# COMPLEX DYNAMICAL SYSTEMS ON BOUNDED SYMMETRIC DOMAINS 

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#### Abstract

We characterize those holomorphic mappings which are the infinitesimal generators of semi-flows on bounded symmetric domains in complex Banach spaces.


## 1. Introduction

Let $D$ be a bounded domain in a complex Banach space $X$. By $\operatorname{Hol}(D, X)$ we denote the set of holomorphic mappings from $D$ into $X$. Let $\operatorname{Hol}(D)$ be the semigroup (with respect to composition) of all holomorphic self-mappings of $D$, and let $\operatorname{Aut}(D) \subset \operatorname{Hol}(D)$ be the subgroup consisting of all holomorphic automorphisms of $D$.

A family $S=\left\{F_{t}\right\} \subset \operatorname{Hol}(D), t \geq 0(-\infty<t<\infty)$, is called a continuous one-parameter semigroup (group) if

$$
\begin{equation*}
F_{s+t}=F_{s} \circ F_{t}, \quad t \geq 0 \quad(-\infty<t<\infty) \tag{1}
\end{equation*}
$$

and

$$
\begin{equation*}
\lim _{\substack{t \rightarrow 0+\\(t \rightarrow 0)}} F_{t}(x)=x, \quad x \in D \tag{2}
\end{equation*}
$$

A mapping $f \in \operatorname{Hol}(D, X)$ is said to be an infinitesimal generator of a semi-flow (complete flow) if there exists a one-parameter semigroup (group) $S_{f}=\left\{F_{t}\right\}$ such that for each $x \in D$,

$$
\begin{equation*}
f(x)=\lim _{\substack{t \rightarrow 0+\\(t \rightarrow 0)}} \frac{x-F_{t}(x)}{t}, \tag{3}
\end{equation*}
$$

where once again the limit is taken with respect to the norm of $X$. We denote by $\operatorname{hol}(D)$ the family of all (infinitesimal) holomorphic generators on $D$.

Note that if $f \in \operatorname{hol}(D)$ generates a complete flow $S_{f}=\left\{F_{t}\right\}_{t \in \mathbb{R}}$, then $F_{t} \in$ $\operatorname{Aut}(D)$ and $F_{t}^{-1}=F_{-t}$ for all $t \in \mathbb{R}$. In this case one writes that $f \in \operatorname{aut}(D)$.

[^0]It can be shown (see, for example, [10] and [11]) that since $f \in \operatorname{hol}(D)$ is locally bounded on $D$, the Cauchy problem

$$
\left\{\begin{array}{l}
\frac{\partial u(t, x)}{\partial t}+f(u(t, x))=0  \tag{4}\\
u(0, x)=x, \quad x \in D
\end{array}\right.
$$

can be solved on $\mathbb{R}^{+}=[0, \infty)$ for each $x \in D$ and $u(t, x)=F_{t}(x)$. Thus (4) defines an analytic dynamical system and $S_{f}=\left\{F_{t}\right\}_{t \geq 0}$ is a uniquely defined semi-flow on D.

Moreover, the convergence in (2) is uniform on each ball strictly inside $D$. If, in addition, $f \in \operatorname{aut}(D)$, then the Cauchy problem (4) can be solved for all $t \in \mathbb{R}=$ $(-\infty, \infty)$.

Note also that if $g \in \operatorname{Hol}(D, X)$, then by allowing $f$ to operate on $g$ by means of the formula $(f g)(x)=g^{\prime}(x) \circ f(x)$ we can interpret $f$ as a derivation of $\operatorname{Hol}(D, X)$, i.e., as a holomorphic vector field. Using this terminology, $f \in \operatorname{hol}(D)$ will be called a semi-complete vector field, and $f \in \operatorname{aut}(D)$ a complete vector field (see, for example, [7], [6], [13] and [10]). It is known that aut $(D)$ is a real Banach Lie algebra, while $\operatorname{hol}(D)$ is only a real cone (see [1], [10] and [11]).

Our purpose in this paper is to describe the class of semi-complete vector fields on a bounded symmetric domain. To motivate our approach we briefly review some previous results.

For the one-dimensional case, namely, $D=\Delta$, the open unit disk in the complex plane $\mathbb{C}$, an implicit condition which characterizes $\operatorname{hol}(\Delta)$ was obtained by $E$. Berkson and H. Porta [4].

