

Connectivity and components. Trees.

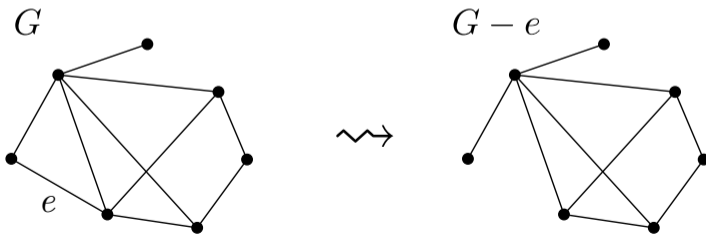
Graph theory
for MSc students in Computer Science

University of Szeged
Szeged, 2024.

Let G be a multigraph, an edge $e \in E(G)$ and a vertex $v \in V(G)$ of it.

$G - e$ denotes the graph obtained by removing the edge e from G (i.e. e is deleted from the edge set and the incidences are inherited from G).

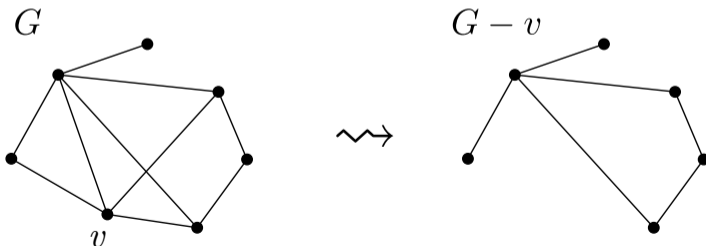
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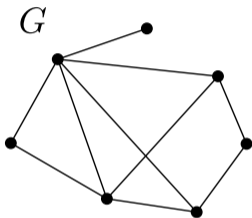
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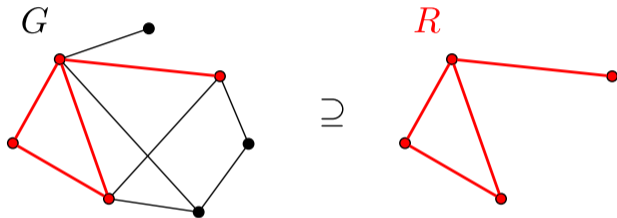
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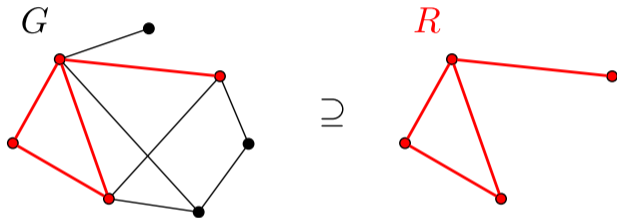
Def. The (multi)graph R is a **sub(multi)graph** of the (multi)graph G , if R can be obtained from G by removing some (or no) edges and vertices. If R is a submultigraph of G , then we also say that G **contains** R . Notation: $R \subseteq G$.



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Remark. G is a subgraph of itself.

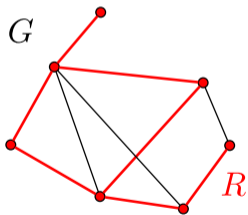
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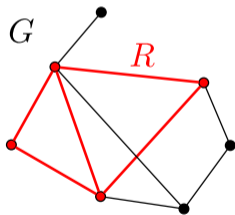
Def. The sub(multi)graph R of G is an **induced sub(multi)graph** (on S), if the vertex set of R is a subset $S \subseteq V(G)$, and R contains exactly those edges of G whose both endpoints belong to S . So the induced submultigraph R is determined by the set S , and it is denoted by $G|_S$.

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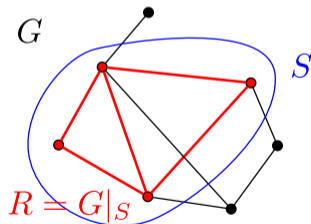
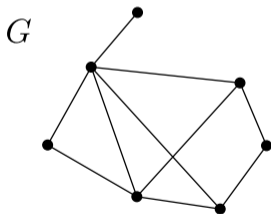
a spanning subgraph



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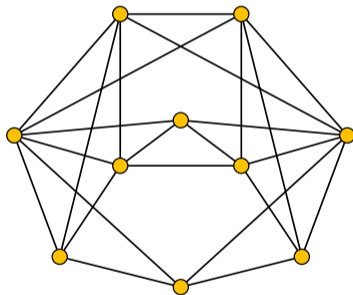


Definition. A **walk** \mathcal{W} in a multigraph G is a sequence

$$\mathcal{W} : (v_0, e_1, v_1, e_2, v_2, e_3, v_3, \dots, v_{l-1}, e_l, v_l),$$

where $v_0, v_1, \dots, v_\ell \in V(G)$, $e_1, \dots, e_\ell \in E(G)$, and the two endvertices of e_i are v_{i-1} and v_i , for every $i = 1, \dots, \ell$.

