

Num. Math.—7

■ gyak fel. (előző óra)

Példa $\|A\|_2$ definíció alapján közelítve, ill mint felt. optimalizálási probléma megoldása

$$A = (\{ \{12, -2, 1\}, \{-2, 15, 3\}, \{1, -2, 10\} \});$$

Táblázatot készítünk sok véletlen vektorokból és erre képezzük a maximumot! Ez jól közelíti a def-ban szereplő sup értéket.

$$T = \text{Table}[\text{Table}[\text{Random}[\text{Real}, \{-1, 1\}], \{3\}], \{10^5\}];$$

$$T[[1]]$$

$$\{-0.0514173, -0.844396, 0.792783\}$$

$$\text{Max}[\text{Map}[\text{Norm}[A.\#] / \text{Norm}[\#] \&, T]]$$

$$16.1931$$

$$N[\text{Norm}[A]]$$

$$16.1931$$

Feltételes szélsőértékprobléma megoldásaként a norma.

$$\text{NMaximize}[\{\text{Norm}[A.\{x1, x2, x3\}], x1^2 + x2^2 + x3^2 == 1\}, \{x1, x2, x3\}]$$

$$\{16.1931, \{x1 \rightarrow -0.43126, x2 \rightarrow 0.897697, x3 \rightarrow 0.0903124\}\}$$

$$\text{Norm}[A]$$

$$\sqrt{\text{Root}[-3294225 + 72816 \#1 - 492 \#1^2 + \#1^3 \&, 3]}$$

$$\text{Maximize}[\{\text{Norm}[A.\{x1, x2, x3\}], x1^2 + x2^2 + x3^2 == 1\}, \{x1, x2, x3\}]$$

$$\left\{ \sqrt{-\text{Root}[3294225 + 72816 \#1 + 492 \#1^2 + \#1^3 \&, 1]}, \right. \\ \left. \left\{ \begin{aligned} x1 &\rightarrow \text{Root}[-3459321856 + 37626759296 \#1^2 - 125676752925 \#1^4 + 125676752925 \#1^6 \&, 3], \\ x2 &\rightarrow \text{Root}[-939299904 + 20827845521 \#1^2 - 125676752925 \#1^4 + 125676752925 \#1^6 \&, 6], \\ x3 &\rightarrow \text{Root}[-9486400 + 1203778745 \#1^2 - 5027070117 \#1^4 + 5027070117 \#1^6 \&, 4] \end{aligned} \right\} \right\}$$

GSexplicit (n=3) [$x_j = x_j^{(m-1)}$, $y_j = x_j^{(m)}$ átnevezéssel]

$$-\text{DiagonalMatrix}[1/\{a11, a22, a33\}].(\{ \{0, a12, a13\}, \{0, 0, a23\}, \{0, 0, 0\} \}.\{y1, y2, y3\} + \\ \{ \{0, 0, 0\}, \{a21, 0, 0\}, \{a31, a32, 0\} \}.\{x1, x2, x3\} - \{a14, a24, a34\})$$

$$\left\{ -\frac{-a14 + a12 y2 + a13 y3}{a11}, -\frac{-a24 + a21 x1 + a23 y3}{a22}, -\frac{-a34 + a31 x1 + a32 x2}{a33} \right\}$$

Jacobi explicit

% /. {y1 -> x1, y2 -> x2, y3 -> x3}

$$\left\{ -\frac{-a14 + a12 x2 + a13 x3}{a11}, -\frac{-a24 + a21 x1 + a23 x3}{a22}, -\frac{-a34 + a31 x1 + a32 x2}{a33} \right\}$$

$$A = \begin{pmatrix} 1 & -2 + i & i \\ -2 - i & 19 & -3 \\ -i & -3 & 3 \end{pmatrix};$$

Oljuk meg $Ax=e1$ GS iterációval (nem diag dom!)

```
PartJG [ AV_ ] := { UpperTriangularize [ AV, 1 ],
  LowerTriangularize [ AV, -1 ], DiagonalMatrix [ Table [ AV [ [ j, j ] ], { j, Length [ AV ] } ] ] }
```

```
Map [ MatrixForm, PartJG [ A ] ]
```

$$\left\{ \begin{pmatrix} 0 & -2 + i & i \\ 0 & 0 & -3 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ -2 - i & 0 & 0 \\ -i & -3 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 19 & 0 \\ 0 & 0 & 3 \end{pmatrix} \right\}$$

```
PA = PartJG [ A ]
```

```
{ { { 0, -2 + i, i }, { 0, 0, -3 }, { 0, 0, 0 } },
  { { 0, 0, 0 }, { -2 - i, 0, 0 }, { -i, -3, 0 } }, { { 1, 0, 0 }, { 0, 19, 0 }, { 0, 0, 3 } } }
```

```
b = Inverse [ PA [ [ 3 ] ] + PA [ [ 2 ] ] ] . { 1, 0, 0 }
```

