in [a, b]$, except on the diagonal, and its derivative is given by*

$$\frac{\partial G}{\partial t}(t, s) = \begin{cases} \frac{1}{b}(s-a) & \text{if } a \leq s < t \leq b \\ -\frac{1}{b}(b-s) & \text{if } a \leq t < s \leq b. \end{cases}$$

(3) $G(.,.)$ and $\frac{\partial G}{\partial t}(.,.)$ satisfy

$$\sup_{t,s \in [a,b]} |G(t,s)| \leq b, \quad \sup_{t,s \in [a,b], t \neq s} \left| \frac{\partial G}{\partial t}(t,s) \right| \leq 1. \quad (3.1)$$

(4) For $f \in \mathbf{L}_E^1([a,b])$ and for the mapping $u_f : [a,b] \rightarrow E$ defined by

$$u_f(t) = v_0 + \frac{b}{b-a} \int_a^b G(t,s) f(s) ds, \quad \forall t \in [a,b] \quad (3.2)$$

one has $u_f(a) = u_f(b) = v_0$.

Furthermore, the mapping u_f is derivable, and its derivative \dot{u}_f satisfies

$$\lim_{h \rightarrow 0} \frac{u_f(t+h) - u_f(t)}{h} = \dot{u}_f(t) = \frac{b}{b-a} \int_a^b \frac{\partial G}{\partial t}(t,s) f(s) ds, \quad (3.3)$$

for all $t \in [a,b]$. Consequently, \dot{u}_f is a continuous mapping from $[a,b]$ into the space E .

(5) The mapping \dot{u}_f is scalarly derivable, that is, there exists a mapping $\ddot{u}_f : [a,b] \rightarrow E$ such that, for every $x' \in E'$, the scalar function $\langle x', \dot{u}_f(\cdot) \rangle$ is derivable, with $\frac{d}{dt} \langle x', \dot{u}_f(t) \rangle = \langle x', \ddot{u}_f(t) \rangle$, furthermore

$$\ddot{u}_f = f \text{ a.e. on } [a,b]. \quad (3.4)$$

Let us mention a useful consequence of Lemma 3.1.

Proposition 3.2. *Let E be a separable Banach space and let $f : [a,b] \rightarrow E$ be a continuous mapping (respectively a mapping in $\mathbf{L}_E^1([a,b])$). Then the mapping*

$$u_f(t) = v_0 + \frac{b}{b-a} \int_a^b G(t,s) f(s) ds, \quad \forall t \in [a,b]$$

is the unique $\mathbf{C}_E^2([a,b])$ -solution (respectively $\mathbf{W}_E^{2,1}([a,b])$ -solution) to the differential equation

$$\begin{cases} \ddot{u}(t) = f(t), & \forall t \in [a,b], \\ u(a) = u(b) = v_0. \end{cases}$$

The following is an existence result for a second order differential inclusion with boundary conditions and a convex valued right hand side. It will be used in the proof of our main theorem.

Proposition 3.3. *Let E be a finite dimensional space, $F : E \times E \rightrightarrows E$ be a convex compact valued multifunction, upper semicontinuous on $E \times E$. Suppose that there is a nonnegative function $m \in \mathbf{L}_{\mathbb{R}}^1([a,b])$ such that $F(x,y) \subset m(t) \overline{\mathbf{B}}_E$ for all $x,y \in [a,b]$. Let $v_0 \in E$. Then the $\mathbf{W}_E^{2,1}([a,b])$ -solutions set of the problem*

$$(P_F) \begin{cases} \ddot{u}(t) \in F(u(t), \dot{u}(t)), & \text{a.e. } t \in [a,b], \\ u(a) = u(b) = v_0, \end{cases}$$

is nonempty and compact in $\mathbf{C}_E^1([a, b])$.

Proof. Step 1. Let

$$\mathbf{S} = \{f \in \mathbf{L}_E^1([a, b]) : \|f(t)\| \leq m(t), a.e. t \in [a, b]\}$$

and

$$\mathbf{X} = \{u_f : [a, b] \rightarrow E : u_f(t) = v_0 + \frac{b}{b-a} \int_a^b G(t, s) f(s) ds, \forall t \in [a, b], f \in \mathbf{S}\}.$$

Obviously \mathbf{S} and \mathbf{X} are convex. Let us prove that \mathbf{S} is a $\sigma(\mathbf{L}_E^1([a, b]), \mathbf{L}_E^\infty([a, b]))$ -compact subset of $\mathbf{L}_E^1([a, b])$. Indeed, let (f_n) be a sequence of \mathbf{S} . It is clear that (f_n) is bounded in $\mathbf{L}_E^\infty([a, b])$, taking a subsequence if necessary, we may conclude that (f_n) weakly* or $\sigma(\mathbf{L}_E^\infty([a, b]), \mathbf{L}_E^1([a, b]))$ -converges to some mapping $f \in \mathbf{L}_E^\infty([a, b]) \subset \mathbf{L}_E^1([a, b])$. Consequently, for all $y(\cdot) \in \mathbf{L}_E^1([a, b])$ we have

$$\lim_{n \rightarrow \infty} \langle f_n(\cdot), y(\cdot) \rangle = \langle f(\cdot), y(\cdot) \rangle.$$