It was shown by M. Abate [1] that their condition can be rewritten explicitly in the form

$$
\begin{equation*}
\operatorname{Re} f(x) \bar{x} \geq-\frac{1}{2} \operatorname{Re} f^{\prime}(x)\left(1-|x|^{2}\right) \tag{5}
\end{equation*}
$$

As a matter of fact, this condition is the special case $n=1$ of a more general (and more complicated) condition, which is valid for the open Euclidean unit ball in $\mathbb{C}^{n}$ (see [1]).

On the other hand, it follows directly from the definition, that if $f \in \operatorname{hol}(D)$ has a continuous extension to $\bar{\Delta}$, then

$$
\begin{equation*}
\operatorname{Re} f(x) \bar{x} \geq 0 \quad \text { for all } x \in \partial \Delta \tag{6}
\end{equation*}
$$

Unfortunately, it is not clear how to derive (6) from (5) in such a situation. At the same time, by rewriting (6) in the form

$$
\operatorname{Re}[f(x)-f(0)] \bar{x} \geq-\operatorname{Re} f(0) \bar{x}
$$

and dividing the left-hand side by $|x|^{2}=1$, we get

$$
\operatorname{Re}\left(\frac{f(x)-f(0)}{x}\right) \geq-\operatorname{Re} \overline{f(0)} x, \quad x \in \partial \Delta
$$

Now it follows by the maximum principle for harmonic functions that the last inequality holds also for $x \in \Delta$. Multiplying it by $|x|^{2}, x \in \Delta, x \neq 0$, we obtain

$$
\begin{equation*}
\operatorname{Re} f(x) \bar{x} \geq \operatorname{Re} f(0) \bar{x}\left(1-|x|^{2}\right), x \in \Delta \tag{7}
\end{equation*}
$$

We claim that even if $f \in \operatorname{Hol}(\Delta, \mathbb{C})$ does not extend continuously to $\bar{\Delta}$, condition (7) is necessary and sufficient for $f$ to be an infinitesimal generator of a semi-flow.

Indeed, for the case of the open unit ball $B$ in a Hilbert space $H$, it was shown in [11], by using its hyperbolic metric, that the condition

$$
\begin{equation*}
\operatorname{Re}\langle f(x), x\rangle \geq \operatorname{Re}\langle f(0), x\rangle\left(1-\|x\|^{2}\right), x \in B \tag{8}
\end{equation*}
$$

where $\langle\cdot, \cdot\rangle$ is the inner product in $H$, characterizes the class $\operatorname{hol}(B)$.
Note that a crucial point of the approach in [11] was the smoothness of the boundary of $B$. It is clear that such a property is no longer valid for the finite product $B^{n}$ equipped with the max norm, and all the more so for the open unit ball in $\mathcal{L}(H, H)$, the space of bounded linear operators from $H$ into $H$.

Another technical way to extend (8) to $B^{n}$, by using a special curve defined by a family of Möbius transformations, was employed in [12].

Therefore a natural idea which arises is that this be done for each Banach space $X$ the open unit ball $D$ of which is a homogeneous domain (i.e., for each pair $x, y \in D$ there is $F \in \operatorname{Aut}(D)$ such that $F(x)=y)$.

Indeed, since every such ball is a bounded symmetric domain (see the definition below), one can propose using the more general and well-developed theory of such domains to derive an analog of condition (8) which will characterize hol $(D)$.

It will become clear that such an approach does not require difficult calculations, and moreover, it establishes new facts concerning the description of semi-complete vector fields.

A domain $D$ is called symmetric if for all $a \in D$ there exists $F_{a} \in \operatorname{Aut}(D)$ such that $F_{a}^{2}=I_{D}$ and $a$ is an isolated fixed point of $F_{a}$.