We say that ℓ is the **length** of the walk. ($\ell = 0$ is a possibility: ' (v_0) ' is a path of length 0.) A walk is **closed** iff $v_0 = v_\ell$, otherwise we call it non-closed.

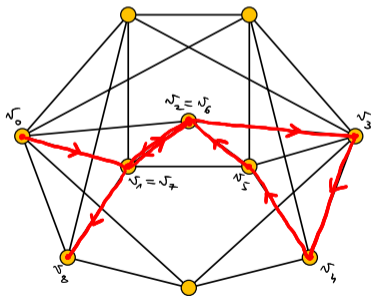


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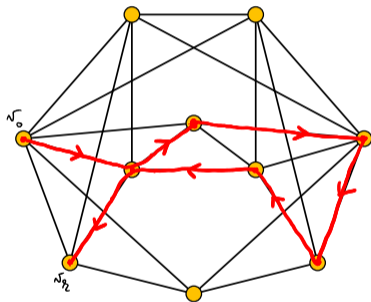
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A non-closed walk of length 8

Definition. Let \mathcal{W} be a walk $(v_0, e_1, v_1, e_2, v_2, e_3, v_3, \dots, v_{l-1}, e_l, v_l)$ in G .

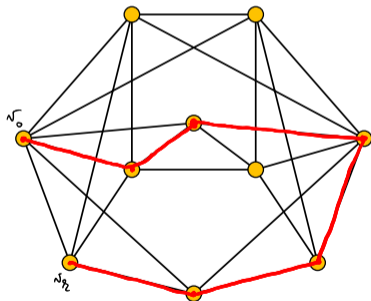
- The walk \mathcal{W} is called **trail** iff it has no repeated edges (i.e. all e_i 's are different).



A trail

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(However, the reversed implications are false. See the former figures.)

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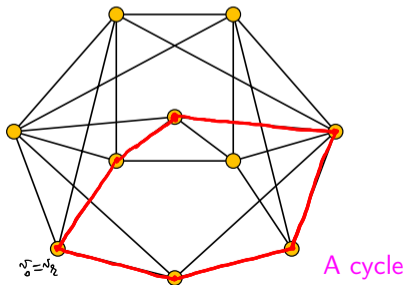
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Proposition. In a multigraph G , for any two vertices x and y , there exists an xy -path in G if and only if there exists an xy -walk in G .

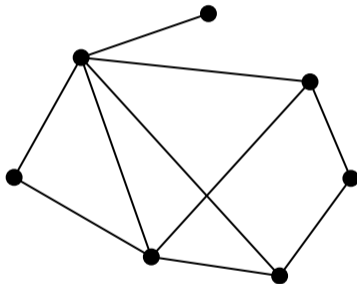
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- The walk \mathcal{W} is called **path** iff it has no repeated vertices (i.e. all v_i 's are different).
- The walk \mathcal{W} is called **cycle** iff $l > 0$, and v_0, v_1, \dots, v_{l-1} are different vertices, but $v_l = v_0$, furthermore in the case $l = 2$ we have $e_1 \neq e_2$.



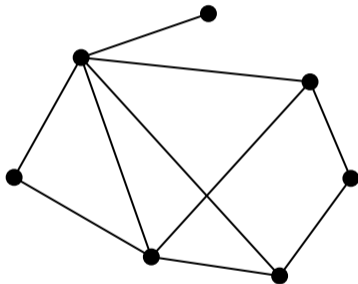
Definition. A multigraph G is **connected**, if for any two vertices $x, y \in V(G)$, there exists an xy -walk (or equivalently, an xy -path) in G . A multigraph that is not connected is called **disconnected**.

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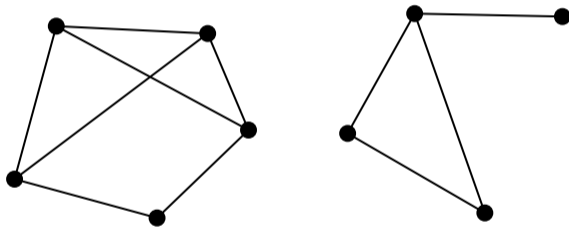
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It is enough to check that any vertex can be reached from an arbitrary fixed vertex v by following some sequence of edges. (Why?)