Let $z(\cdot) \in \mathbf{L}_E^\infty([a, b]) \subset \mathbf{L}_E^1([a, b])$, then

$$\lim_{n \rightarrow \infty} \langle f_n(\cdot), z(\cdot) \rangle = \langle f(\cdot), z(\cdot) \rangle.$$

This shows that (f_n) weakly or $\sigma(\mathbf{L}_E^1([a, b]), \mathbf{L}_E^\infty([a, b]))$ -converges to $f(\cdot)$ and that $\|f(t)\| \leq m(t)$ a.e on $[a, b]$ since \mathbf{S} is convex and strongly closed in $\mathbf{L}_E^1([a, b])$ and hence it is weakly closed in $\mathbf{L}_E^1([a, b])$.

Now, let us prove that \mathbf{X} is compact in $\mathbf{C}_E^1([a, b])$ equipped with the norm $\|\cdot\|_{\mathbf{C}^1}$. For any $u_f \in \mathbf{X}$ and all $t, \tau \in [a, b]$ we have

$$\begin{aligned} \|u_f(t) - u_f(\tau)\| &\leq \frac{b}{b-a} \int_a^b |G(t, s) - G(\tau, s)| \|f(s)\| ds \\ &\leq \frac{b}{b-a} \int_a^b |G(t, s) - G(\tau, s)| m(s) ds \end{aligned}$$

and by the relation (3.3) in Lemma 3.1

$$\begin{aligned} \|\dot{u}_f(t) - \dot{u}_f(\tau)\| &\leq \frac{b}{b-a} \int_a^b \left| \frac{\partial G}{\partial t}(t, s) - \frac{\partial G}{\partial t}(\tau, s) \right| \|f(s)\| ds \\ &\leq \frac{b}{b-a} \int_a^b \left| \frac{\partial G}{\partial t}(t, s) - \frac{\partial G}{\partial t}(\tau, s) \right| m(s) ds. \end{aligned}$$

Since $m \in \mathbf{L}_\mathbb{R}^1([a, b])$ and the function G is uniformly continuous we get the equicontinuity of the sets \mathbf{X} and $\{\dot{u}_f : u_f \in \mathbf{X}\}$. On the other hand, for any $u_f \in \mathbf{X}$ and for all $t \in [a, b]$ we have by the relations (3.1), (3.2) and (3.3)

$$\|u_f(t)\| \leq \|v_0\| + \frac{b^2}{b-a} \|m\|_{\mathbf{L}^1} \text{ and } \|\dot{u}_f(t)\| \leq \frac{b}{b-a} \|m\|_{\mathbf{L}^1},$$

that is, the sets $\mathbf{X}(t)$ and $\{\dot{u}_f(t) : u_f \in \mathbf{X}\}$ are relatively compact in the finite dimensional space E . Hence, we conclude that \mathbf{X} is relatively compact

in $(\mathbf{C}_E^1([a, b]), \|\cdot\|_{\mathbf{C}^1})$. We claim that \mathbf{X} is closed in $(\mathbf{C}_E^1([a, b]), \|\cdot\|_{\mathbf{C}^1})$. Fix any sequence (u_{f_n}) of \mathbf{X} converging to $u \in \mathbf{C}_E^1([a, b])$. Then, for each $n \in \mathbb{N}$

$$u_{f_n}(t) = v_0 + \frac{b}{b-a} \int_a^b G(t, s) f_n(s) ds, \quad \forall t \in [a, b]$$

and $f_n \in \mathbf{S}$. Since \mathbf{S} is $\sigma(\mathbf{L}_E^1([a, b]), \mathbf{L}_E^\infty([a, b]))$ -compact, by extracting a subsequence if necessary we may conclude that $(f_n) \sigma(\mathbf{L}_E^1([a, b]), \mathbf{L}_E^\infty([a, b]))$ -converges to $f \in \mathbf{S}$. Putting for all $t \in [a, b]$

$$u_f(t) = v_0 + \frac{b}{b-a} \int_a^b G(t, s) f(s) ds,$$

we obtain for all $z(\cdot) \in \mathbf{L}_E^\infty([a, b])$ and for all $t \in [a, b]$

$$\lim_{n \rightarrow \infty} \langle f_n(\cdot), G(t, \cdot) z(\cdot) \rangle = \langle f(\cdot), G(t, \cdot) z(\cdot) \rangle.$$

Hence

$$\begin{aligned} \lim_{n \rightarrow \infty} \int_a^b \langle G(t, s) f_n(s), z(s) \rangle ds &= \lim_{n \rightarrow \infty} \int_a^b \langle f_n(s), G(t, s) z(s) \rangle ds \\ &= \int_a^b \langle f(s), G(t, s) z(s) \rangle ds \\ &= \int_a^b \langle G(t, s) f(s), z(s) \rangle ds. \end{aligned}$$

