



KRITIKUS PONTOK KÖVETÉSE

**IDŐBEN VÁLTOZÓ SIMA
FELÜLETEKEN ÉS FINOM DISZKRETIZÁCIÓIKON**

DOMOKOS GÁBOR, LÁNGI ZSOLT ÉS SIPOS ANDRÁS

MTA-BME MOROFDINAMIKA KUTATÓCSOPORT

SZEGEDI GEOMETRIAI NAP, 2017. OKTÓBER 6.

GEOPHYSICAL MOTIVATION: FLUVIAL ABRASION AND EQUILIBRIA

HAND EXPERIMENTS WIT PEBBLES:

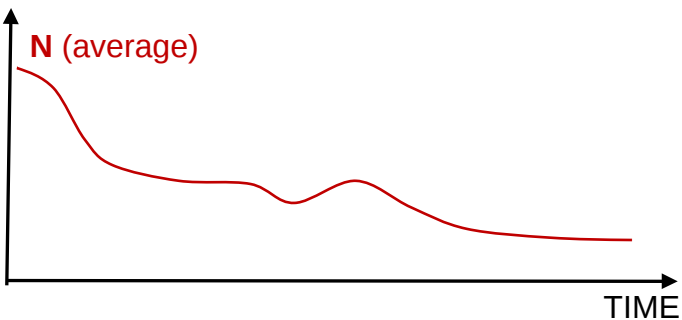


STABLE (S)



UNSTABLE (U)

FIELD OBSERVATION:

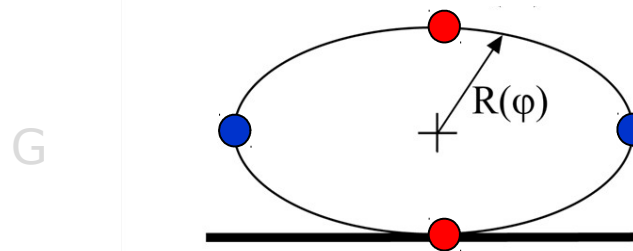


STATIC EQUILIBRIA

a) 2D: $S=U$

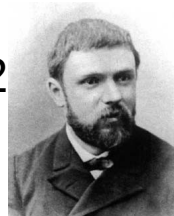
$$N = S + U$$

- STABLE (S)
- UNSTABLE (U)



b) 3D: $S+U-H=2$

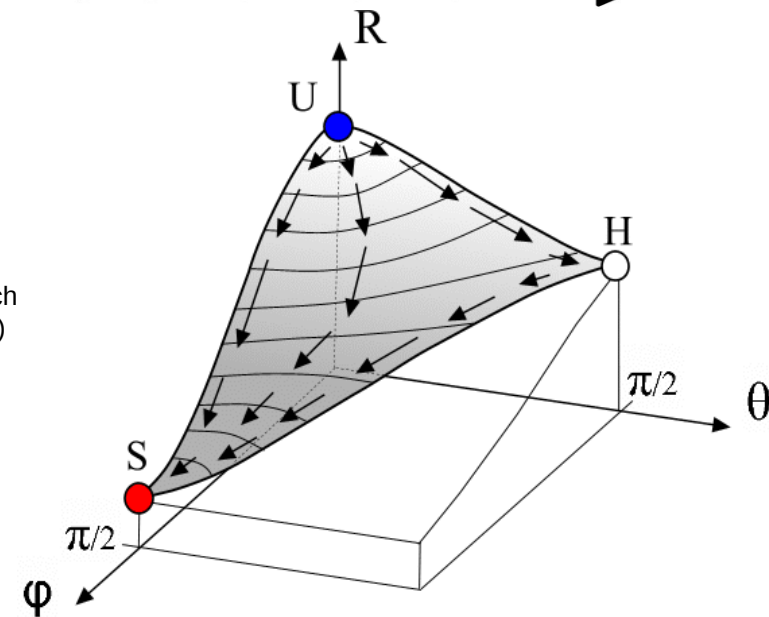
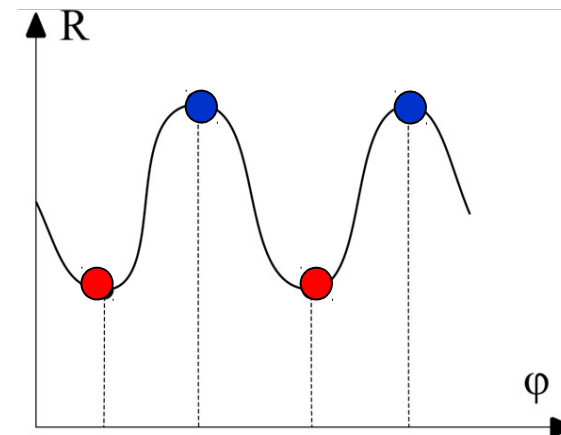
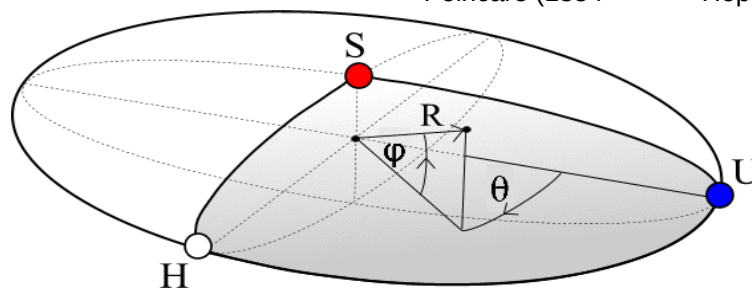
$$N = S + U + H$$



Jules Henri Poincaré (1854-1912)

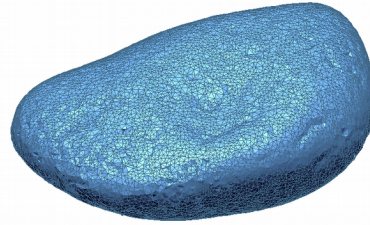


Eberhard Friedrich Hopf (1902-1983)

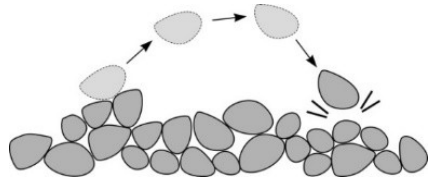


Fluvial abrasion of pebbles: intuitive

Field
observations

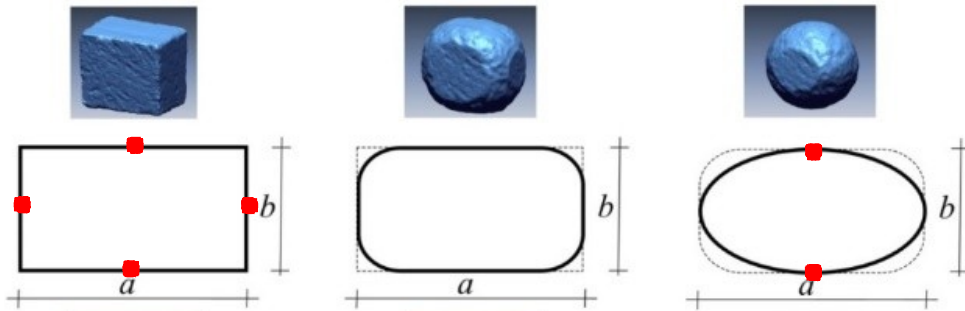


Abrasion
by many
collisions



Continuum approach
=global model)