$$\left\{ 1, \frac{2}{19} + \frac{i}{19}, \frac{2}{19} + \frac{22i}{57} \right\}$$

```
B = -Inverse [ PA [ [ 3 ] ] + PA [ [ 2 ] ] ] . ( PA [ [ 1 ] ] )
```

$$\left\{ \{ 0, 2 - i, -i \}, \left\{ 0, \frac{5}{19}, \frac{4}{19} - \frac{2i}{19} \right\}, \left\{ 0, \frac{34}{57} + \frac{2i}{3}, \frac{31}{57} - \frac{2i}{19} \right\} \right\}$$

```
Eigenvalues [ B ] // Abs // N
```

```
{ 0.8697, 0.13532, 0. }
```

b

$$\left\{ 1, \frac{2}{19} + \frac{i}{19}, \frac{2}{19} + \frac{22i}{57} \right\}$$

```
NestList [B.# + b &, b, 50] // N
```

```
{ {1., 0.105263 + 0.0526316 i, 0.105263 + 0.385965 i},
  {1.64912 - 0.105263 i, 0.195753 + 0.136657 i, 0.23084 + 0.686365 i},
  {2.21453 - 0.153278 i, 0.277624 + 0.208793 i, 0.328717 + 0.946969 i},
  {2.71101 - 0.188754 i, 0.347206 + 0.272337 i, 0.410125 + 1.17601 i},
  {3.14276 - 0.212657 i, 0.406766 + 0.328709 i, 0.477651 + 1.37629 i},
  {3.51853 - 0.226999 i, 0.457738 + 0.378601 i, 0.533404 + 1.55145 i},
  {3.84552 - 0.23394 i, 0.501326 + 0.422736 i, 0.579306 + 1.70458 i},
  {4.12996 - 0.235161 i, 0.538579 + 0.461756 i, 0.616966 + 1.83841 i},
  {4.37733 - 0.232033 i, 0.570399 + 0.496237 i, 0.647744 + 1.95535 i},
  {4.59238 - 0.22567 i, 0.597561 + 0.526688 i, 0.672784 + 2.05748 i},
  {4.77929 - 0.216969 i, 0.620732 + 0.553568 i, 0.693055 + 2.14667 i},
  {4.9417 - 0.20665 i, 0.640485 + 0.577284 i, 0.709368 + 2.22452 i},
  {5.08277 - 0.195285 i, 0.657312 + 0.598197 i, 0.722407 + 2.29245 i},
  {5.20528 - 0.183324 i, 0.671637 + 0.616631 i, 0.732745 + 2.35172 i},
  {5.31163 - 0.171119 i, 0.683822 + 0.632871 i, 0.740861 + 2.40341 i},
  {5.40393 - 0.15894 i, 0.694178 + 0.647173 i, 0.747158 + 2.44848 i},
  {5.48401 - 0.14699 i, 0.702973 + 0.659762 i, 0.751969 + 2.48777 i},
  {5.55347 - 0.135418 i, 0.710436 + 0.670839 i, 0.755575 + 2.522 i},
  {5.61371 - 0.124333 i, 0.716762 + 0.680581 i, 0.758206 + 2.55182 i},
  {5.66592 - 0.113806 i, 0.722119 + 0.689145 i, 0.760055 + 2.57778 i},
  {5.71117 - 0.103884 i, 0.726652 + 0.696671 i, 0.76128 + 2.60039 i},
  {5.75037 - 0.0945888 i, 0.730482 + 0.703283 i, 0.762012 + 2.62007 i},
  {5.78432 - 0.0859288 i, 0.733716 + 0.709088 i, 0.762359 + 2.6372 i},