For the case when $D$ is a bounded symetric domain, the class aut ( $D$ ) of all complete vector fields on $D$ has been well-described with the help of an algebraic approach (see, for example, [7], [13], [3] and [6]). Namely, it is known that aut ( $D$ ) is a real Banach Lie algebra and each $f \in \operatorname{aut}(D)$ is a polynomial of degree at most 2. Moreover, if

$$
\begin{equation*}
p=\left\{f \in \operatorname{aut}(D): f^{\prime}(0)=0\right\} \tag{9}
\end{equation*}
$$

and

$$
\begin{equation*}
k=\{f \in \operatorname{aut}(D): f(0)=0\} \tag{10}
\end{equation*}
$$

then $\operatorname{aut}(D)$ is the direct sum decomposition

$$
\operatorname{aut}(D)=p \oplus k
$$

and each element of $X$ can be realized as the constant term of a unique element of $p$, i.e., for each $y \in X$ there is a unique two-homogeneous polynomial $P_{y}$ such that the mapping $g_{y} \in \operatorname{Hol}(X, X)$ defined by the formula

$$
\begin{equation*}
g_{y}(x)=y+P_{y}(x) \tag{11}
\end{equation*}
$$

belongs to $p \subset \operatorname{aut}(D)$.
Furthermore, by Kaup's theorem [8], every bounded symmetric domain $D$ can be realized as the open unit ball of a $J B^{*}$-triple system, and moreover, it is a homogeneous domain, i.e., for each pair $x, y \in D$ there is $F \in \operatorname{Aut}(D)$ such that $F(x)=y$.

Note also that an automorphism which moves the origin to $y \in D$ can be generated by $g \in p \subset \operatorname{aut}(D)$, i.e., $g$ has the form (11) (see, for example, [13] and [6]).

So, in the sequel we will always assume that a bounded symmetric domain is realized as a convex balanced domain. At the same time, in this case the gauge
of $D$ (the Minkowski functional) can be defined as $c_{D}(0, \cdot)$, where $c_{D}(\cdot, \cdot)$ is the infinitesimal Carathéodory metric on $D$, and $D$ is the indicatrix of this gauge, i.e.,

$$
D=\left\{x \in X: c_{D}(0, x)<1\right\} .
$$

Thus, since $D$ is bounded, $c_{D}(0, \cdot)$ is a norm which is equivalent to the norm of $X$, and $D$ can be considered the open unit ball of $X$ when it is equipped with this norm. So, our problem may be formulated as follows.

Let $X$ be a complex Banach space such that the open unit ball $D$ of $X$ is a homogeneous domain. What are the geometric conditions which characterize semicomplete vector fields on $D$ ?

Let $X^{\prime}$ be the dual space of $X$. As usual, we use the pairing $\left\langle x, x^{\prime}\right\rangle$ to denote the action of a linear functional $x^{\prime} \in X^{\prime}$ on an element $x \in X$. In particular, for $X=H$, a Hilbert space, $\langle\cdot, \cdot\rangle$ means the inner product in $H$. Recall also that the normalized duality mapping $J: X \rightarrow 2^{X^{\prime}}$ is defined by

$$
J(x)=\left\{x^{\prime} \in X^{\prime}:\left\langle x, x^{\prime}\right\rangle=\|x\|^{2}=\left\|x^{\prime}\right\|^{2}\right\}
$$

## 2. Main Result

Theorem 1. Let $X$ be a complex Banach space such that the open unit ball $D$ of $X$ is a homogeneous domain. Then the following assertions hold:

1. If $f \in \operatorname{hol}(D)$, then for each $x \in D$ and for each $x^{\prime} \in J(x)$,

$$
\begin{equation*}
\operatorname{Re}\left\langle f(x), x^{\prime}\right\rangle \geq \operatorname{Re}\left\langle f(0), x^{\prime}\right\rangle\left(1-\|x\|^{2}\right) \tag{12}
\end{equation*}
$$

2. If $f \in \operatorname{Hol}(D, X)$ is bounded on each subset strictly inside $D$ and for each $x \in D$ there exists $x^{\prime} \in J(x)$ such that (12) holds, then $f \in \operatorname{hol}(D)$.
3. If $f \in \operatorname{hol}(D)$ and $S_{f}=\left\{F_{t}\right\}_{t \geq 0}$ is the semi-flow generated by $f$, then $F_{t} \in$ $\operatorname{Hol}(D)$ satisfies the following estimate:

$$
\begin{equation*}
\left\|F_{t}(x)\right\| \leq \frac{\|x\|+1-e^{-2\|f(0)\| t}(1-\|x\|)}{\|x\|+1+e^{-2\|f(0)\| t}(1-\|x\|)} \tag{13}
\end{equation*}
$$

To prove our theorem we need several preliminary assertions.
Proposition 1. [10], [11]. Let $D$ be a bounded convex domain in $X$. Then $f \in$ $\operatorname{Hol}(D, X)$ is semi-complete (i.e., belongs to $\operatorname{hol}(D)$ ) if and only if for each $\lambda>0$ the nonlinear resolvent $R(\lambda, f)=(I+\lambda f)^{-1}$ is a well-defined holomorphic self-mapping of $D$.