In particular, for $z(\cdot) = \chi_{[a, b]}(\cdot) e_j$, where $\chi_{[a, b]}(\cdot)$ stands for the characteristic function of $[a, b]$ and (e_j) a basis of E , we obtain

$$\lim_{n \rightarrow \infty} \int_a^b \langle G(t, s) f_n(s), \chi_{[a, b]}(s) e_j \rangle ds = \int_a^b \langle G(t, s) f(s), \chi_{[a, b]}(s) e_j \rangle ds,$$

or equivalently

$$\langle \lim_{n \rightarrow \infty} \int_a^b G(t, s) f_n(s) ds, e_j \rangle = \langle \int_a^b G(t, s) f(s) ds, e_j \rangle,$$

which entails

$$\lim_{n \rightarrow \infty} (v_0 + \frac{b}{b-a} \int_a^b G(t, s) f_n(s) ds) = v_0 + \frac{b}{b-a} \int_a^b G(t, s) f(s) ds = u_f(t).$$

Consequently, the sequence (u_{f_n}) converges to u_f in $\mathbf{C}_E([a, b])$. By the same arguments, we prove that the sequence (\dot{u}_{f_n}) with

$$\dot{u}_{f_n}(t) = \frac{b}{b-a} \int_a^b \frac{\partial G}{\partial t}(t, s) f_n(s) ds, \quad \forall t \in [a, b]$$

converges to \dot{u}_f in $\mathbf{C}_E([a, b])$. That is, (u_{f_n}) converges to u_f in $\mathbf{C}_E^1([a, b])$. This shows that \mathbf{X} is compact in $(\mathbf{C}_E^1([a, b]), \|\cdot\|_{\mathbf{C}^1})$.

Step 2. Observe that a mapping $u : [a, b] \rightarrow E$ is a $\mathbf{W}_E^{2,1}([a, b])$ -solution of (P_F) iff there exists $u_f \in \mathbf{X}$ and $f(t) \in F(u_f(t), \dot{u}_f(t))$ for a.e $t \in [a, b]$.

For any Lebesgue-measurable mappings $v, w : [a, b] \rightarrow E$, there is a Lebesgue-measurable selection $s \in \mathbf{S}$ such that $s(t) \in F(v(t), w(t))$ a.e. Indeed, there exist sequences (v_n) and (w_n) of simple E -valued functions such that (v_n) converges pointwise to v and (w_n) converges pointwise to w for E endowed by the strong topology. Notice that the multifunctions $F(v_n(\cdot), w_n(\cdot))$ are Lebesgue-measurable. Let s_n be a Lebesgue-measurable selection of $F(v_n(\cdot), w_n(\cdot))$. As $s_n(t) \in F(v_n(t), w_n(t)) \subset m(t)\overline{\mathbf{B}}_E$ for all $t \in [a, b]$ and \mathbf{S} is $\sigma(\mathbf{L}_E^1([a, b]), \mathbf{L}_E^\infty([a, b]))$ -compact in $\mathbf{L}_E^1([a, b])$, by Eberlein-Šmulian theorem, we may extract from (s_n) a subsequence (s'_n) which converges $\sigma(\mathbf{L}_E^1([a, b]), \mathbf{L}_E^\infty([a, b]))$ to some mapping $s \in \mathbf{S}$. Here we may invoke the fact that \mathbf{S} is a weakly compact metrizable set in the separable Banach space $\mathbf{L}_E^1([a, b])$. Now, application of the Mazur's trick to (s'_n) provides a sequence (z_n) with $z_n \in \text{co}\{s'_m : m \geq n\}$ such that (z_n) converges almost every where to s . Then, for almost every $t \in [a, b]$

$$\begin{aligned} s(t) &\in \bigcap_{k \geq 0} \overline{\{z_n(t) : n \geq k\}} \\ &\subset \bigcap_{k \geq 0} \overline{\text{co}\{s'_n(t) : n \geq k\}}. \end{aligned}$$

As $s'_n(t) \in F(v_n(t), w_n(t))$, we obtain

$$\begin{aligned} s(t) &\in \bigcap_{k \geq 0} \overline{\text{co}\left(\bigcup_{n \geq k} F(v_n(t), w_n(t))\right)} \\ &= \overline{\text{co}(\limsup_{n \rightarrow \infty} F(v_n(t), w_n(t)))}, \end{aligned}$$

using the pointwise convergence of $(v_n(\cdot))$ and $(w_n(\cdot))$ to $v(\cdot)$ and $w(\cdot)$ respectively, the upper semicontinuity of F and the compactness of its values we get

$$s(t) \in \overline{\text{co}(F(v(t), w(t)))} = F(v(t), w(t))$$

since $F(v(t), w(t))$ is a closed convex set.

Step 3. Let us consider the multifunction $\Phi : \mathbf{S} \rightrightarrows \mathbf{S}$ defined by

$$\Phi(f) = \{g \in \mathbf{S} : g(t) \in F(u_f(t), \dot{u}_f(t)) \text{ a.e. } t \in [a, b]\}$$

where $u_f \in \mathbf{X}$. In view of Step 2, $\Phi(f)$ is a nonempty set. These considerations lead us to the application of the Kakutani-ky Fan fixed point theorem to the multifunction $\Phi(\cdot)$. It is clear that $\Phi(f)$ is a convex weakly compact subset of \mathbf{S} . We need to check that Φ is upper semicontinuous on the convex weakly compact metrizable set \mathbf{S} . Equivalently, we need to prove that the graph of Φ is sequentially weakly compact in $\mathbf{S} \times \mathbf{S}$. Let (f_n, g_n) be a sequence in the graph of Φ . $(f_n) \subset \mathbf{S}$. By extracting a subsequence we may

