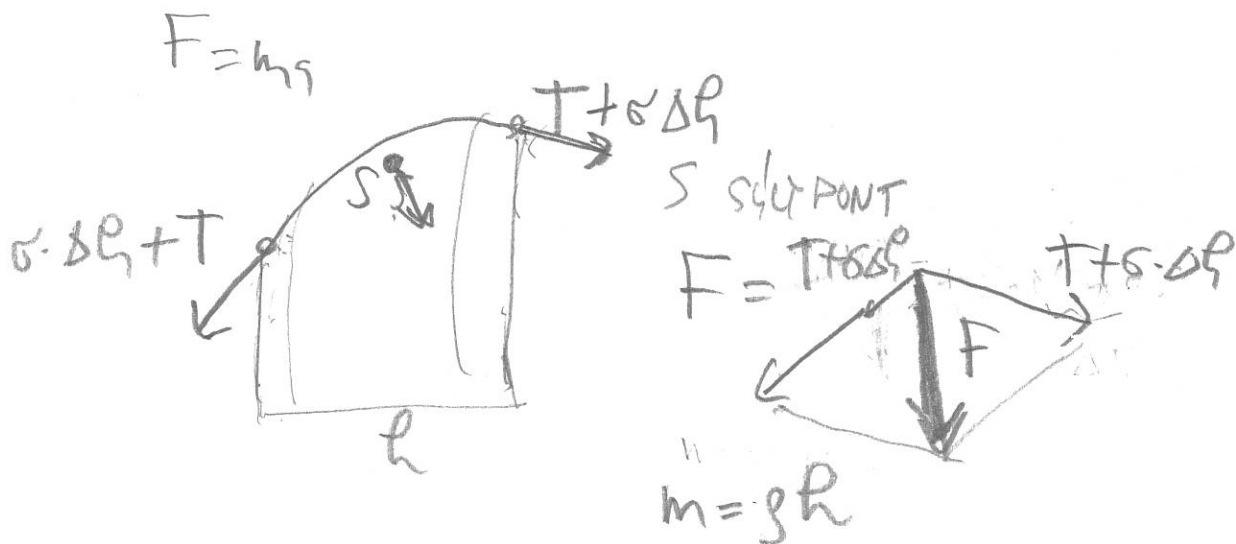
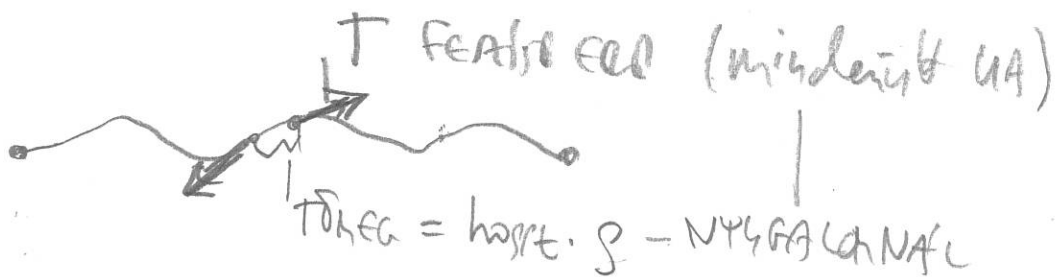
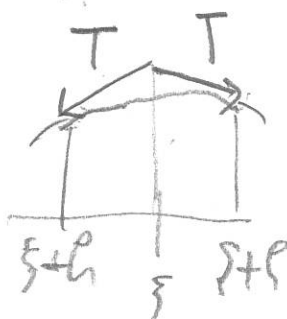
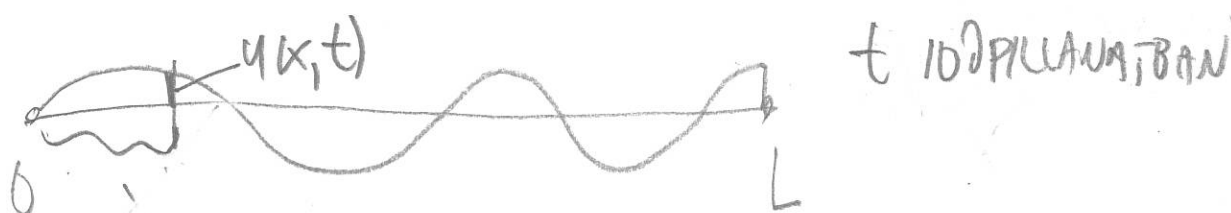


HULLÁMEGYENLET

1D) Homogén rögös húr



LINEÁRIS KÖZELÍTÉS KIS KITEREMLÉS



FERDESGŐ ELMÁNYTÁROLVA
 δl ELMÁNYTÁROLVA

$\approx F \perp g \delta l$



$\frac{\partial y}{\partial x} \Big|_{x=\delta l} - \frac{\partial y}{\partial x} \Big|_{x=0}$