In addition, if $S_{f}=\left\{F_{t}\right\}_{t \geq 0}$ is the semi-flow generated by $f$, then it can be given by the exponential formula

$$
\begin{equation*}
F_{t}=\lim _{n \rightarrow \infty} R^{n}\left(\frac{1}{n} t, f\right), \quad t \geq 0 \tag{14}
\end{equation*}
$$

where the limit in (14) is taken with respect to the norm of $X$ uniformly on each subset strictly inside $D$.

Proposition 2. [10], [11]. Let $D$ be as in Proposition 1. Then $\operatorname{hol}(D)$ is a real cone, i.e., for each pair $f$ and $g$ from $\operatorname{hol}(D)$ and all $\alpha, \beta>0$, the mapping $\alpha f+\beta g$ also belongs to hol $(D)$.

Since $\operatorname{aut}(D)=\operatorname{hol}(D) \cap(-\operatorname{hol}(D))$ is a linear space, Proposition 2 immediately implies the following assertion.

Proposition 3. Let $D$ be a bounded balanced convex symmetric domain in $X$. Then each element $f \in \operatorname{hol}(D)$ can be represented as

$$
\begin{equation*}
f=h+g \tag{15}
\end{equation*}
$$

where $h \in \operatorname{hol}(D)$ with $h(0)=0$ and $g=g_{y} \in p \subset$ aut $(D)$ is defined by (11) with $y=f(0)$. This representation is unique.

Proposition 4. Let $f \in \operatorname{hol}(D)$ be as above, and let $g_{f(0)} \in p \subset$ aut $(D)$ be defined by (11). Then for each $x \in D$ and for each $x^{\prime} \in J(x)$ the following inequality holds:

$$
\begin{equation*}
\operatorname{Re}\left\langle f(x), x^{\prime}\right\rangle \geq \operatorname{Re}\left\langle g_{f(0)}(x), x^{\prime}\right\rangle \tag{16}
\end{equation*}
$$

Proof. Indeed, it follows by (15) that $h=f-g_{f(0)}$ belongs to $\operatorname{hol}(D)$ and

$$
\begin{equation*}
h(0)=0 . \tag{17}
\end{equation*}
$$

Let $S_{h}=\left\{\mathcal{H}_{t}\right\}_{t \geq 0} \subset \operatorname{Hol}(D)$ be the semi-flow generated by $h$, i.e., for each $x \in D$,

$$
\lim _{t \rightarrow 0^{+}} \frac{x-\mathcal{H}_{t}(x)}{t}=h(x)
$$

It follows by the uniqueness of the solution to the Cauchy problem (4) and by (17) that the origin is a common fixed point of $S_{h}=\left\{\mathcal{H}_{t}\right\}_{t \geq 0}$ for all $t \geq 0$. Since $\left\|\mathcal{H}_{t}(x)\right\| \leq 1$, it follows by the Schwarz Lemma that $\left\|\mathcal{H}_{t}(x)\right\| \leq\|x\|$ for all $x \in D$. Now using (17), we get

$$
\begin{equation*}
\operatorname{Re}\left\langle h(x), x^{\prime}\right\rangle \geq 0 \tag{18}
\end{equation*}
$$

for all $x^{\prime} \in J(x)$. By the definition of $h,(18)$ is exactly (16), and we are done.
Now it is very easy to prove the necessity of (12) for $f$ to be a semi-complete vector field. In fact, for each $u \in \partial D$ and each $g \in \operatorname{aut}(D)$ we have

$$
\begin{equation*}
\operatorname{Re}\left\langle g(u), u^{\prime}\right\rangle=0 \tag{19}
\end{equation*}
$$