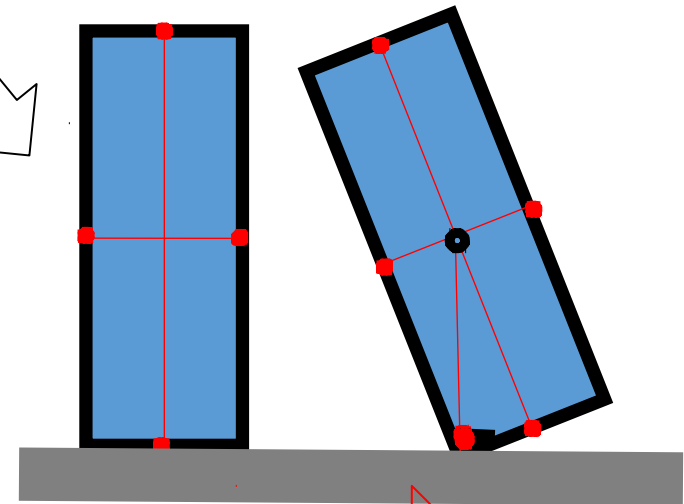
Discrete approach
=local model)



$S=$
4

EVOLUTION

$S=$
2



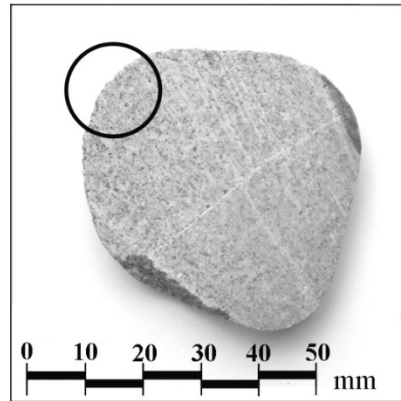
$S=$
4

EVOLUTION

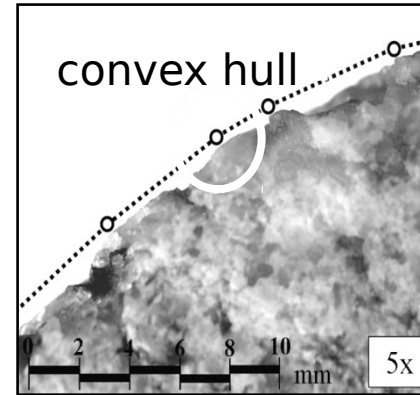
$S=$
5

GLOBAL AND LOCAL MODELS OF PEBBLE CONTOUR

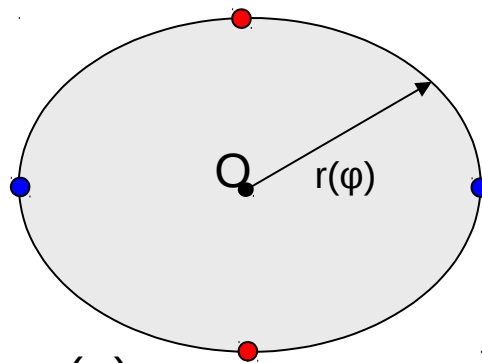
PEBBLE CONTOUR:



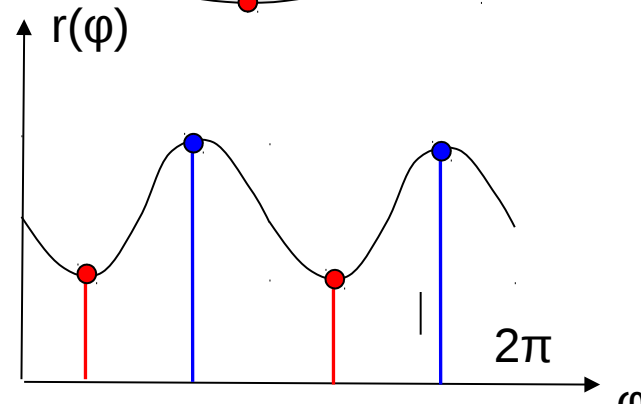
5x ZOOM



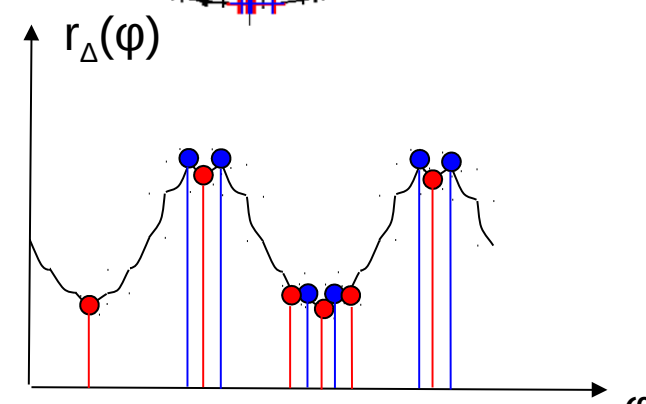
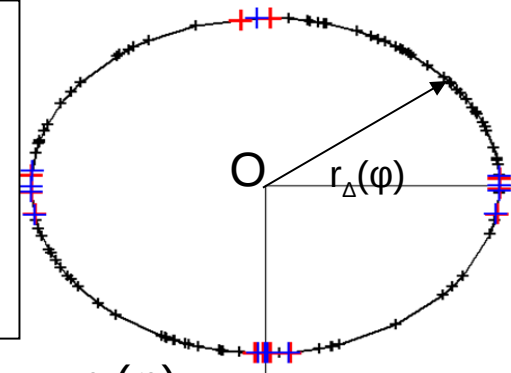
GEOMETRIC MODEL: **GLOBAL:** C^3 -smooth curve $r(\varphi)$



EQUILIBRIA	
● Stable	
$S=2$	$S=9$
● Unstable	
$U=2$	$U=9$
Total	
$N=4$	$N_{\Delta}=18$

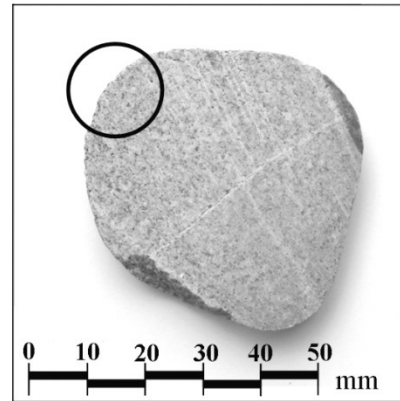


LOCAL: Polygon $r_{\Delta}(\varphi)$

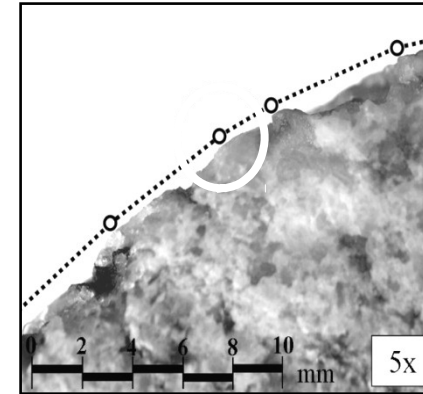


GLOBAL AND LOCAL MODELS OF PEBBLE CONTOUR

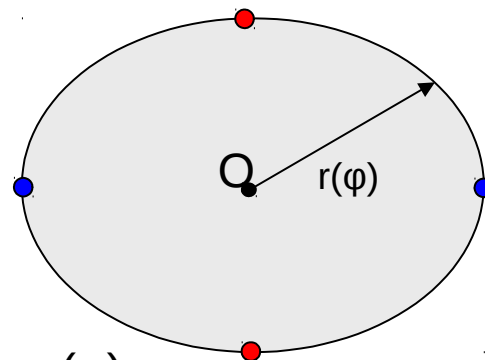
PEBBLE CONTOUR:



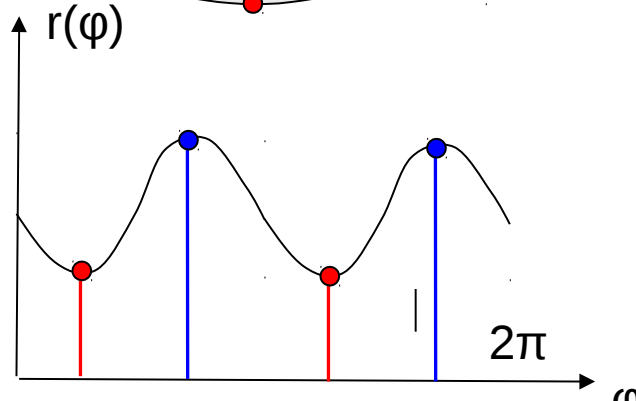
5x ZOOM



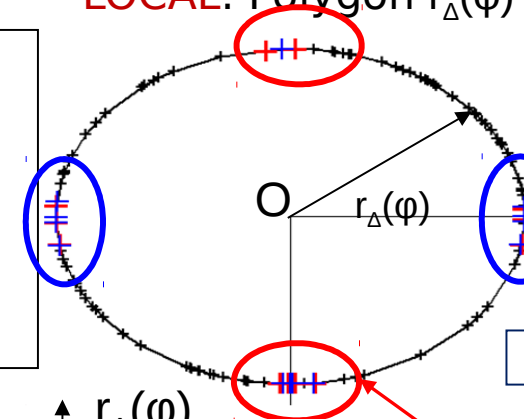
GEOMETRIC MODEL: **GLOBAL:** C^3 -smooth curve $r(\varphi)$



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LOCAL: Polygon $r_{\Delta}(\varphi)$



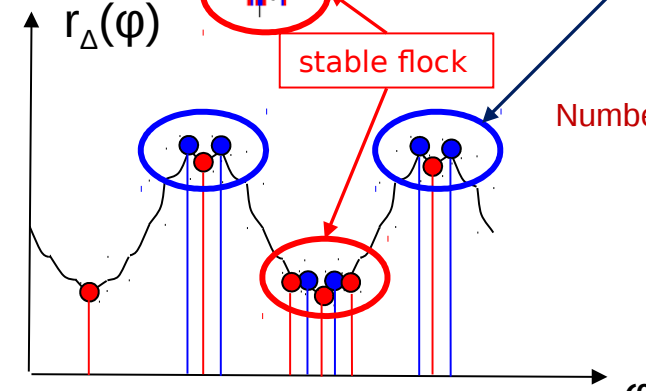
FLOCKS



unstable flock

stable flock

Number of equilibria in i^{th} flock = N_{Δ}^i



(A) „STATIC” THEORY: GENERIC FLOCKS

ASSUMPTIONS:

1. $r(\varphi)$ is C^3 -smooth
2. Discretization is uniform
3. Equilibrium is generic, i.e. $dr/d\varphi=0$, $d^2r/d\varphi^2 \neq 0$

RESULTS:

1. GENERIC FLOCK SIZE $\lim_{\Delta \rightarrow 0} (N_{\Delta}^i) = (1+|r\kappa|)/|1+r\kappa|$, where κ is the curvature (Monatshefte)
2. NO EQUILIBRIA OUTSIDE FLOCKS: $\lim_{\Delta \rightarrow 0} N_{\Delta} = \sum_i \lim_{\Delta \rightarrow 0} (N_{\Delta}^i)$ (THEOREM 1)
3. SMALL RANDOM FLUCTUATIONS OF Δ CAUSE SMALL CHANGES IN N_{Δ} (THEOREM 2)

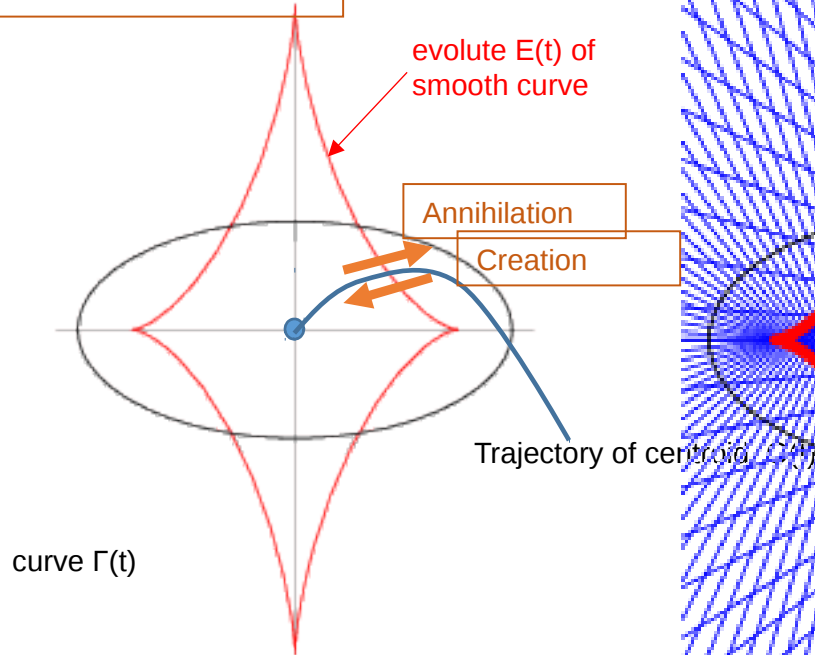
(B) „DYNAMIC” THEORY: $N(t)$, $N_{\Delta}(t)$ AND CRITICAL FLOCKS

ASSUMPTIONS:

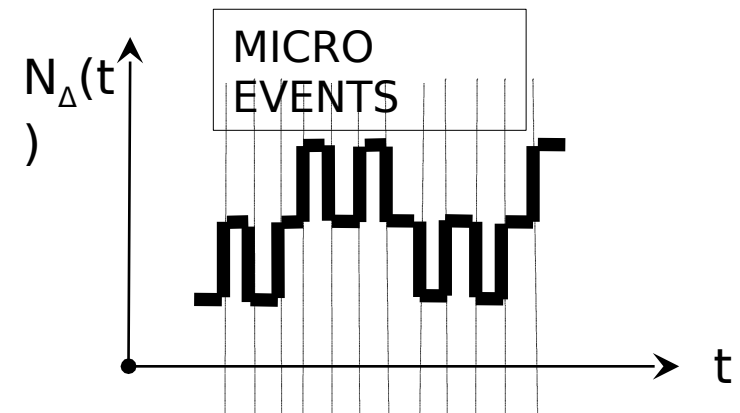
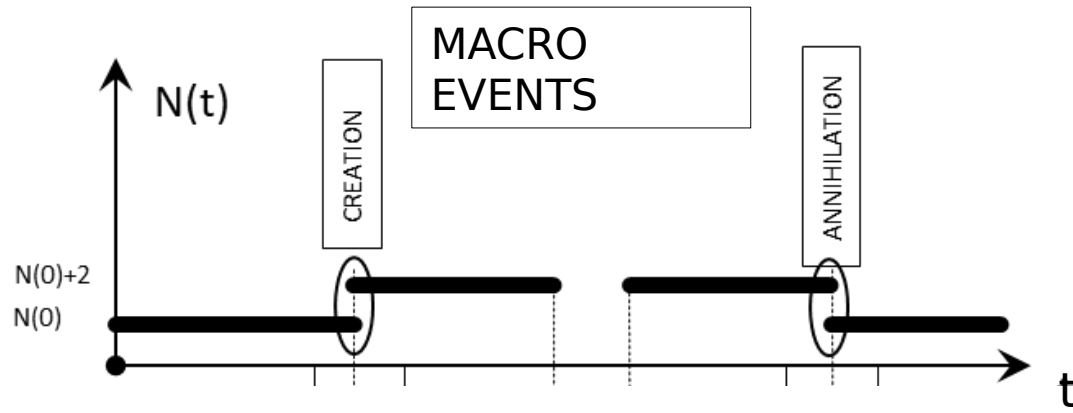
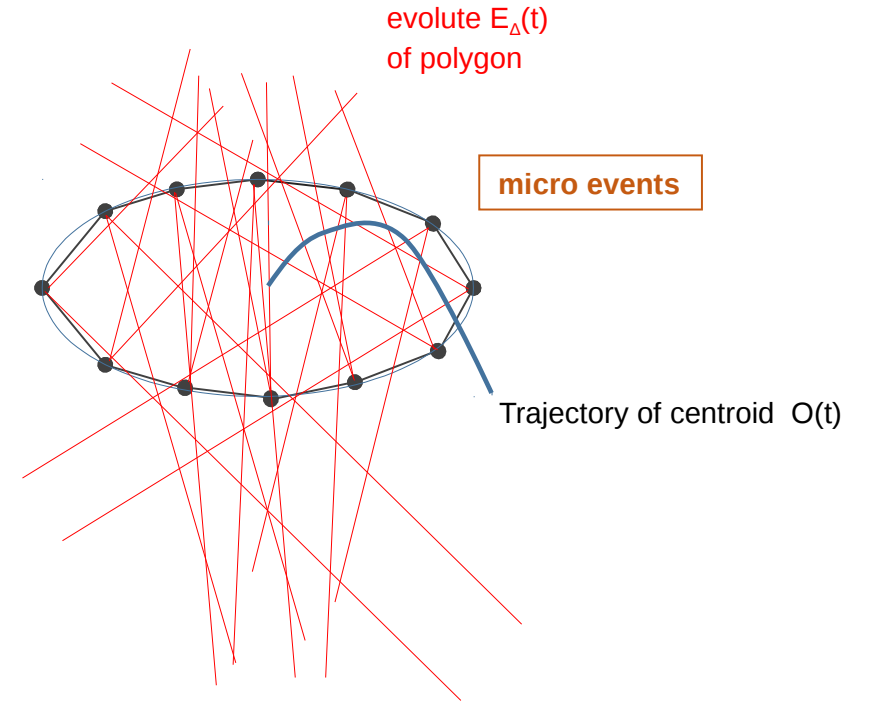
1. $r(\varphi, t)$ is C^3 -smooth
2. Discretization is uniform for all t

(B) „DYNAMIC” THEORY: GEOMETRIC INTERPRETATION AND TYPE OF EVENTS

MACRO events



MICRO events



(A) „STATIC” THEORY: GENERIC FLOCKS

ASSUMPTIONS:

1. $r(\varphi)$ is C^3 -smooth
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3. SMALL RANDOM FLUCTUATIONS OF Δ CAUSE SMALL CHANGES IN N_Δ (THEOREM 2)

(B) „DYNAMIC” THEORY: $N(t)$, $N_\Delta(t)$ AND CRITICAL FLOCKS

ASSUMPTIONS:

1. $r(\varphi, t)$ is C^3 -smooth
2. Discretization is uniform for all t

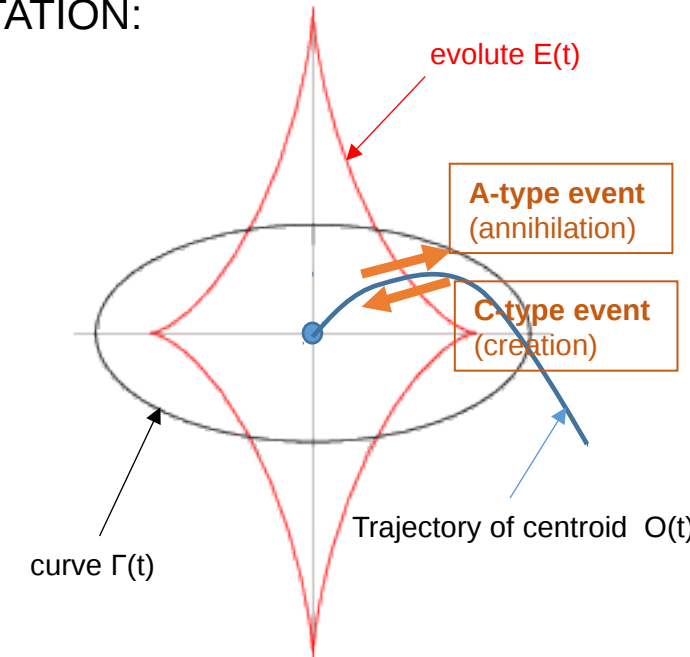
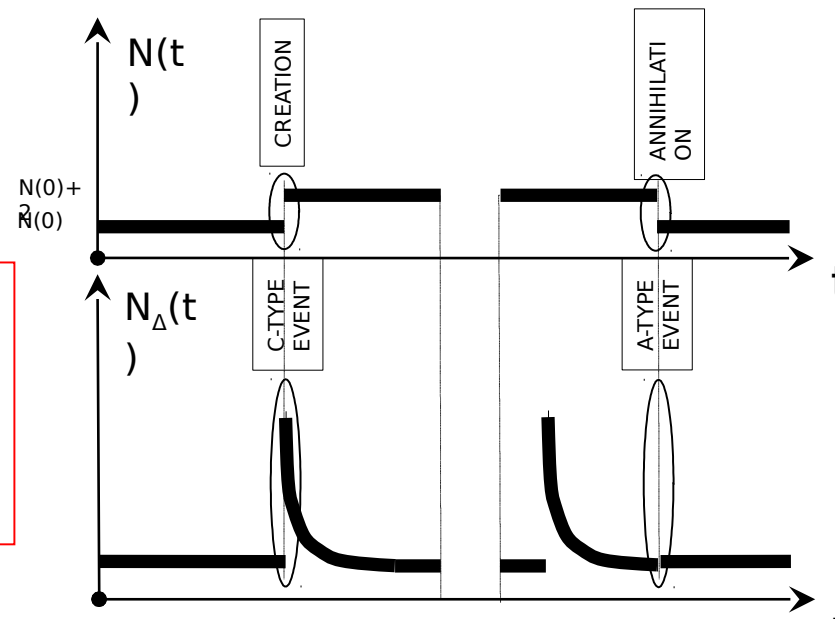
INTERPRETATION:

RESULTS:

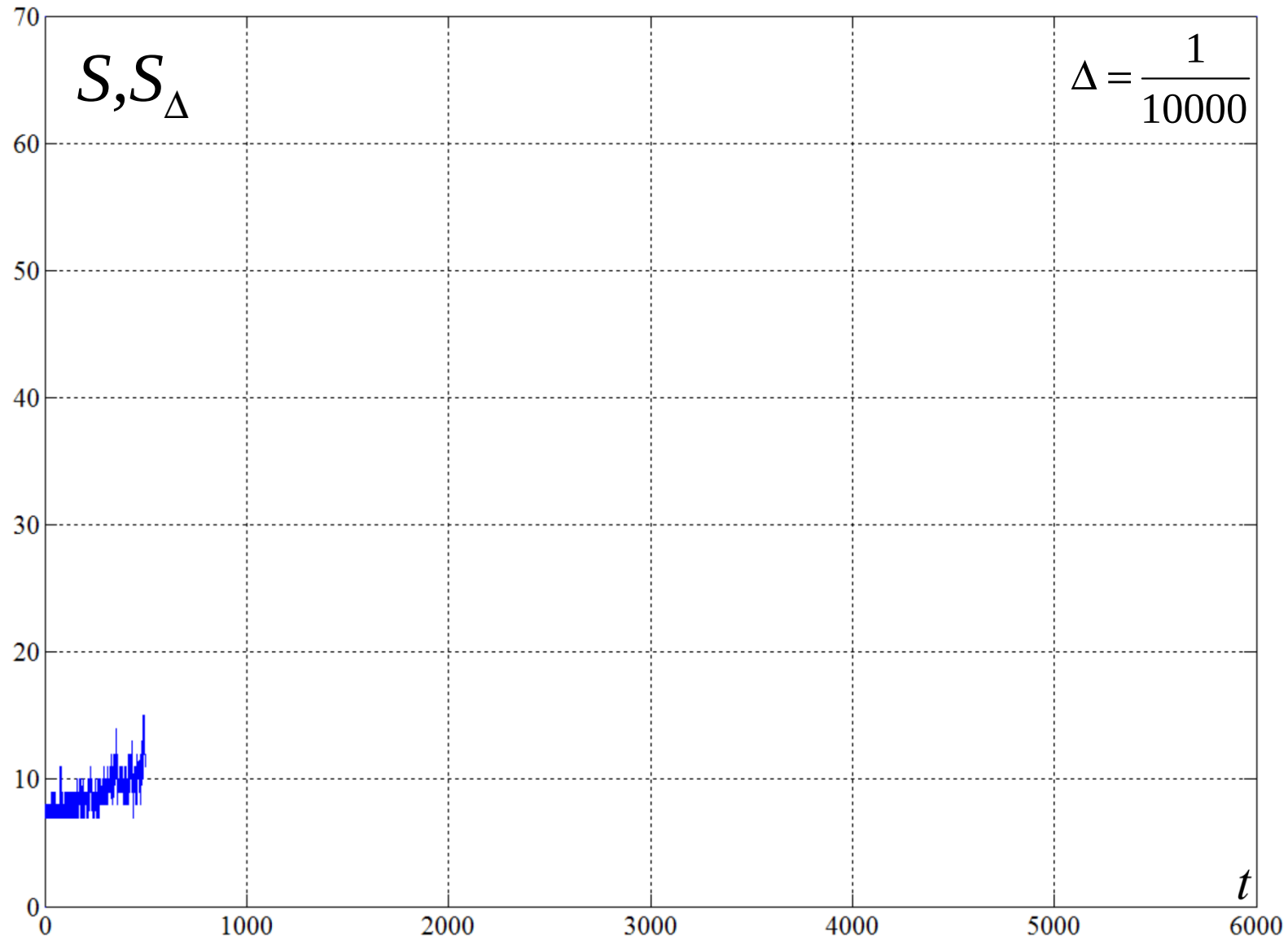
Theorem: (THEOREM 3)

$$N(t) = N(0) + 2(c - a)$$

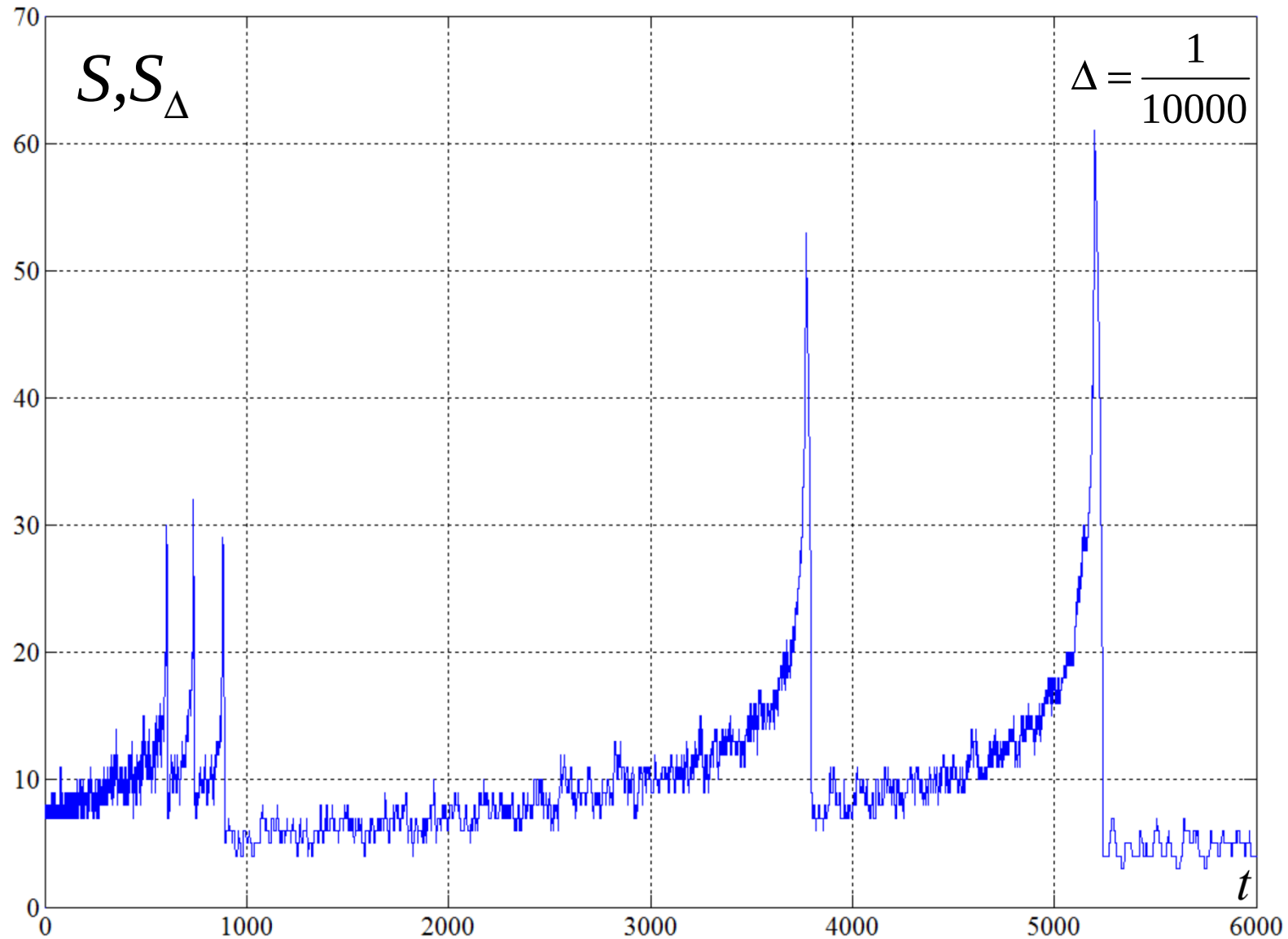
Where c and a refer to the number of C- and A-type events, respectively.