suppose that $(f_n) \sigma(\mathbf{L}_E^1([a, b]), \mathbf{L}_E^\infty([a, b]))$ converges to $f \in \mathbf{S}$. It follows that the sequences (u_{f_n}) and (\dot{u}_{f_n}) converge pointwise to u_f and \dot{u}_f respectively. On the other hand, $g_n \in \Phi(f_n) \subset \mathbf{S}$. We may suppose that (g_n) converges weakly to some element $g \in \mathbf{S}$. As $g_n(t) \in F(u_{f_n}(t), \dot{u}_{f_n}(t))$ a.e., by repeating the arguments given in Step 2, we obtain that $g(t) \in F(u_f(t), \dot{u}_f(t))$ a.e. This shows that the graph of Φ is weakly compact in the weakly compact set $\mathbf{S} \times \mathbf{S}$. Hence Φ admits a fixed point, that is, there exists $f \in \mathbf{S}$ such that $f \in \Phi(f)$ and so $f(t) \in F(u_f(t), \dot{u}_f(t))$ for almost every $t \in [a, b]$. Equivalently (see Lemma 3.1) $\ddot{u}_f(t) \in F(u_f(t), \dot{u}_f(t))$ for almost every $t \in [a, b]$ with $u_f(a) = \dot{u}_f(b) = v_0$, what in turn, means that the mapping u_f is a $\mathbf{W}_E^{2,1}([a, b])$ -solution of the problem (P_F) . Compactness of the solutions set follows easily from the compactness in $\mathbf{C}_E^1([a, b])$ of \mathbf{X} given in Step 1, and the preceding arguments. ■

Now, we present an existence result of solutions to the problem (P_F) if we suppose on F a linear growth condition.

Theorem 3.4. *Let E be a finite dimensional space and $F : E \times E \rightrightarrows E$ be a convex compact valued multifunction, upper semicontinuous on $E \times E$. Suppose that there is two nonnegative functions p and q in $\mathbf{L}_{\mathbb{R}}^1([a, b])$ with $\|p+q\|_{\mathbf{L}_{\mathbb{R}}^1} < \frac{b-a}{b^2}$ such that $F(x, y) \subset (p(t)\|x\| + bq(t)\|y\|)\overline{\mathbf{B}}_E$ for all $t \in [a, b]$ and for all $(x, y) \in E \times E$. Let $v_0 \in E$. Then the $\mathbf{W}_E^{2,1}([a, b])$ -solutions set of the problem (P_F) is nonempty and compact in $\mathbf{C}_E^1([a, b])$.*

For the proof of our Theorem we need the following Lemma.

Lemma 3.5. *Let E be a finite dimensional space. Suppose that the hypotheses of Theorem 3.4 are satisfied. If u is a solution in $\mathbf{W}_E^{2,1}([a, b])$ of the problem (P_F) , then for all $t \in [a, b]$ we have*

$$\|u(t)\| \leq \alpha, \quad \|\dot{u}(t)\| \leq \frac{\alpha}{b}$$

where

$$\alpha = \frac{\|v_0\|}{1 - \frac{b^2}{b-a} \|p+q\|_{\mathbf{L}_{\mathbb{R}}^1}}.$$

Proof. Suppose that $u : [a, b] \rightarrow E$ is a $\mathbf{W}_E^{2,1}([a, b])$ -solution of (P_F) . Then, there exists a measurable mapping $f : [a, b] \rightarrow E$ such that $f(t) \in F(u_f(t), \dot{u}_f(t))$ for almost every $t \in [a, b]$ and

$$u(t) = u_f(t) = v_0 + \frac{b}{b-a} \int_a^b G(t, s) f(s) ds \quad \forall t \in [a, b].$$

Consequently, for all $t \in [a, b]$

$$\begin{aligned}
 \|u(t)\| &= \left\| v_0 + \frac{b}{b-a} \int_a^b G(t, s) f(s) ds \right\| \\
 &\leq \|v_0\| + \frac{b}{b-a} \int_a^b |G(t, s)| \|f(s)\| ds \\
 &\leq \|v_0\| + \frac{b}{b-a} \int_a^b (b(p(s)\|u(s)\| + bq(s)\|\dot{u}(s)\|)) ds \\
 &\leq \|v_0\| + \frac{b}{b-a} \int_a^b (b(p(s)\|u\|_{\mathbf{C}_E^1} + q(s)\|u\|_{\mathbf{C}_E^1})) ds \\
 &\leq \|v_0\| + \frac{b^2}{b-a} \|u\|_{\mathbf{C}_E^1} \int_a^b (p(s) + q(s)) ds,
 \end{aligned}$$

and hence,

$$\|u(t)\| \leq \|v_0\| + \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} \|u\|_{\mathbf{C}_E^1}.$$