MEGNEVEZÉS

$\tan \alpha = \frac{1}{2} (\downarrow)$

$$F \approx 2T \sin \alpha \approx 2T \tan \alpha = 2T \left(\frac{\partial y}{\partial x} \Big|_{x=2R} - \frac{\partial y}{\partial x} \Big|_{x=0} \right) / 2$$

↑
KIS stränge

$$m = \rho \cdot 2R$$

$$\downarrow \text{S GLEICHUNG WIRD} = \frac{\partial^2 y}{\partial t^2} \Big|_{x=0}$$

$$m g \approx F$$

$$2\rho R \cdot \frac{\partial^2 y}{\partial t^2} \approx T \cdot \left(\frac{\partial y}{\partial x} \Big|_{x=2R} - \frac{\partial y}{\partial x} \Big|_{x=0} \right) \quad | : (2R)$$

h y 0

$$\rho \frac{\partial^2 y}{\partial t^2} = T \cdot \frac{\partial^2 y}{\partial x^2}$$

HULLER FÜR
IDEALISIERUNG

HF: 1) HA $\rho = \rho(x)$, ABER IS $\rho \frac{\partial^2 y}{\partial t^2} = T \cdot \frac{\partial^2 y}{\partial x^2}$

2) INGA



$$m \frac{\partial^2 x}{\partial t^2} = -mg \sin \theta(t) \cos \theta(t)$$

$$= -mg \frac{x(t)}{l} \sqrt{1 - \left(\frac{x(t)}{l}\right)^2} \approx$$

$$\approx -mg \frac{x(t)}{l} \left[1 - \frac{1}{2} \left(\frac{x(t)}{l}\right)^2 \right] \approx$$

$$\approx -mg \frac{x(t)}{l}$$

↑
1REND

D'Alembert megoldás

$$S \frac{\partial^2 u}{\partial t^2} = T \frac{\partial^2 u}{\partial x^2}$$

$$\frac{T}{S} = \frac{e n^2}{\epsilon_0 n^2 / \epsilon_0 \mu_0} = \frac{\epsilon_0 \mu_0 n^2 / \epsilon_0 \mu_0}{\epsilon_0 \mu_0 / \epsilon_0 \mu_0} = \frac{\epsilon_0 \mu_0 n^2}{\epsilon_0 \mu_0} = n^2 c^2$$

TARTALOM, REKURZÍVA

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$$

(*)
$$\left. \begin{aligned} y &= x + ct \\ z &= x - ct \end{aligned} \right\} X = \begin{pmatrix} x \\ t \end{pmatrix} \quad Y = \begin{pmatrix} y \\ z \end{pmatrix} \quad \frac{\partial u}{\partial x} = \frac{\partial u}{\partial y} \frac{\partial y}{\partial x} + \frac{\partial u}{\partial z} \frac{\partial z}{\partial x}$$

$$\left(\frac{\partial f}{\partial x} \quad \frac{\partial f}{\partial t} \right) = \left(\frac{\partial f}{\partial y} \quad \frac{\partial f}{\partial z} \right) \begin{pmatrix} \partial y / \partial x & \partial y / \partial t \\ \partial z / \partial x & \partial z / \partial t \end{pmatrix} = \left(\frac{\partial f}{\partial y} \quad \frac{\partial f}{\partial z} \right) \begin{pmatrix} 1 & c \\ 1 & -c \end{pmatrix}$$

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial y} + \frac{\partial f}{\partial z} \quad \frac{\partial f}{\partial t} = c \frac{\partial f}{\partial y} - c \frac{\partial f}{\partial z}$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial(\partial u / \partial x)}{\partial x} = \frac{\partial(\partial u / \partial y)}{\partial y} + c \frac{\partial(\partial u / \partial x)}{\partial z} =$$

$$= \frac{\partial}{\partial y} \left[\frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} \right] + \frac{\partial}{\partial z} \left[c \frac{\partial u}{\partial y} - c \frac{\partial u}{\partial z} \right] = \frac{\partial^2 u}{\partial y^2} + 2 \frac{\partial^2 u}{\partial y \partial z} + \frac{\partial^2 u}{\partial z^2}$$

$$\frac{\partial^2 u}{\partial t^2} = HF = c^2 \left[\frac{\partial^2 u}{\partial y^2} - 2 \frac{\partial^2 u}{\partial y \partial z} + \frac{\partial^2 u}{\partial z^2} \right]$$

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} \quad \text{oder } Y = \begin{pmatrix} y \\ z \end{pmatrix} = \begin{pmatrix} x+ct \\ x-ct \end{pmatrix} \text{ Koordinatentransformation}$$

$$c^2 \left[\frac{\partial^2 u}{\partial y^2} - 2 \frac{\partial^2 u}{\partial y \partial z} + \frac{\partial^2 u}{\partial z^2} \right] = c^2 \left[\frac{\partial^2 u}{\partial y^2} + 2 \frac{\partial^2 u}{\partial y \partial z} + \frac{\partial^2 u}{\partial z^2} \right]$$