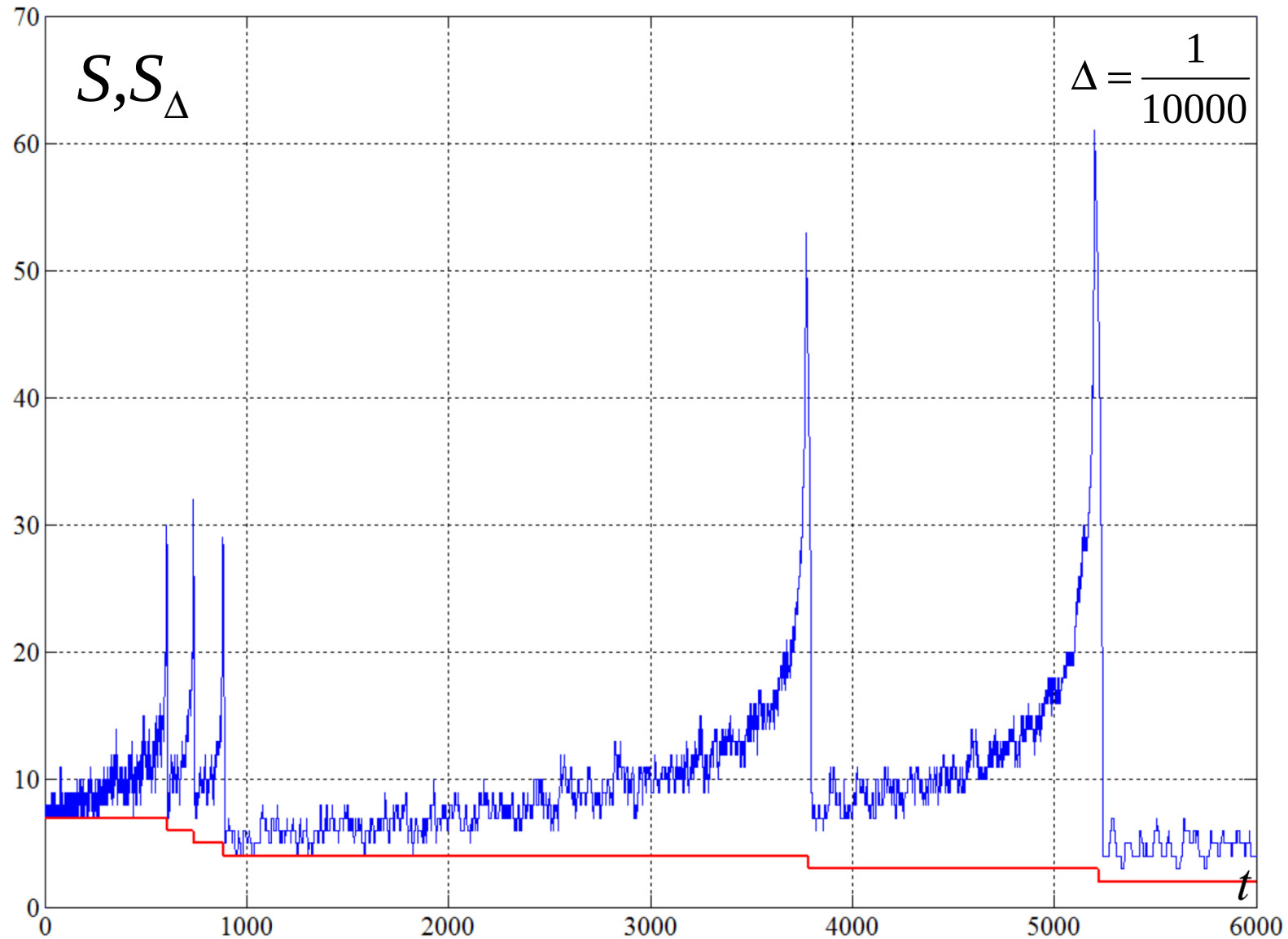
Evolution of equilibria in 2D



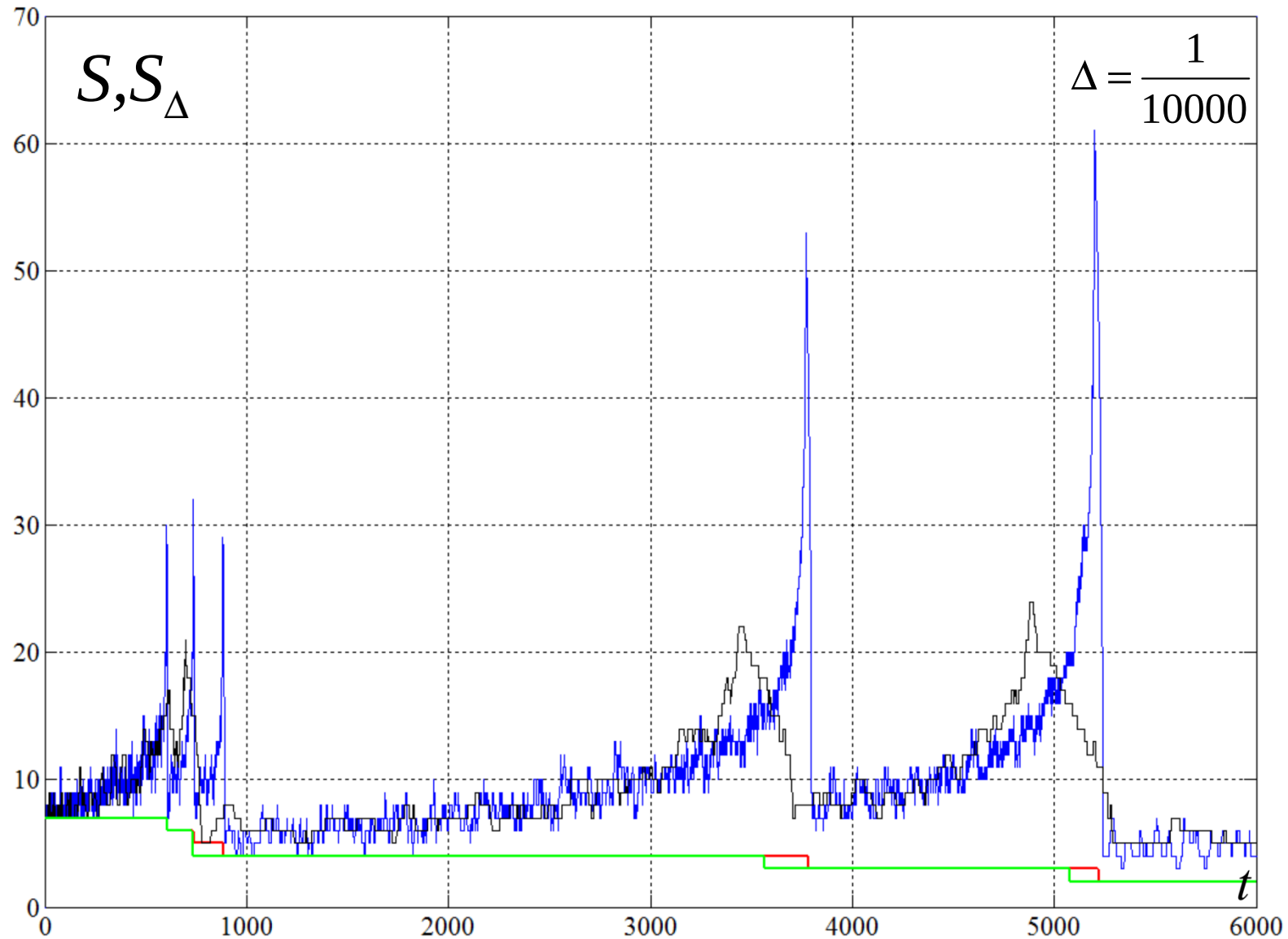
Evolution of equilibria in 2D



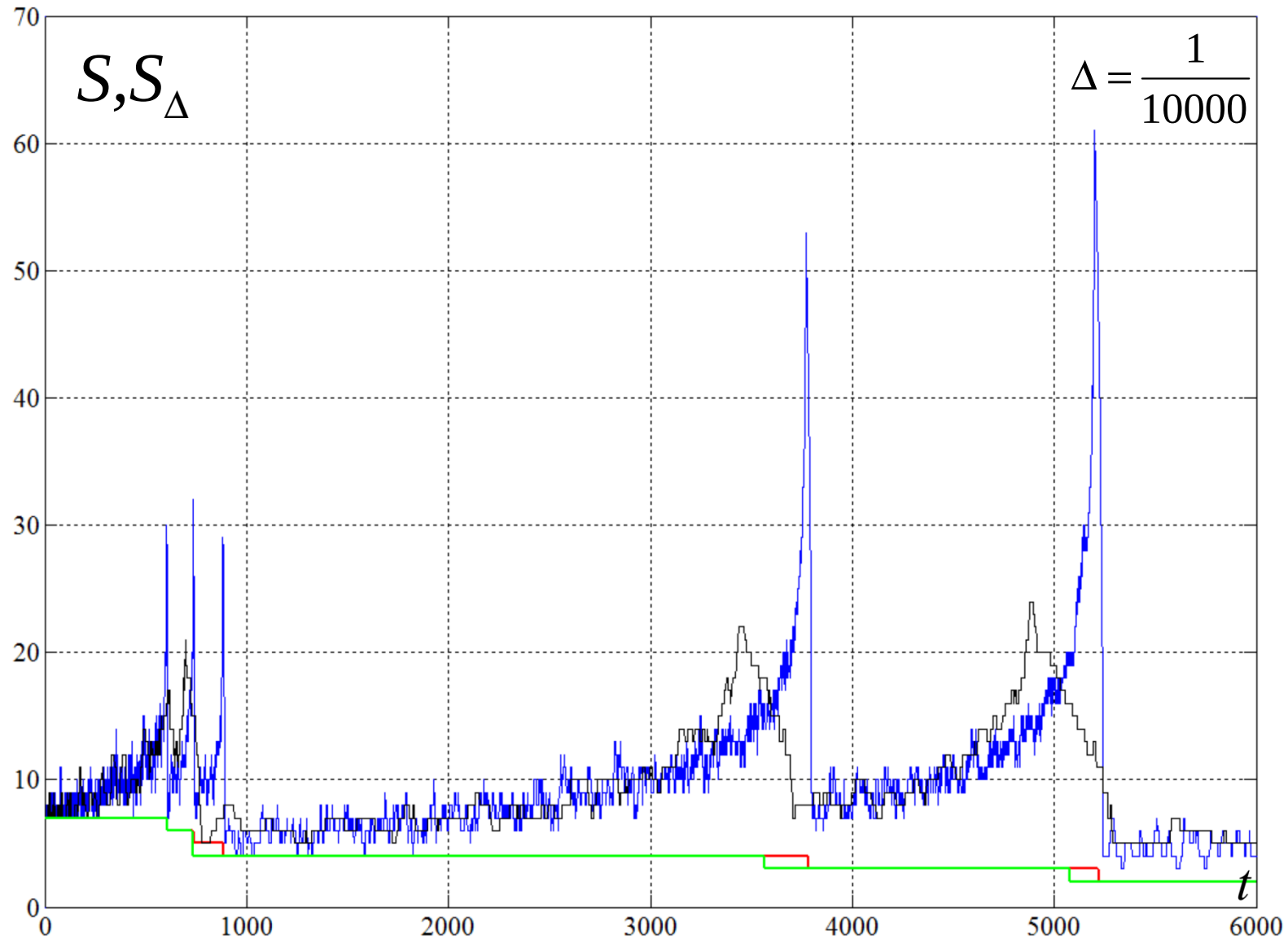
Evolution of equilibria in 2D



Evolution of equilibria in 2D



Evolution of equilibria in 2D



MORE RESULTS ON CRITICAL FLOCKS

1. **SPATIAL EVOLUTION (DIAMETER) AT FIXED, CRITICAL TIME $t=t^*$.** IF THE FIRST NON-VANISHING TERM IN THE TAYLOR SERIES OF $r(\varphi)$ IS OF ORDER k THEN THE DIAMETER D OF THE FLOCK CAN BE WRITTEN AS

$$D = \Theta(\Delta^{1/(k-1)}) \text{ (THEOREM 4)}$$

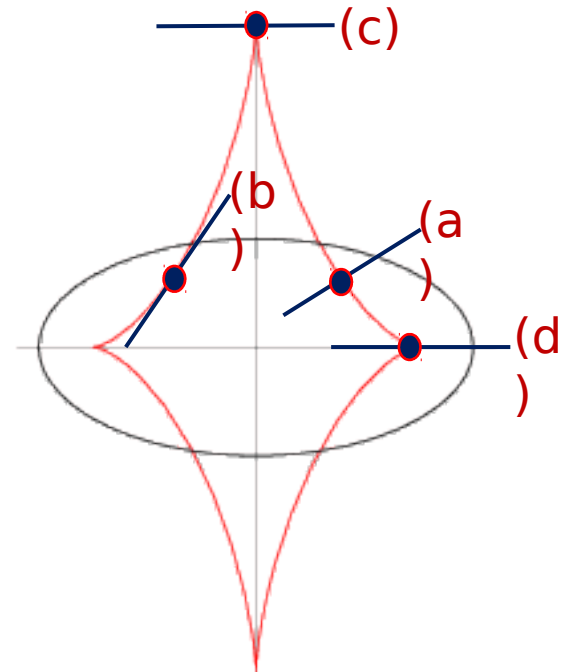
Corollaries:

- a) For generic (codimension 0) flocks we have $k=2$, thus $D = \Theta(\Delta)$
- b) At codimension 1, generic saddle-node bifurcations we have $k=3$, thus $D = \Theta(\Delta^{1/2})$
- c) At codimension 2 bifurcations (e.g. generic cusps) we have $k=4$, thus $D = \Theta(\Delta^{1/3})$

2. **TIME EVOLUTION AT FIXED, SUFFICIENTLY SMALL Δ .** IF THE INTERSECTION OF $O(t)$ AND THE EVOLUTE $E(t)$ AT $t=t^*$ IS

- a) transversal at a generic point of the evolute then, as $t \rightarrow t^*$ we have $N_\Delta(t) = \Theta(t^{-1/2})$ on one side, and $N_\Delta(t) = \text{const.}$ on the other side,
- b) tangential at a generic point of the evolute then, as $t \rightarrow t^*$ we have $N_\Delta(t) = \Theta(1/t)$,
- c) transversal at a generic cusp point of the evolute then, as $t \rightarrow t^*$ we have $N_\Delta(t) = \Theta(t^{-2/3})$,
- d) tangential at a generic cusp point of the evolute then, as $t \rightarrow t^*$ we have $N_\Delta(t) = \Theta(1/t)$.