In the same way we have

$$\begin{aligned}
 \|\dot{u}(t)\| &= \left\| \frac{b}{b-a} \int_a^b \frac{\partial G}{\partial t}(t, s) f(s) ds \right\| \leq \frac{b}{b-a} \int_a^b \left| \frac{\partial G}{\partial t}(t, s) \right| \|f(s)\| ds \\
 &\leq \frac{b}{b-a} \int_a^b (p(s)\|u(s)\| + bq(s)\|\dot{u}(s)\|) ds \leq \frac{b}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} \|u\|_{\mathbf{C}_E^1},
 \end{aligned}$$

and hence

$$b\|\dot{u}(t)\| \leq \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} \|u\|_{\mathbf{C}_E^1} \leq \|v_0\| + \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} \|u\|_{\mathbf{C}_E^1}.$$

These last inequalities show that

$$\|u\|_{\mathbf{C}_E^1} \leq \|v_0\| + \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} \|u\|_{\mathbf{C}_E^1},$$

or

$$\left(1 - \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1}\right) \|u\|_{\mathbf{C}_E^1} \leq \|v_0\|,$$

equivalently

$$\|u\|_{\mathbf{C}_E^1} \leq \frac{\|v_0\|}{1 - \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1}} = \alpha.$$

By the definition of $\|u\|_{\mathbf{C}_E^1}$ we conclude that for all $t \in [a, b]$

$$\|u(t)\| \leq \alpha \quad \text{and} \quad \|\dot{u}(t)\| \leq \frac{\alpha}{b}.$$

Proof of Theorem 3.4. Let us consider the mapping $\varphi_\kappa : E \rightarrow E$ defined by

$$\varphi_\kappa(x) = \begin{cases} \|x\| & \text{if } \|x\| \leq \kappa \\ \frac{\kappa x}{\|x\|} & \text{if } \|x\| > \kappa, \end{cases}$$

and consider the multifunction $F_0 : E \times E \rightrightarrows E$ defined by

$$F_0(x, y) = F(\varphi_\alpha(x), \varphi_{\frac{\alpha}{b}}(y)).$$

Then F_0 inherits the hypotheses on F , and furthermore, for all $(x, y) \in E \times E$

$$\begin{aligned} F_0(x, y) &= F(\varphi_\alpha(x), \varphi_{\frac{\alpha}{b}}(y)) \\ &\subset (p(t)\|\varphi_\alpha(x)\| + bq(t)\|\varphi_{\frac{\alpha}{b}}(y)\|)\overline{\mathbf{B}}_E \\ &\subset (p(t)\alpha + b\frac{1}{b}q(t)\alpha)\overline{\mathbf{B}}_E = \alpha(p(t) + q(t))\overline{\mathbf{B}}_E = \beta(t)\overline{\mathbf{B}}_E. \end{aligned}$$

Consequently, F_0 satisfies all the hypotheses of Proposition 3.3. Hence, we conclude the existence of a $\mathbf{W}_E^{2,1}([a, b])$ -solution of the problem (P_{F_0}) .

Now, let us prove that u is a solution of (P_{F_0}) if and only if u is a solution of (P_F) .

If u is a solution of (P_{F_0}) , there exists a measurable mapping f_0 such that $u = u_{f_0}$ and $f_0(t) \in F_0(u(t), \dot{u}(t))$, a.e., with for almost every $t \in [a, b]$

$$\|f_0(t)\| \leq \beta(t) = \alpha(p(t) + q(t)).$$

Using this inequality and the fact that for all $t \in [a, b]$

$$u(t) = v_0 + \frac{b}{b-a} \int_a^b G(t, s) f_0(s) ds, \text{ and } \dot{u}(t) = \frac{b}{b-a} \int_a^b \frac{\partial G}{\partial t}(t, s) f_0(s) ds,$$

we obtain

$$\begin{aligned} \|u(t)\| &\leq \|v_0\| + \frac{b^2}{b-a} \|\beta\|_{\mathbf{L}_{\mathbb{R}}^1} = \|v_0\| + \frac{b^2}{b-a} \alpha \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} \\ &= \|v_0\| + \left(\frac{b^2}{b-a}\right) \frac{\|v_0\|}{1 - \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1}} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} = \frac{\|v_0\|}{1 - \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1}} = \alpha, \end{aligned}$$

and

$$\begin{aligned} \|\dot{u}(t)\| &\leq \frac{b}{b-a} \|\beta\|_{\mathbf{L}_{\mathbb{R}}^1} = \frac{b}{b-a} \alpha \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} = \left(\frac{b}{b-a}\right) \frac{\|v_0\|}{1 - \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1}} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} \\ &< \left(\frac{b}{b-a}\right) \left(\frac{\|v_0\|}{1 - \frac{b^2}{b-a} \|p + q\|_{\mathbf{L}_{\mathbb{R}}^1}}\right) \left(\frac{b-a}{b^2}\right) = \frac{\alpha}{b}. \end{aligned}$$

These last relations show that $\varphi_\alpha(u(t)) = u(t)$ and $\varphi_{\frac{\alpha}{b}}(\dot{u}(t)) = \dot{u}(t)$, or equivalently $F_0(u(t), \dot{u}(t)) = F(u(t), \dot{u}(t))$. Consequently, u is a solution of (P_F) .