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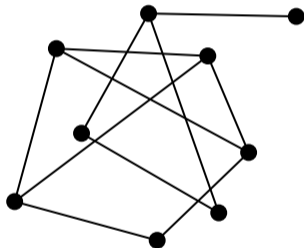
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(This graph has 9 vertices.)

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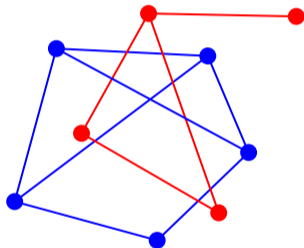
A disconnected graph #2.



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The following theorem gives the structure of disconnected multigraphs:

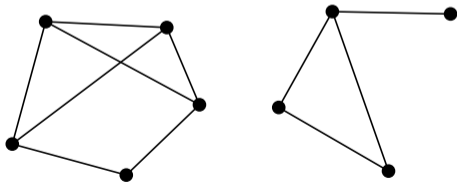
Theorem. Every multigraph G is a vertex-disjoint union of **connected** multigraphs G_1, \dots, G_k ; and this decomposition is unique. (That is, G_1, \dots, G_k are connected induced submultigraphs of G such that there is no edge in G between G_i and G_j for $i \neq j$.)

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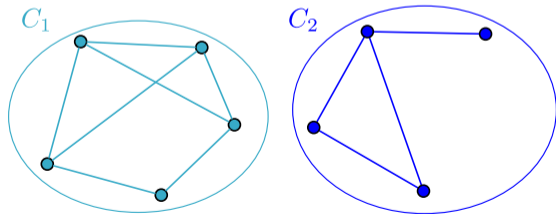


A disconnected graph with 2 components

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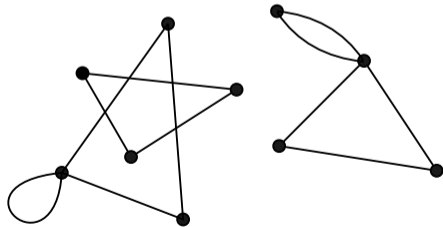


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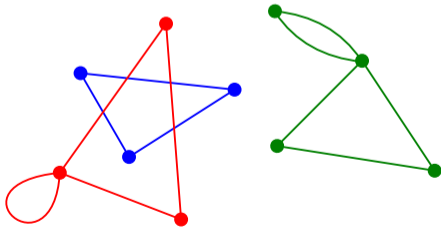


A disconnected multigraph with 3 components

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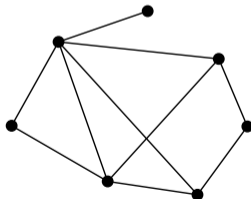


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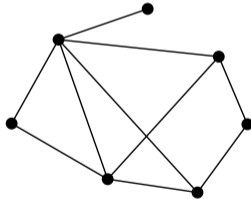
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A connected graph (with 1 components)

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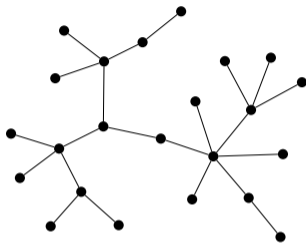
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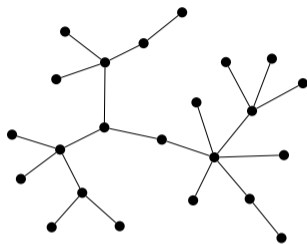
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Remark. We note that a multigraph is disconnected, if and only if it has more than one components.

Def. A multigraph is a **tree**, if it is connected and it does not contain a cycle.



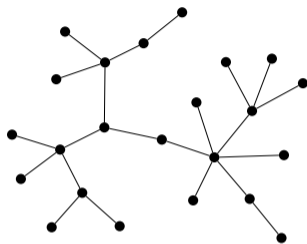
Def. A multigraph is a **tree**, if it is connected and it does not contain a cycle.



Remark. Every tree is a simple graph by definition. (A loop would form a cycle of length 1, two parallel edges would form a cycle of length 2.)

Remark. Graphs without cycles are called **acyclic** graphs.

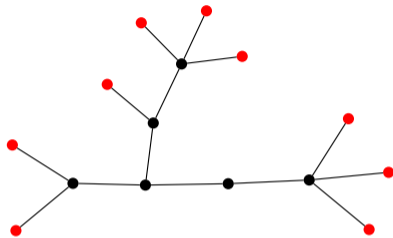
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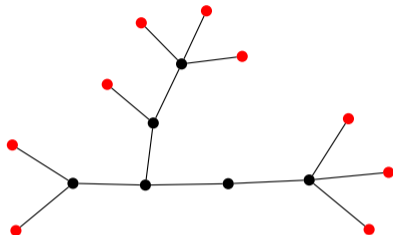
Thm. For any graph G , the following statements are equivalent.