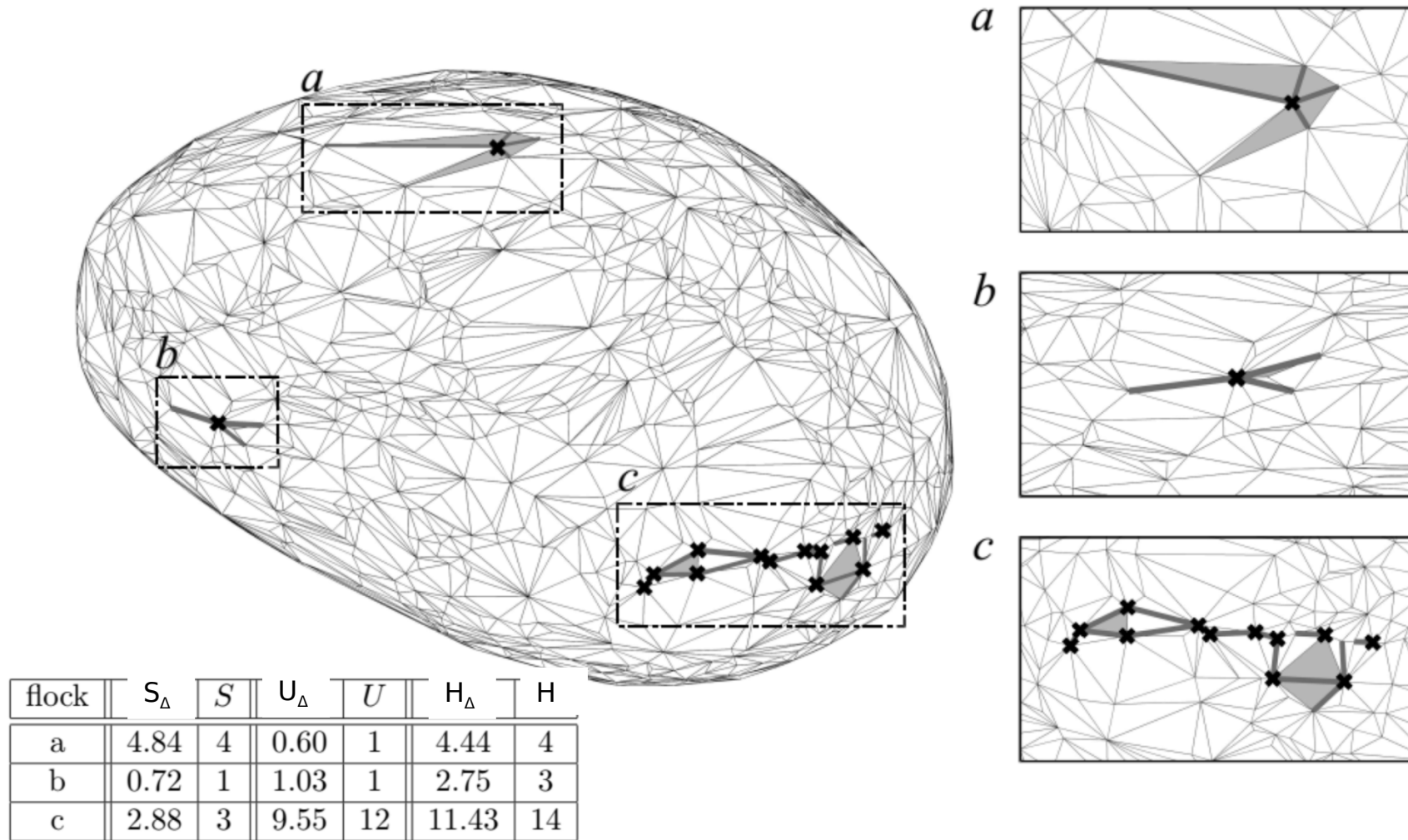
(THEOREM 5)



SOME ILLUSTRATIONS IN 3D

1. SIZE OF GENERIC FLOCKS:

$S_{\Delta}^i = d^i$, $U_{\Delta}^i = \kappa_1^i \kappa_2^i (r^i)^2 d^i$, $H_{\Delta}^i = -(\kappa_1^i + \kappa_2^i) r^i d^i$, where $1/d^i = |(1 + \kappa_1^i r^i)(1 + \kappa_2^i r^i)|$ (MONATSHEFTE)



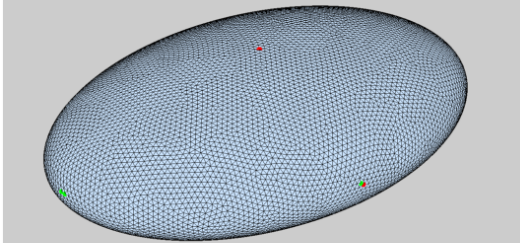
2. CRITICAL FLOCKS ON TRI-AXIAL ELLIPSOID

Here we move the reference point (=centroid) along the major axis of the ellipsoid. Observe the two peaks in the number of local equilibria as the reference point crosses the two evolutes.

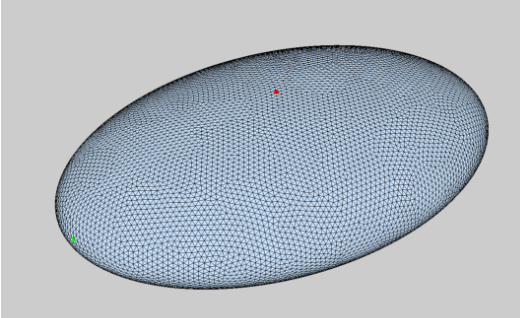
3:2:1 ELLIPSOID

$$v=[1,0,0]$$

LOCAL $S=5, U=6$

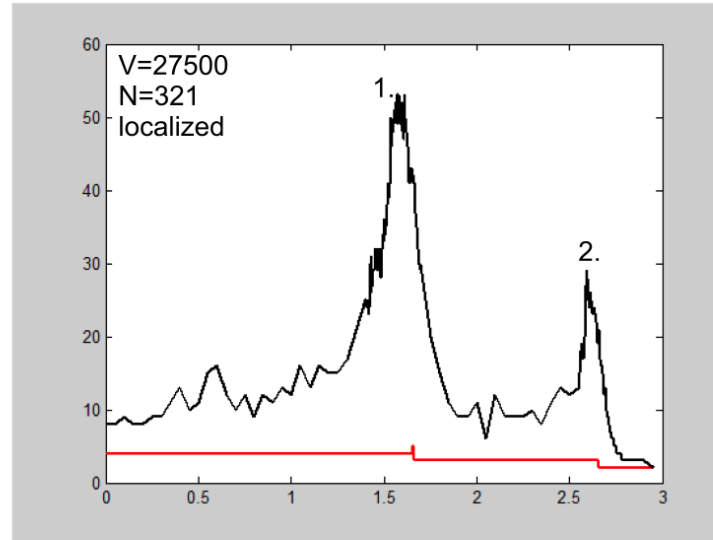


GLOBAL $S=2, U=2$

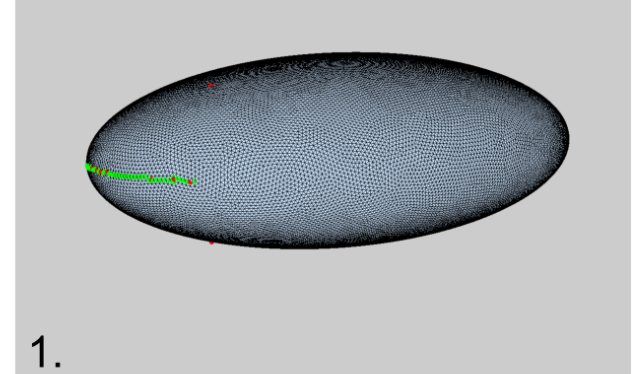


— LOCAL
STABLE
EQUILIBRIA

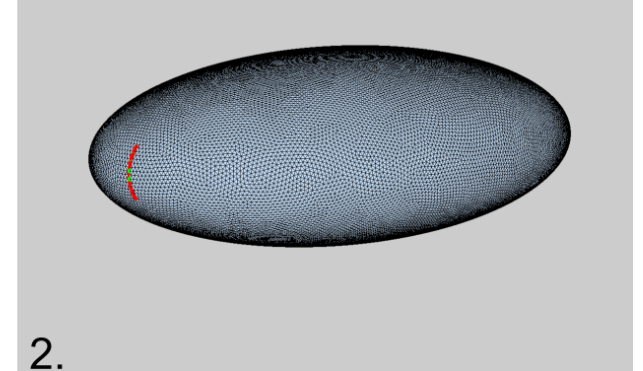
— GLOBAL
STABLE
EQUILIBRIA



LOCAL $x_s=1.57$ $S=9, U=41$



LOCAL $x_s=2.595$ $S=23, U=6$



2. DEGENERATE, UMBILIC FLOCKS ON TRI-AXIAL ELLIPSOID

Here we move the reference point (=centroid) approximately in the direction of the origin of the osculating sphere at the umbilic point of the ellipsoid..

2:1.5:1 ELLIPSOID

$$v=[1,0,a/c*[(b*b-c*c)/(a*a-b*b)]^{3/2}]$$