Suppose now that u is a solution of (P_F) . By Lemma 3.5, we have for all $t \in [a, b]$

$$\|u(t)\| \leq \alpha \text{ and } \|\dot{u}(t)\| \leq \frac{\alpha}{b}.$$

Then, $F(u(t), \dot{u}(t)) = F_0(u(t), \dot{u}(t))$, that is, u is a solution of (P_{F_0}) . \blacksquare

Now we are able to give our main result.

Theorem 3.6. *Let E be a finite dimensional space and $F : E \times E \rightrightarrows E$ be an almost convex compact valued multifunction, upper semicontinuous on $E \times E$ and satisfying the following assumptions:*

(1) *there is two nonnegative functions $p, q \in \mathbf{L}_{\mathbb{R}}^1([a, b])$, satisfying*

$\|p + q\|_{\mathbf{L}_{\mathbb{R}}^1} < \frac{b-a}{b^2}$, such that $F(x, y) \subset (p(t)\|x\| + bq(t)\|y\|)\overline{\mathbf{B}}_E$ for all $(x, y) \in E \times E$,

(2) *$F(x, \xi y) \subseteq \xi F(x, y)$ for all $(x, y) \in E \times E$ and for every $\xi > 0$.*

Let $v_0 \in E$. Then there is at least a $\mathbf{W}_E^{2,1}([a, b])$ -solution of the problem (P_F) .

For the proof we need the following result.

Theorem 3.7. *Let $F : E \times E \rightrightarrows E$ be a multifunction upper semicontinuous on $E \times E$. Suppose that the assumption (2) in Theorem 3.6 is also satisfied. Let $v_0 \in E$ and let $x : [a, b] \rightarrow E$, be a solution of the problem*

$$(P_{\text{co}(F)}) \begin{cases} \ddot{u}(t) \in \text{co}(F(u(t), \dot{u}(t))), & \text{a.e. } t \in [a, b], \\ u(a) = u(b) = v_0, \end{cases}$$

and assume that there are two constants λ_1 and λ_2 , satisfying $0 \leq \lambda_1 \leq 1 \leq \lambda_2$, such that for almost every $t \in [a, b]$, we have

$$\lambda_1 \ddot{x}(t) \in F(x(t), \dot{x}(t)) \text{ and } \lambda_2 \ddot{x}(t) \in F(x(t), \dot{x}(t)).$$

Then there exists $t = t(\tau)$, a nondecreasing absolutely continuous map of the interval $[a, b]$ onto itself, such that the map $\tilde{x}(\tau) = x(t(\tau))$ is a solution of the problem (P_F) . Moreover $\tilde{x}(a) = \tilde{x}(b) = v_0$.

Proof. Step 1. Let $[\alpha, \beta]$ ($0 \leq \alpha < \beta < +\infty$) be an interval, and assume that there exist two constants λ_1, λ_2 , with the properties stated above.

Assume that $\lambda_1 > 0$. We claim that there exist two measurable subsets of $[\alpha, \beta]$, having characteristic functions \mathcal{X}_1 and \mathcal{X}_2 such that $\mathcal{X}_1 + \mathcal{X}_2 = \mathcal{X}_{[\alpha, \beta]}$, and an absolutely continuous function $s = s(\tau)$ on $[\alpha, \beta]$, satisfying $s(\alpha) - s(\beta) = \alpha - \beta$, such that

$$\dot{s}(\tau) = \frac{1}{\lambda_1} \mathcal{X}_1(\tau) + \frac{1}{\lambda_2} \mathcal{X}_2(\tau).$$

Indeed, set

$$\gamma = \begin{cases} \frac{1}{2} & \text{when } \lambda_1 = \lambda_2 = 1 \\ \frac{\lambda_2 - 1}{\lambda_2 - \lambda_1} & \text{otherwise.} \end{cases}$$

With this definition we have that $0 \leq \gamma \leq 1$ and that both equalities

$$1 = \gamma + (1 - \gamma) = \gamma\lambda_1 + (1 - \gamma)\lambda_2.$$

In particular, we have

$$\int_{\alpha}^{\beta} 1 dt = \int_{\alpha}^{\beta} \left[\frac{\gamma\lambda_1}{\lambda_1} + \frac{(1 - \gamma)\lambda_2}{\lambda_2} \right] dt.$$

Applying Liapunov's theorem on the range of measures, to infer the existence of two subsets having characteristic functions $\mathcal{X}_1(\cdot), \mathcal{X}_2(\cdot)$ such that $\mathcal{X}_1 + \mathcal{X}_2 = \mathcal{X}_{[\alpha, \beta]}$ and with the property that

$$\int_{\alpha}^{\beta} 1 dt = \int_{\alpha}^{\beta} \left[\frac{1}{\lambda_1} \mathcal{X}_1(t) + \frac{1}{\lambda_2} \mathcal{X}_2(t) \right] dt.$$

Define $\dot{s}(\tau) = \frac{1}{\lambda_1} \mathcal{X}_1(\tau) + \frac{1}{\lambda_2} \mathcal{X}_2(\tau)$. Then $\int_{\alpha}^{\beta} \dot{s}(\tau) d\tau = \beta - \alpha$.