  {5.81372 - 0.0778982 i, 0.736442 + 0.714184 i, 0.762409 + 2.65209 i},
  {5.83916 - 0.0704821 i, 0.738738 + 0.718656 i, 0.762232 + 2.66504 i},
  {5.86117 - 0.0636584 i, 0.740669 + 0.722578 i, 0.761888 + 2.6763 i},
  {5.88022 - 0.0574005 i, 0.74229 + 0.726017 i, 0.761423 + 2.68609 i},
  {5.89669 - 0.0516783 i, 0.743648 + 0.729032 i, 0.760875 + 2.69459 i},
  {5.91092 - 0.0464598 i, 0.744786 + 0.731673 i, 0.760272 + 2.70198 i},
  {5.92322 - 0.0417123 i, 0.745736 + 0.733986 i, 0.75964 + 2.70839 i},
  {5.93385 - 0.0374028 i, 0.746528 + 0.736012 i, 0.758995 + 2.71396 i},
  {5.94303 - 0.0334988 i, 0.747187 + 0.737785 i, 0.758353 + 2.7188 i},
  {5.95095 - 0.0299688 i, 0.747733 + 0.739337 i, 0.757723 + 2.72299 i},
  {5.95779 - 0.0267825 i, 0.748186 + 0.740694 i, 0.757114 + 2.72663 i},
  {5.96369 - 0.0239111 i, 0.74856 + 0.741881 i, 0.75653 + 2.72978 i},
  {5.96878 - 0.0213272 i, 0.748867 + 0.742919 i, 0.755976 + 2.73251 i},
  {5.97317 - 0.0190055 i, 0.749119 + 0.743826 i, 0.755454 + 2.73488 i},
  {5.97695 - 0.0169219 i, 0.749325 + 0.744618 i, 0.754966 + 2.73693 i},
  {5.9802 - 0.0150545 i, 0.749492 + 0.74531 i, 0.75451 + 2.73871 i},
  {5.98301 - 0.0133826 i, 0.749628 + 0.745914 i, 0.754088 + 2.74025 i},
  {5.98542 - 0.0118875 i, 0.749736 + 0.746442 i, 0.753699 + 2.74158 i},
  {5.9875 - 0.0105518 i, 0.749823 + 0.746902 i, 0.75334 + 2.74273 i},
  {5.98928 - 0.00935978 i, 0.749892 + 0.747303 i, 0.753012 + 2.74373 i},
  {5.99082 - 0.00829689 i, 0.749946 + 0.747653 i, 0.752711 + 2.74459 i},
  {5.99214 - 0.00735001 i, 0.749987 + 0.747959 i, 0.752437 + 2.74534 i},
  {5.99327 - 0.00650719 i, 0.750019 + 0.748225 i, 0.752188 + 2.74598 i},
  {5.99424 - 0.0057576 i, 0.750043 + 0.748457 i, 0.751962 + 2.74654 i},
  {5.99508 - 0.00509144 i, 0.75006 + 0.748659 i, 0.751757 + 2.74702 i},
  {5.9958 - 0.00449985 i, 0.750072 + 0.748834 i, 0.751572 + 2.74743 i},
  {5.99641 - 0.00397487 i, 0.75008 + 0.748987 i, 0.751405 + 2.74779 i},
  {5.99694 - 0.0035093 i, 0.750084 + 0.749121 i, 0.751254 + 2.7481 i}}
```

```
LinearSolve [A, {1, 0, 0}]
```

```
{6,  $\frac{3}{4} + \frac{3i}{4}$ ,  $\frac{3}{4} + \frac{11i}{4}$ }
```