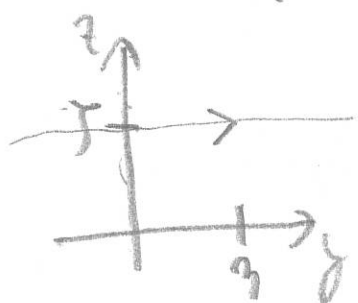
$$0 = \cancel{4} \frac{\partial^2 u}{\partial y \partial z}$$

Total $u: \mathbb{R}^2 \rightarrow \mathbb{R}$ 2x PDE diff, $\begin{pmatrix} y \\ z \end{pmatrix}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ Koordinatentransformation (LIM)

$$\frac{\partial^2 u}{\partial y \partial z} = 0 \Rightarrow u(y, z) = \phi(y) + \psi(z) + \cancel{u(0,0)}$$

$$\phi(\eta) = u(\eta, 0), \quad \psi(\zeta) = u(0, \zeta)$$

bei $\frac{\partial}{\partial y} \frac{\partial u}{\partial z} = 0$



Fix σ

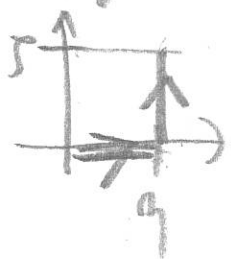
$$\frac{d}{d\tau} \frac{\partial u}{\partial z}(\tau, \sigma) = 0$$

$$\tau \mapsto \frac{\partial u}{\partial z}(\tau, \sigma) = \text{const}(\sigma) =$$

$$= \frac{\partial u}{\partial z}(0, \sigma) = \frac{d}{d\sigma} u(0, \sigma) \uparrow$$

$$\frac{\partial u}{\partial z}(\tau, \sigma) = \psi'(\sigma) \quad \text{wobei } \psi(\sigma) := u(0, \sigma)$$

$$\frac{\partial u}{\partial y}(\eta, \tau) = \phi'(\eta), \quad \phi(\eta) := u(\eta, 0)$$



$$u(\eta, \sigma) = u(\eta, 0) + [u(\eta, \sigma) - u(\eta, 0)] = \phi(\eta) + \int_{\tau=0}^{\sigma} \frac{\partial u}{\partial z}(\eta, \tau) d\tau$$

$$u(x, t) = \phi(x) + \int_0^t \psi(\tau) d\tau =$$

$$= \phi(x) + [\psi(x) - \underbrace{\psi(0)}_{u(0,0)}]$$

D'Alembert Formel

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} \quad \text{HEGELDINGUNG}$$

$$u(x, t) = \phi(x+ct) + \psi(x-ct)$$

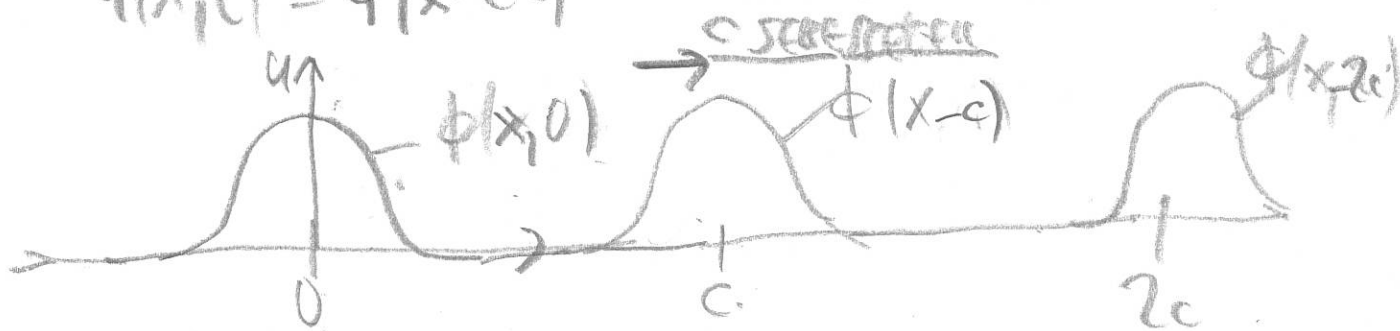
Regionen

ACT. ERST. DERIVATIVESAL (\rightarrow DISTRIBUTIONEN)

ϕ, ψ TETRA FOURIER IS LCHET

Halbe Wellen

$$u(x, t) = \phi(x-ct)$$



„KATRA KAWO“ $u(x, t) = \psi(x+ct)$

„Filerkerchel“