whenever $u^{\prime} \in J(u)$ (note that $g$ is holomorphically extensible to $\partial D$ ). In particular, this holds for $g_{y}=y+P_{y}(x) \in p$ where $P_{y}$ is a homogeneous polynomial of degree 2. Therefore, if for $x \in D, x \neq 0$, we set $u=\frac{1}{\|x\|} x$, we obtain

$$
\begin{aligned}
\operatorname{Re}\left\langle g_{y}(x), x^{\prime}\right\rangle= & \operatorname{Re}\left\langle y+P_{y}(x), x^{\prime}\right\rangle=\operatorname{Re}\left\langle y, x^{\prime}\right\rangle+\operatorname{Re}\left\langle P_{y}(x), x^{\prime}\right\rangle \\
= & \operatorname{Re}\left\langle y, x^{\prime}\right\rangle+\|x\|^{3} \operatorname{Re}\left\langle P_{y}(u), u^{\prime}\right\rangle \\
= & \operatorname{Re}\left\langle y, x^{\prime}\right\rangle+\|x\|^{3}\left(\operatorname{Re}\left\langle P_{y}(u), u^{\prime}\right\rangle+\left\langle y, u^{\prime}\right\rangle\right) \\
& -\|x\|^{3} \operatorname{Re}\left\langle y, u^{\prime}\right\rangle \\
= & \operatorname{Re}\left\langle y, x^{\prime}\right\rangle-\|x\|^{2} \operatorname{Re}\left\langle y,\|x\| u^{\prime}\right\rangle \\
= & \operatorname{Re}\left\langle y, x^{\prime}\right\rangle\left(1-\|x\|^{2}\right) .
\end{aligned}
$$

Using this equality with $y=f(0)$ and (16) we obtain (12). Assertion 1 of our theorem is proved. To prove assertions 2 and 3 we first establish a somewhat more general proposition.
Proposition 5. Let $X$ be an arbitrary complex Banach space, and let $D$ be the open unit ball in $X$. Suppose that $f \in \operatorname{Hol}(D, X)$ is bounded on each subset strictly inside $D$ and satisfies the following condition: For each $x \in D$ and some $x^{\prime} \in J(x)$,

$$
\begin{equation*}
\operatorname{Re}\left\langle f(x), x^{\prime}\right\rangle \geq \alpha(\|x\|) \cdot\|x\| \tag{20}
\end{equation*}
$$

where $\alpha:[0,1] \rightarrow \mathbb{R}$ is an increasing continuous function on $[0,1]$ such that

$$
\begin{equation*}
\alpha(0) \cdot \alpha(1) \leq 0 \tag{21}
\end{equation*}
$$

## Then

1. $f$ is a semi-complete vector field on $D$.
2. If $S_{f}=\left\{F_{t}\right\}$ is the semi-flow generated by $f$, then for all $t \geq 0$ and $x \in D$,

$$
\begin{equation*}
\left\|F_{t}(x)\right\| \leq \beta_{t}(\|x\|) \tag{22}
\end{equation*}
$$

where $\beta_{t}$ is the solution of the Cauchy problem

$$
\left\{\begin{array}{l}
\frac{d \beta_{t}(s)}{d t}+\alpha\left(\beta_{t}(s)\right)=0  \tag{23}\\
\beta_{0}(s)=s, \quad s \in[0,1]
\end{array}\right.
$$

Proof. Fix $r \in(0,1)$ and consider the equations

$$
\begin{align*}
x+\lambda f(x) & =z  \tag{24}\\
s+\lambda \alpha(s) & =\|z\| \tag{25}
\end{align*}
$$

where $z \in \bar{D}_{r}=\{x \in X:\|x\| \leq r<1\}, s \in[0,1]$, and $\lambda>0$. It follows from (21) that for a fixed $z \in \bar{D}_{r}$, the function $\gamma(s)=s+\lambda \alpha(s)-\|z\|$ satisfies the conditions $\gamma(0) \leq 0, \gamma(1)>0$. Hence equation (25) has a unique solution $s_{0}=s_{0}(z) \in[0,1)$. So, for an arbitrary $\delta>0$ we can find $\epsilon>0$ such that $\gamma\left(s_{0}+\delta\right) \geq \epsilon$. Now taking $x \in D$ such that $\|x\|=s=s_{0}+\delta$, we have by (20) for such $x$ and any $x^{\prime} \in J(x)$,