- G is a tree.
- G is connected, but the removal of any edge would disconnect it (i.e. $G - e$ is disconnected for all $e \in E(G)$).
- or any two vertices $x, y \in V(G)$, there exists exactly one xy -path in G .

Def. In a tree T , the vertices with degree 1 are called the **leaves** of T .

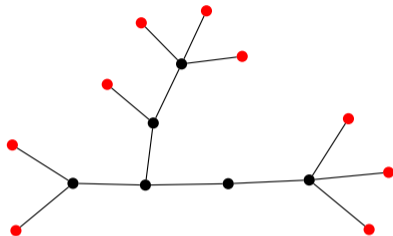


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Claim. Every tree with at least two vertices has a leaf. (In fact, every such tree has at least two leaves.)

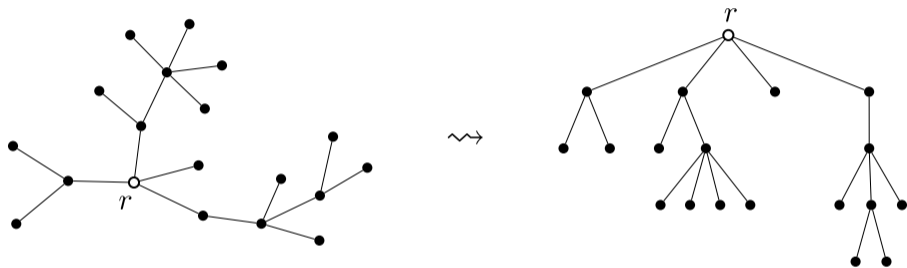
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Thm. A tree on n vertices has exactly $n - 1$ edges.

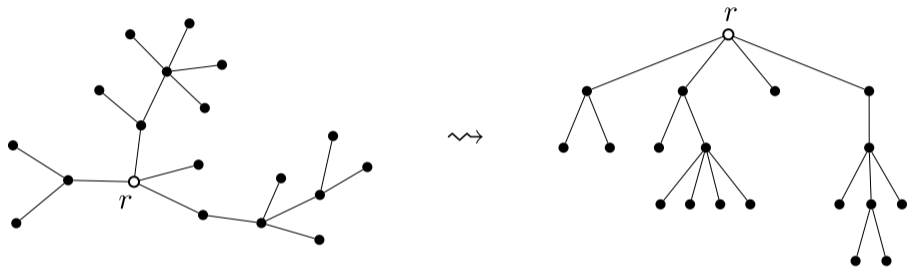
Every tree T can be drawn like a family tree, as illustrated in the figure. (An arbitrary vertex $r \in V(T)$ can be designated as the root of the family tree.)



In the drawing, the vertices of T are arranged in levels, such that

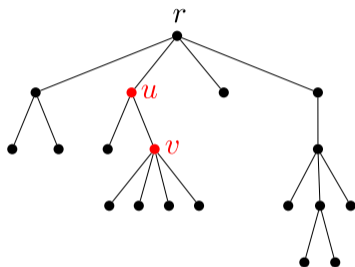
- (i) there is exactly one vertex on the top level, the (root) vertex r ;
- (ii) every edge of T connects two vertices on adjacent levels;
- (iii) for any non-root vertex u , there is exactly one edge in T that connects u to a vertex on the level just above the level of u .

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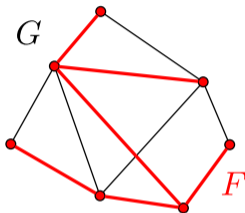
Remark. After designating a root vertex r in a tree T , this drawing of is unique in the following sense: The level of any vertex $v \in V(T)$ is uniquely determined. If the length of the unique rv -path in T is ℓ , then v belongs to the $(\ell + 1)^{\text{th}}$ level (from top to bottom). We refer to this drawing as **rooted tree** T (with root r).

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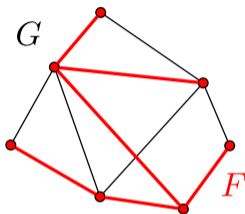


Def. If u and v are adjacent vertices in a rooted tree T , and the level of v is lower than the level of u , then u is called the **parent** of v , and v is called the **child** of u . (And other related names are used, like siblings, etc.)

Def. A **spanning tree** of a multigraph G is spanning subgraph (that contains all vertices of G) which is a tree.

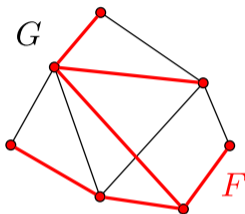


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Corollary. Every **connected** graph on n vertices has at least $n - 1$ edges.