

# DIFF-FORMA PRIMITIUEI

Def  $f \in C(\mathbb{R})$  este  $F \in C^1(\mathbb{R})$  primitivă  $f$ ,  $F' = f$ .

Diff Formă:  $F$  (ind. formă) primitivă  $f dx$ -ul,  $hs$   $dF = f dx$

$$F_0 := \left[ f \mapsto \int_{t=0}^f f(t) dt \right] \text{ realizează } \{f \text{ primitivă } f dx\} = \{F_0 + c = c \in \mathbb{R}\}$$

Def  $\omega: \mathbb{R}^k \rightarrow \{ \text{forme } k\text{-form} \}$  primitivă  $\Omega: \mathbb{R}^k \rightarrow \{ \text{forme } (k-1)\text{-form} \}$

$$hs \quad d\Omega = \omega. \quad \Omega_0(x) := \int_{t=0}^{x_1, \dots, x_{k-1}} \omega(t, x_1, \dots, x_{k-1}) dt$$

Teoremă  $P_\omega = \{ \omega \text{ primitivă} \} \neq \emptyset \Leftrightarrow d\omega = 0$ , alors  $P_\omega = \{ \Omega_0 + dc = c \in \mathbb{R} \}$

bit 1)  $\Omega \in P_\omega \Rightarrow d\Omega = \omega \Rightarrow d(\Omega - \Omega_0) = d\omega$

2) Stare =  $\omega$ -t regulată =  $Q \mapsto \int_Q \omega$  ( $Q$   $k$ -dim. chiar)

3)  $Q$ -box  $\tilde{Q} = [0, 1]^{k+1} \rightarrow (t, t_1, \dots, t_k) \mapsto t Q(t_1, \dots, t_k)$

Teoremă  $\partial Q = \sum_{n=1}^{2k} R_n$  unde  $R_{11}, R_n$   $(k-1)$ -boxuri,  
 și alors  $\partial \tilde{Q} = Q + \sum_{n=1}^{2k} \tilde{R}_n$

4) Teoremă  $d\omega = 0$  atunci

Stokes,  $\Rightarrow \int_Q d\omega = \int_Q \omega = \int_Q \omega + \sum_{n=1}^{2k} \int_{\tilde{R}_n} \omega$

$$\int_Q \omega = - \sum_{n=1}^{2k} \int_{\tilde{R}_n} \omega$$

5)  $R = (s_{11}, \dots, s_{k1}) \mapsto R(s_{11}, \dots, s_{k1})$  (k-dim. Fläche)

$\tilde{R} = (t, s_{11}, \dots, s_{k1}) \mapsto tR(s_{11}, \dots, s_{k1})$  (k+1-dim. Fläche)

Tydyit:  $\int_{\tilde{R}} \omega = \int_{(t, s_{11}, \dots, s_{k1}) \in [0,1] \times K} \omega(R(t, s_{11}, \dots, s_{k1})) \left[ \frac{\partial \tilde{R}}{\partial t}, \frac{\partial \tilde{R}}{\partial s_{11}}, \dots, \frac{\partial \tilde{R}}{\partial s_{k1}} \right] dt ds_{11} \dots ds_{k1}$

$\int_{\tilde{R}} \omega = \int_{t=0}^1 \int_{S \subset (0,1)^{k-1}} \omega(t, R(s)) \left[ R, t \frac{\partial R}{\partial s_1}, \dots, t \frac{\partial R}{\partial s_{k-1}} \right] dt ds_1 \dots ds_{k-1} =$

$= \int_{t=0}^1 t^{k-1} \omega(tx) \left[ x, \frac{\partial R}{\partial s_1}, \dots, \frac{\partial R}{\partial s_{k-1}} \right] ds_1 \dots ds_{k-1} dt =$

$= \int_{\tilde{R}} \omega_0$

6)  $k \leq n$ :  $\int \omega = \sum_{i_1 < \dots < i_k} \int \omega_{i_1, \dots, i_k} = \int \omega_0 = \int_Q d\omega_0$  (Quadrat)

Koordinatwahl  
 $\omega = \sum_{1 \leq i_1 < \dots < i_k \leq N} f_{i_1, \dots, i_k} dx_{i_1} \wedge \dots \wedge dx_{i_k} = \sum_I f_I dx_I$

$\int_{\tilde{R}} \omega = \int_{t=0}^1 \int_I t^{k-1} \omega(tx) [x, v_1, \dots, v_{k-1}] dt$

$\int_{\tilde{R}} \omega = \int_{t=0}^1 \int_{S \subset (0,1)^{k-1}} t^k f_I(t, R(s)) \cdot \det \begin{pmatrix} R_{i_1}(s) & \frac{\partial R_{i_1}}{\partial s_1} & \dots & \frac{\partial R_{i_1}}{\partial s_{k-1}} \\ \vdots & \vdots & \ddots & \vdots \\ R_{i_k}(s) & \frac{\partial R_{i_k}}{\partial s_1} & \dots & \frac{\partial R_{i_k}}{\partial s_{k-1}} \end{pmatrix} ds_1 \dots ds_{k-1} dt$

$\omega_I = \sum_{t=0}^1 t^{k-1} f_I(tx) \prod_{j=1}^k (x_j - 1)^{j-1} dx_1 \wedge \dots \wedge dx_k$

Pöytä  $w = \frac{1}{1+x^2+y^2+z^2} (y dy + x dx + z dz)$  Primitive

$$dw = \frac{\partial [y/(1+x^2+y^2+z^2)]}{\partial x} dy + \frac{\partial [x/(1+x^2+y^2+z^2)]}{\partial y} dx + \frac{\partial [z/(1+x^2+y^2+z^2)]}{\partial z} dz =$$

$$= -2 \frac{xy}{(1+x^2+y^2+z^2)^2} dx + \frac{y^2 - x^2}{(1+x^2+y^2+z^2)^2} dy + \frac{2xz}{(1+x^2+y^2+z^2)^2} dz = 0$$

$$Q = \int_{t=0}^1 t \frac{ty}{1+t^2x^2+t^2y^2+t^2z^2} [y dz - z dy] dt +$$

$$+ \int_{t=0}^1 t \frac{tx}{1+t^2x^2+t^2y^2+t^2z^2} [x dz - z dx] dt =$$

$$= \int_{t=0}^1 \frac{t^2 dt}{1+t^2x^2+t^2y^2+t^2z^2} [(y^2+x^2) dz - yz dy - xz dx]$$

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$$\frac{1}{1+x^2+y^2+z^2} \text{ Mellin } \text{CSA} (1+x^2+y^2+z^2)$$