$$
\begin{aligned}
\operatorname{Re}\left\langle x+\lambda f(x)-z, x^{\prime}\right\rangle & =\operatorname{Re}\left(\left\langle x, x^{\prime}\right\rangle+\lambda\left\langle f(x), x^{\prime}\right\rangle-\left\langle z, x^{\prime}\right\rangle\right) \\
& \geq s^{2}+\lambda \alpha(s) \cdot s-\|z\| \cdot s \\
& =s \gamma(s) \geq s \cdot \epsilon
\end{aligned}
$$

It follows by the same considerations as in Theorem 3 in [2] that equation (24) has a unique solution $x=x(z)$ such that $\|x(z)\| \leq s_{0}+\delta$. Since $\delta>0$ is arbitrary, we must have

$$
\|x(z)\| \leq s_{0}
$$

In terms of nonlinear resolvents the last inequality can be rewritten as

$$
\begin{aligned}
\|R(\lambda, f)(z)\| & =\left\|\left(I_{X}+\lambda f\right)^{-1}(z)\right\| \leq R(\lambda, \alpha)(\|z\|) \\
& =\left(I_{\mathbb{R}}+\lambda \alpha\right)^{-1}(\|z\|)
\end{aligned}
$$

Now using Proposition 1 and the exponential formula (14) we deduce our assertion.
To prove our theorem we need only observe that the function

$$
\begin{equation*}
\alpha(s)=-\|f(0)\|\left(1-s^{2}\right) \tag{26}
\end{equation*}
$$

satisfies all the conditions of Proposition 5, and that the solution $\beta_{t}(s)$ of the Cauchy problem (23) with $\alpha$ defined by (26) has the same form as the right-hand side of (13). The theorem is proved.

Remark 1. If $X$ is a $J^{*}$-algebra, then condition (16) can be rewritten in the form

$$
\begin{equation*}
\operatorname{Re}\left\langle f(x), x^{\prime}\right\rangle \geq \operatorname{Re}\left\langle f(0)-x[f(0)]^{*} x, x^{\prime}\right\rangle \tag{27}
\end{equation*}
$$

which also characterizes those mappings $f \in \operatorname{Hol}(D, X)$ which are semi-complete vector fields on the open unit ball of $X$.

For example, consider the case of the algebra $X=\mathcal{L}_{c}\left(H_{1}, H_{2}\right)$ of all linear compact operators $\mathcal{A}: H_{1} \rightarrow H_{2}$ ( $\mathcal{A}$ is defined on the whole of $H_{1}$ and maps it compactly into $H_{2}$ ), when $H_{1}$ and $H_{2}$ are Hilbert spaces.

Let $\mathcal{D}$ be the open unit operator ball of $\mathcal{L}_{c}\left(H_{1}, H_{2}\right)$, that is, $\mathcal{D}=\left\{\mathcal{A} \in \mathcal{L}_{c}\left(H_{1}, H_{2}\right)\right.$ : $\|\mathcal{A}\|<1\}$. Suppose that the mapping $f$ belongs to $\operatorname{Hol}(D, X)$. It is easy to see that for any $\mathcal{A} \in \mathcal{L}_{c}\left(H_{1}, H_{2}\right)$ there exists $x_{\mathcal{A}} \in H_{1}$ such that $\|\mathcal{A}\|=\left\|\mathcal{A} x_{\mathcal{A}}\right\|$ and
$\left\|x_{\mathcal{A}}\right\|=1$. Indeed, $\|\mathcal{A}\|=\sup _{\substack{\| x \neq 1 \\ x \in H_{1}}}\|\mathcal{A} x\|$, so there exists $\left\{x_{n}\right\}_{n=1}^{\infty}$ such that $\left\|x_{n}\right\|=1$ and $\left\|\mathcal{A} x_{n}\right\| \rightarrow\|\mathcal{A}\|$, as $n \rightarrow \infty$. Since $H_{1}$ is a Hilbert space, there exists a subsequence $\left\{x_{n_{k}}\right\}_{k=1}^{\infty}$ of the sequence $\left\{x_{n}\right\}_{n=1}^{\infty}$ which converges weakly to some $x_{A} \in H_{1}$. Since $\mathcal{A}$ is compact, $\mathcal{A} x_{n_{k}} \rightarrow \mathcal{A} x_{A}$ as $k \rightarrow \infty$. Hence $\left\|\mathcal{A} x_{\mathcal{A}}\right\|=\|\mathcal{A}\|$ and $\left\|x_{\mathcal{A}}\right\|=1$.