Step 2. (a) Consider

$$C = \{ \tau \in [a, b] : 0 \in F(x(\tau), \dot{x}(\tau)) \}.$$

We have that C is a closed set. Indeed, let (τ_n) be a sequence in C converging to $\tau \in [a, b]$. Then, for each $n \in \mathbb{N}$,

$$0 \in F(x(\tau_n), \dot{x}(\tau_n)).$$

Since F is upper semicontinuous with compact values we have that its graph is closed, and since $x(\cdot)$ and $\dot{x}(\cdot)$ are continuous we get $0 \in F(x(\tau), \dot{x}(\tau))$, that is C is closed.

(b) Consider the case in which C is empty. In this case, it cannot be that $\lambda_1 = 0$, and the Step 1 can be applied to the interval $[a, b]$. Set $s(\tau) = a + \int_a^{\tau} \dot{s}(\omega) d\omega$, s is increasing and we have $s(a) = a$ and $s(b) = a + \int_a^b \dot{s}(\omega) d\omega = a + b - a = b$, that is s maps $[a, b]$ onto itself. Let $t : [a, b] \rightarrow [a, b]$ be its inverse, so $t(a) = a$; $t(b) = b$, and we have $\frac{d}{d\tau} s(t(\tau)) = \dot{s}(t(\tau)) \dot{t}(\tau) = 1$. Then, $\dot{t}(\tau) = \frac{1}{\dot{s}(t(\tau))} = \lambda_1 \mathcal{X}_1(t(\tau)) + \lambda_2 \mathcal{X}_2(t(\tau))$, and $\ddot{t}(\tau) = 0$. Consider the map $\tilde{x}(\tau) = x(t(\tau))$. We have $\frac{d}{d\tau} \tilde{x}(\tau) = \dot{t}(\tau) \dot{x}(t(\tau))$, and $\frac{d^2}{d\tau^2} \tilde{x}(\tau) =$

$(\dot{t}(\tau))^2 \ddot{x}(t(\tau)) + \ddot{t}(\tau) \dot{x}(t(\tau)) = \ddot{x}(t(\tau))(\dot{t}(\tau))^2$. Hence

$$\begin{aligned} \frac{1}{\dot{t}(\tau)} \frac{d^2}{d\tau^2} \tilde{x}(\tau) &= \ddot{x}(t(\tau))(\dot{t}(\tau)) = \ddot{x}(t(\tau))[\lambda_1 \mathcal{X}_1(t(\tau)) + \lambda_2 \mathcal{X}_2(t(\tau))] \\ &\in F(x(t(\tau)), \dot{x}(t(\tau))) = F(\tilde{x}(\tau), \frac{1}{\dot{t}(\tau)} \dot{\tilde{x}}(\tau)), \end{aligned}$$

and by the assumption 2, we have

$$F(\tilde{x}(\tau), \frac{1}{\dot{t}(\tau)} \dot{\tilde{x}}(\tau)) \subseteq \frac{1}{\dot{t}(\tau)} F(\tilde{x}(\tau), \dot{\tilde{x}}(\tau))$$

then we get

$$\frac{1}{\dot{t}(\tau)} \frac{d^2}{d\tau^2} \tilde{x}(\tau) \in \frac{1}{\dot{t}(\tau)} F(\tilde{x}(\tau), \dot{\tilde{x}}(\tau)).$$

Consequently

$$\frac{d^2}{d\tau^2} \tilde{x}(\tau) \in F(\tilde{x}(\tau), \dot{\tilde{x}}(\tau)).$$

(c) Now we shall assume that C is nonempty. Let $c = \sup\{\tau; \tau \in C\}$, there is a sequence (τ_n) in C such that $\lim_{n \rightarrow \infty} \tau_n = c$. Since C is closed we get $c \in C$. The complement of C is open relative to $[a, b]$, it consists of at most countably many nonoverlapping open intervals $]a_i, b_i[$, with the possible exception of one of the form $]a_{i_i}, b_{i_i}[$ with $a_{i_i} = a$ and one of the form $]a_{i_f}, b_{i_f}[$ with $a_{i_f} = c$. For each i , apply Step 1 to the interval $]a_i, b_i[$ to infer the existence of K_1^i and K_2^i , two subsets of $]a_i, b_i[$ with characteristic functions $\mathcal{X}_1^i(\cdot)$, $\mathcal{X}_2^i(\cdot)$ such that $\mathcal{X}_1^i + \mathcal{X}_2^i = \mathcal{X}_{]a_i, b_i[}$, setting

$$\dot{s}(\tau) = \frac{1}{\lambda_1} \mathcal{X}_1^i(\tau) + \frac{1}{\lambda_2} \mathcal{X}_2^i(\tau)$$

we obtain

$$\int_{a_i}^{b_i} \dot{s}(\omega) d\omega = b_i - a_i.$$

(d) On $[a, c]$ set

$$\dot{s}(\tau) = \frac{1}{\lambda_2} \mathcal{X}_C(\tau) + \sum_i \left(\frac{1}{\lambda_1} \mathcal{X}_1^i(\tau) + \frac{1}{\lambda_2} \mathcal{X}_2^i(\tau) \right),$$

where the sum is over all intervals contained in $[a, c]$, i.e., with the exception of $]c, b]$. We have that

$$\int_a^c \dot{s}(\omega) d\omega = \kappa \leq c - a$$

since $\lambda_2 \geq 1$ and $\int_{a_i}^{b_i} \dot{s}(\omega) d\omega = b_i - a_i$. Setting $s(\tau) = a + \int_a^\tau \dot{s}(\omega) d\omega$, we obtain that s is an invertible map from $[a, c]$ to $[a, \kappa + a]$.