Valós gyökök közelítése (Newton, Newton-Raphson)

■ 1

Legyen f kétszer diff. $\exists x \in [a, b]: f[x]=0$? pl folytonossági megfontolások

Alapötlet: legyen x_0 egy jó közelítése a gyöknek és használjuk a deriváltat egy jobb közelítés megadására

$$f'[x_n] = (0 - f[x_n]) / (x_{n+1} - x_n) \implies x_{n+1} = x_n + \frac{-f[x_n]}{f'[x_n]}$$

Példa. $f[x] = \cos[x] - x^3$

```
f[x_] := Cos[x] - x^3;
```

```
NSolve[f[x] == 0, x]
```

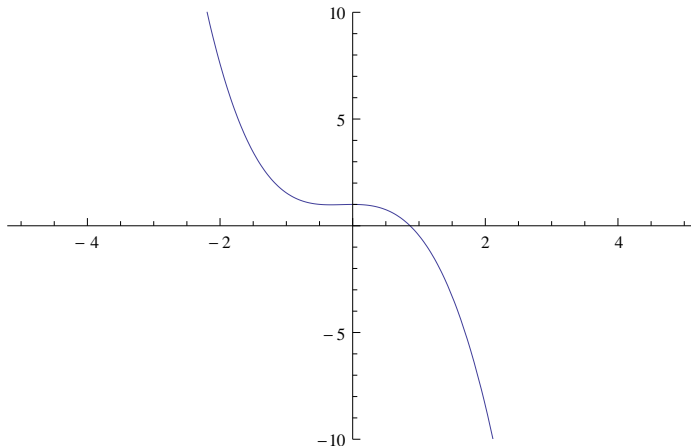
NSolve::nsmet: This system cannot be solved with the methods available to NSolve. >>

```
NSolve[-x^3 + Cos[x] == 0, x]
```

```
NSolve[x^2 - 5x + 6 == 0, x]
```

```
{{x -> 2.}, {x -> 3.}}
```

```
Plot[f[x], {x, -5, 5}, PlotRange -> {-10, 10}]
```



```
FindRoot[f[x], {x, 1}]
```

```
{x -> 0.865474}
```

```
Options[FindRoot]
```

```
{AccuracyGoal -> Automatic, Compiled -> Automatic, DampingFactor -> 1, Evaluated -> True,
 EvaluationMonitor -> None, Jacobian -> Automatic, MaxIterations -> 100, Method -> Automatic,
 PrecisionGoal -> Automatic, StepMonitor -> None, WorkingPrecision -> MachinePrecision}
```

Most mi is megoldjuk iterációval! → Nest, NestList, NestWhile

```
Nest[F, x, 3]
```

```
F[F[F[x]]]
```

```
NestList[F, x, 3]
```

```
{x, F[x], F[F[x]], F[F[F[x]]]}
```


Négyzetgyökvonás

`Nest [NewtonRaphsonStep, 2, 4]`

2.23607

$N[\sqrt{5}]$

2.23607

Most osztályozzuk a valós egyenes pontjait:

A osztály) Konvergencia van és $\lim = \text{Sqrt}[5]$,

B osztály) Konvergencia van és $\lim = -\text{Sqrt}[5]$,

C osztály) Nincs konvergencia vagy az iterációssorozat nem értelmezhető

x0

x0

```
TableForm [ Table [ Nest [ NewtonRaphsonStep, x0, 10 ], { x0, -5, 5, 1 / 4 } ] ]
```

```
Power::infy : Infinite expression  $\frac{1}{0}$  encountered. >>
```

```
Infinity::indet : Indeterminate expression 0 ComplexInfinity encountered. >>
```

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■ Projektmunka: NR Vizualizáció

Egy lépés viz.

```
Clear [ f, g ]
```

```
f [ x_ ] := x ^ 2 - 5;
```

```
g [ x_ ] := x ^ 3 - 2;
```

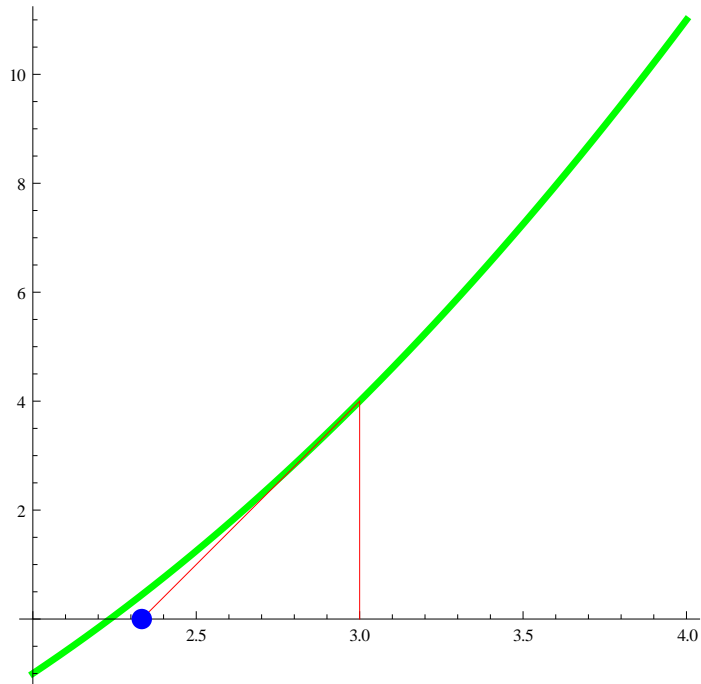


```

NewtonRaphsonVis[f_, x0_] := Module[{x},
  Plot[f[x], {x, x0 - 1, x0 + 1}, PlotStyle -> {Thickness[.01], RGBColor[0, 1, 0]}, AspectRatio -> 1,
  Epilog -> {RGBColor[1, 0, 0], Line[{{x0, f[x0]}, {-f[x0] / (D[f[x], x] /. x -> x0) + x0, 0}],
  Line[{{x0, 0}, {x0, f[x0]}]}, RGBColor[0, 0, 1], PointSize[.03],
  Point[{-f[x0] / (D[f[x], x] /. x -> x0) + x0, 0}]]]