For any $\mathcal{A} \in \mathcal{L}_{c}\left(H_{1}, H_{2}\right)$ we construct the support functional $g_{\mathcal{A}} \in\left(\mathcal{L}_{c}\left(H_{1}, H_{2}\right)\right)^{*}$ in the following way:

$$
g_{\mathcal{A}}(T):=\left(T x_{\mathcal{A}},\|\mathcal{A}\|^{-1} \mathcal{A} x_{A}\right), T \in \mathcal{L}_{c}\left(H_{1}, H_{2}\right) .
$$

$\left((x, y)\right.$ is the scalar product in $\left.H_{2}\right)$.
We have $\left|g_{\mathcal{A}}(T)\right| \leq\left\|T x_{\mathcal{A}}\right\|\left\|x_{\mathcal{A}}\right\| \leq\|T\|, \quad g_{\mathcal{A}}(\mathcal{A})=\|\mathcal{A}\|$, hence $\left\|g_{\mathcal{A}}\right\|=1$. Thus $g_{\mathcal{A}}$ belongs to $J(\mathcal{A})$.

The following condition is a natural analog of (7) for this algebra:

$$
\begin{equation*}
\operatorname{Re} \mathcal{A}^{*} f(A) \geq \operatorname{Re} \mathcal{A}^{*} f(0)\left(\mathcal{I}-|\mathcal{A}|^{2}\right) \tag{28}
\end{equation*}
$$

(here $|\mathcal{A}|^{2}=\mathcal{A}^{*} \mathcal{A}$ ).
We claim that this simple condition implies (27). Indeed, (28) is equivalent to

$$
\begin{aligned}
\operatorname{Re}\left(\mathcal{A}^{*} f(\mathcal{A}) x, x\right) & \geq \operatorname{Re}\left(\mathcal{A}^{*} f(0)\left(\mathcal{I}-|\mathcal{A}|^{2}\right) x, x\right) \\
& \left.=\operatorname{Re}\left(\left(\mathcal{A}^{*} f(0) x, x\right)-A^{*} f(0) \mathcal{A}^{*} \mathcal{A} x, x\right)\right) \\
& =\operatorname{Re}\left(\left(\mathcal{A}^{*} f(0) x, x\right)-\left(\mathcal{A}^{*} \mathcal{A}[f(0)]^{*} \mathcal{A} x, x\right)\right) .
\end{aligned}
$$

Hence for $x=x_{\mathcal{A}}$ we obtain:

$$
\operatorname{Re}\left(f(\mathcal{A}) x_{\mathcal{A}}, \mathcal{A} x_{\mathcal{A}}\right) \geq \operatorname{Re}\left(\left(f(0) x_{\mathcal{A}}, \mathcal{A} x_{\mathcal{A}}\right)-\left(\mathcal{A}[f(0)]^{*} \mathcal{A} x_{\mathcal{A}}, \mathcal{A} x_{\mathcal{A}}\right),\right.
$$

or, setting $\mathcal{A}^{\prime}$ to be $g_{\mathcal{A}}$,

$$
\operatorname{Re}\left\langle f(\mathcal{A}), \mathcal{A}^{\prime}\right\rangle \geq \operatorname{Re}\left\langle f(0)-\mathcal{A}[f(0)]^{*} \mathcal{A}, \mathcal{A}^{\prime}\right\rangle,
$$

which is precisely (27).
Note that in the particular case when $\min \left(\operatorname{dim} H_{1}, \operatorname{dim} H_{2}\right)<\infty, \mathcal{L}_{c}\left(H_{1}, H_{2}\right)=$ $\mathcal{L}\left(H_{1}, H_{2}\right)$, the space of all bounded linear operators $\mathcal{A}: H_{1} \rightarrow H_{2}$. So in this case all of the above is also true for the open unit ball $\mathcal{D}$ of $\mathcal{L}\left(H_{1}, H_{2}\right)$.