(e) Define $t : [a, \kappa + a] \rightarrow [a, c]$ to be the inverse of $s(\cdot)$. Extend $t(\cdot)$ as an absolutely continuous map $\tilde{t}(\cdot)$ on $[a, c]$, setting $\tilde{t}(\tau) = 0$ for $\tau \in]\kappa + a, c]$. We claim that the function $\tilde{x}(\tau) = x(\tilde{t}(\tau))$ is a solution to the problem (P_F) on the interval $[a, c]$. Moreover, we claim that it satisfies $\tilde{x}(c) = x(c)$. Observe that, as in (b), we have that for $\tau \in [a, \kappa + a]$, $\tilde{t}(\tau) = t(\tau)$ is invertible, such that $\dot{t}(\tau) = \lambda_2 \mathcal{X}_C(\tau) + \sum_i (\lambda_1 \mathcal{X}_1^i(\tau) + \lambda_2 \mathcal{X}_2^i(\tau))$. Since

$$\frac{d^2}{d\tau^2} \tilde{x}(\tau) = (\dot{t}(\tau))^2 \ddot{x}(t(\tau)) + \ddot{t}(\tau) \dot{x}(t(\tau)) = \ddot{x}(t(\tau)) (\dot{t}(\tau))^2,$$

we get

$$\begin{aligned} \frac{1}{\dot{t}(\tau)} \frac{d^2 \tilde{x}(\tau)}{d\tau^2} &= \ddot{x}(t(\tau)) (\dot{t}(\tau)) = [\lambda_2 \mathcal{X}_C(t(\tau)) + \sum_i (\lambda_1 \mathcal{X}_1^i(t(\tau)) + \lambda_2 \mathcal{X}_2^i(t(\tau)))] \ddot{x}(t(\tau)) \\ &\in F(x(t(\tau)), \dot{x}(t(\tau))) = F(\tilde{x}(\tau), \frac{1}{\dot{t}(\tau)} \dot{\tilde{x}}(\tau)) \\ &\subseteq \frac{1}{\dot{t}(\tau)} F(\tilde{x}(\tau), \dot{\tilde{x}}(\tau)). \end{aligned}$$

Consequently

$$\frac{d^2}{d\tau^2} \tilde{x}(\tau) \in F(\tilde{x}(\tau), \dot{\tilde{x}}(\tau)).$$

In particular, from $t(\kappa + a) = c$ and $\tilde{t}(\tau) = 0$ for all $\tau \in]\kappa + a, c]$ we obtain

$$\tilde{t}(\tau) = \tilde{t}(\kappa + a) = t(\kappa + a), \quad \forall \tau \in]\kappa + a, c]$$

then

$$\tilde{x}(\kappa + a) = x(\tilde{t}(\kappa + a)) = x(\tilde{t}(\tau)) = \tilde{x}(\tau), \quad \forall \tau \in]\kappa + a, c]$$

so, on $] \kappa + a, c]$, \tilde{x} is constant, and since $c \in C$ we have

$$\frac{d^2}{d\tau^2} \tilde{x}(\tau) = 0 \in F(x(c), \dot{x}(c)) = F(\tilde{x}(\kappa + a), \frac{1}{\dot{t}(\kappa + a)} \dot{\tilde{x}}(\kappa + a)) \subset F(\tilde{x}(\tau), \dot{\tilde{x}}(\tau)).$$

This proves the claim.

(f) It is left to define the solution on $[c, b]$. On it, $\lambda_1 > 0$ and the construction of Step 1 and (b) can be repeated to find a solution to problem (P_F) on $[c, b]$. This completes the proof of the theorem. \blacksquare

Proof of the Theorem 3.6. In view of Theorem 3.4, and since $co(F) : E \times E \rightrightarrows E$ is a multifunction with compact values, upper semicontinuous on $E \times E$ and furthermore, for all $(x, y) \in E \times E$,

$$co(F(x, y)) \subset (p(t)\|x\| + bq(t)\|y\|)co(\overline{\mathbf{B}}_E) = (p(t)\|x\| + bq(t)\|y\|)\overline{\mathbf{B}}_E,$$

we conclude the existence of a $\mathbf{W}_E^{2,1}([a, b])$ -solution x of the problem $(P_{co(F)})$. By the almost convexity of the values of F , there exist two constants λ_1 and

λ_2 , satisfying $0 \leq \lambda_1 \leq 1 \leq \lambda_2$, such that, for almost every $t \in [a, b]$, we have

$$\lambda_1 \ddot{x}(t) \in F(x(t), \dot{x}(t)) \text{ and } \lambda_2 \ddot{x}(t) \in F(x(t), \dot{x}(t)).$$

Using Theorem 3.7, we conclude the existence of a $\mathbf{W}_E^{2,1}([a, b])$ -solution of the problem (P_F) .

This completes the proof of our main result. ■

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