```

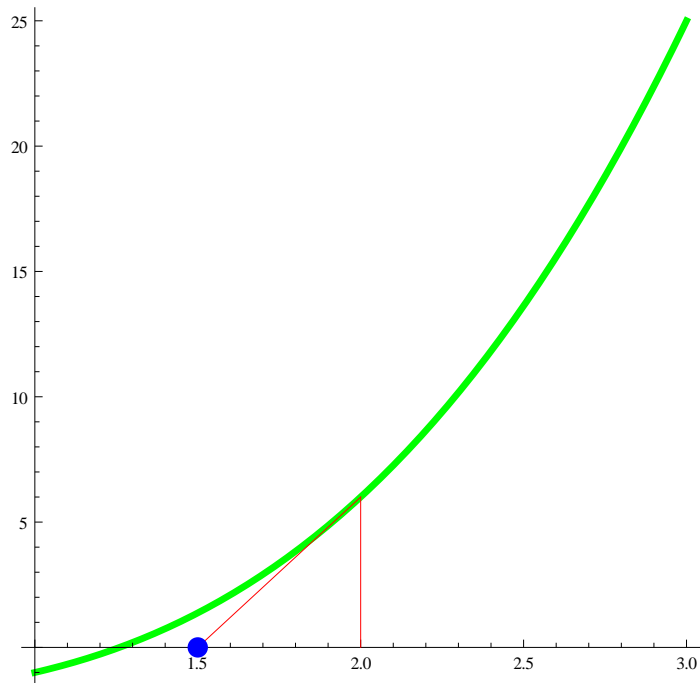
```
NewtonRaphsonVis[f, 3]
```



```
Nest[NewtonRaphsonStep, 3, 1]
```

```
2.33333
```

NewtonRaphsonVis [g, 2]



Memo: f globális NR-re nézve!

$f[x_] = g[x];$

Nest [NewtonRaphsonStep, 2, 1]

2.25

■ Kitekintés: Többdimenziós NR

$f[x,y]=0$

$g[x,y]=0$

Vektoriteráció

$F[\{x_, y_\}] := \{x + 1, 2 y\}$

NestList [F, {0, 1}, 5] // TableForm

0	1
1	2
2	4
3	8
4	16
5	32

$f1[x_, y_] = x^2 + y^2 - 5;$

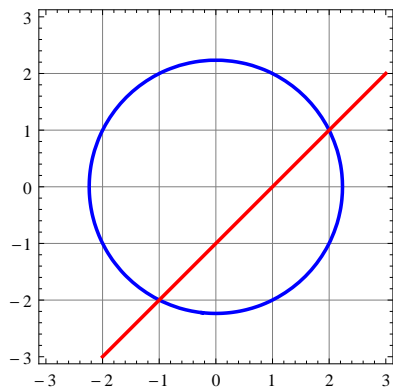
$f2[x_, y_] = x - y - 1;$

Solve [{f1[x, y] == 0, f2[x, y] == 0}, {x, y}]

{{x → -1, y → -2}, {x → 2, y → 1}}

Meg tudjuk-e közelíteni hasonlóan a megoldásokat?

```
ContourPlot[{f1[x, y] == 0, f2[x, y] == 0}, {x, -3, 3}, {y, -3, 3}, ImageSize -> {200, 200},
  GridLines -> Automatic, ContourStyle -> {{Blue, Thickness[.01]}, {Red, Thickness[.01]}}
```



Általánosítás 2 dimenzióra a Jacobi mátrix segítségével:

$$J[x_, y_] = \begin{pmatrix} D[f1[x, y], x] & D[f1[x, y], y] \\ D[f2[x, y], x] & D[f2[x, y], y] \end{pmatrix}$$

```
{{2 x, 2 y}, {1, -1}}
```

```
J[1/2, 1/2]
```

```
{{1, 1}, {1, -1}}
```

```
NewtonRaphsonStep2D[{x_, y_}] := N[{x, y} - Inverse[J[x, y]].{f1[x, y], f2[x, y]}];
```

```
TableForm[NestList[NewtonRaphsonStep2D, {1/2, 1/2}, 5]]
```

$\frac{1}{2}$	$\frac{1}{2}$
3.25	2.25
2.28409	1.28409
2.02262	1.02262
2.00017	1.00017
2.	1.

```
TableForm[NestList[NewtonRaphsonStep2D, {-3, -1/2}, 5]]
```

-3	$-\frac{1}{2}$
-1.89286	-2.89286
-1.16658	-2.16658
-1.00832	-2.00832
-1.00002	-2.00002
-1.	-2.