Remark 2. If $f \in \operatorname{hol}(D)$, then it follows from the representation (15) (see Proposition 3) that the linear operator $A=f^{\prime}(0)$ is accretive.

Indeed, if $h=f-g_{f(0)}$, then $h^{\prime}(0)=f^{\prime}(0)=A$. But $h(0)=0$ and the origin is a common fixed point of the semi-flow $S_{h}=\left\{\mathcal{H}_{t}\right\}_{t \geq 0}$. Using the Cauchy inequalities, it is easy to check that the family $\left\{B_{t}=\left(\mathcal{H}_{t}\right)^{\prime}(0)\right\}_{t \geq 0}$ is a semigroup of linear contractions generated by $A$. Therefore $A$ is accretive by the Lumer-Phillips Theorem.

Thus, if in the $J^{*}$-algebra $X$ we consider the Riccati flow equation

$$
\left\{\begin{array}{l}
\dot{x}_{t}=a+b x_{t}-x_{t} a^{*} x_{t}, \\
x_{0}=x \in D
\end{array}\right.
$$

then this equation has a solution on $D \times \mathbb{R}^{+}$if and only if the element $b \in X$ defines an accretive linear operator by $x \mapsto b x$.
Remark 3. As a matter of fact, if under the conditions of our Theorem, the operator $B=i A$, where $A=f^{\prime}(0)$, is Hermitian, i.e., Re $\left\langle A x, x^{\prime}\right\rangle=0$ for all $x \in X$ and $x^{\prime} \in J(x)$, then $f \in \operatorname{hol}(D)$ actually belongs to aut $(D)$.

Indeed, it is enough to prove that $h$ in the representation (15) has the form

$$
\begin{equation*}
h(x)=f^{\prime}(0) x \tag{29}
\end{equation*}
$$

To see this, let us represent $h(x)$ by the Taylor formula

$$
h(x)=h^{\prime}(0) x+k(x)
$$

where $k(x)$ contains the terms of order greater or equal to 2 . Then, by (18), we have

$$
\operatorname{Re}\left\langle h(x), x^{\prime}\right\rangle=\operatorname{Re}\left\langle h^{\prime}(0) x, x^{\prime}\right\rangle+\operatorname{Re}\left\langle k(x), x^{\prime}\right\rangle \geq 0
$$

Since $h^{\prime}(0)=f^{\prime}(0)$ we see that

$$
\operatorname{Re}\left\langle k(x), x^{\prime}\right\rangle \geq 0
$$

Since $k(0)=0$, we get by the theorem that $k \in \operatorname{hol}(D)$. But $k^{\prime}(0)=0$ and it follows by the infinitesimal version of the Cartan Uniqueness Theorem (see [10]) that $k=0$ and we are done.

Following S. G. Krein [9] (see also E. Vesentini [14]), a linear operator $A: X \rightarrow X$ such that $\operatorname{Re}\left\langle A x, x^{\prime}\right\rangle=0$ for all $x \in X$ and $x^{\prime} \in J(x)$ is called a conservative operator. So we have the following result.

Corollary 1. Let $f \in \operatorname{hol}(D)$. Then $f$ is a complete vector field $(f \in \operatorname{aut}(D)$ if and only if the operator $f^{\prime}(0)$ is conservative.

The following proposition is a direct consequence of assertion 3 of the Theorem. It is motivated by Proposition 7 in [5].
Corollary 2. Let $S=\left\{F_{t}\right\}_{t \geq 0}$ be a one-parameter semigroup of holomorphic selfmappings of $D$ such that $F_{t}$ converges to $I$, as $t \rightarrow 0^{+}$, locally uniformly on $D$. Then for each $\rho \in(0,1), M \in \mathbb{R}^{+}$and $\alpha \in \mathbb{R}^{+}$, there exists a positive number $A=A(\rho, M, \alpha)<1$ such that

$$
\sup \left\{\left\|F_{t}(x)\right\|:\|\xi\| \leq M, \quad\|x\| \leq \rho, 0 \leq t \leq \alpha\right\} \leq A
$$

where $\xi=\frac{d^{+} F_{t}(0)}{d t}$.
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