# Characterization of self-adjoint domains for regular even order *C*-symmetric differential operators

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**Abstract.** Let *C* be a skew-diagonal constant matrix satisfying  $C^{-1} = -C = C^*$ . We characterize the self-adjoint domains for regular even order *C*-symmetric differential operators with two-point boundary conditions. The previously known characterizations are a special case of this one.

**Keywords:** *C*-symmetric, differential operators, boundary conditions, self-adjoint domains.

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## 1 Introduction

Consider the differential equation

$$My = \lambda wy \quad \text{on } J = (a, b), \ -\infty \le a < b \le \infty$$
 (1.1)

with boundary conditions

$$AY(a) + BY(b) = 0, \qquad A, B \in M_n(\mathbb{C}), \tag{1.2}$$

where  $M_n(\mathbb{C})$  denotes the set of  $n \times n$  matrices of complex numbers. (This notation is standard and should not conflict with the notation *M* for differential expressions.)

In this paper, for regular endpoints *a*, *b*, any n = 2k, k > 1, and any skew-diagonal constant matrix *C* which satisfies

$$C^{-1} = -C = C^*, (1.3)$$

we generate symmetric differential expressions  $M = M_Q$  and characterize the boundary conditions (1.2) which determine self-adjoint operators S in  $L^2(J, w)$  satisfying  $S_{\min} \subset S = S^* \subset S_{\max}$ . Here the matrix  $Q \in Z_n(J, \mathbb{C})$  is a C-symmetric matrix in the sense that

$$Q = -C^{-1}Q^*C (1.4)$$

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and  $M = M_Q$  is generated by Q.

Such a characterization is well known [17] when

$$C = E = ((-1)^r \delta_{r,n+1-s})_{r,s=1}^n.$$
(1.5)

We prove the following theorem:

**Theorem 1.1.** Let  $Q \in Z_n(J, \mathbb{C})$ , n = 2k, k = 1, 2, 3, ..., let  $M = M_Q$ , let w be a weight function. Suppose a, b are regular endpoints. Assume that C satisfies (1.4) and Q satisfies the C-symmetry condition:

$$Q = -C^{-1}Q^*C.$$

Then the linear manifold D(S) defined by

$$D(S) = \{ y \in D_{\max}; (1.2) \text{ holds} \}$$
(1.6)

is the domain of a self-adjoint extension S of  $S_{min}$  (or restriction of  $S_{max}$ ) if and only if

$$\operatorname{rank}(A:B) = n \quad and \quad ACA^* = BCB^*. \tag{1.7}$$

*Proof.* The proof will be given below.

**Remark 1.2.** We find it remarkable that the self-adjoint boundary conditions are characterized by the same matrix *C* which generates the symmetric operators *M*.

The definitions of  $Z_n(J,\mathbb{C})$ , the quasi-derivatives  $y^{[j]}$ , j = 0, ..., n - 1, and  $M_Q$  will be given in Section 2, the proof of the theorem in Section 3 and examples of matrices *C* and *C*-self-adjoint boundary conditions are given in Section 4. See [17] for definitions of  $S_{\min}$ ,  $S_{\max}$ ,  $D_{\min}$ ,  $D_{\max}$ , etc.

## 2 *C*-symmetric expressions

In this section, we develop a general form of the *C*-symmetric quasi-differential expression *M* with complex coefficient of any even order n = 2k,  $k \ge 1$  on an interval J = (a, b),  $-\infty < a < b < \infty$ .

Let

$$Z_n(J) := \left\{ Q = (q_{r,s})_{r,s=1}^n : \ Q \in M_n(L_{\text{loc}}(J)); \\ q_{r,r+1} \neq 0 \text{ a.e. } J, \ q_{r,r+1}^{-1} \in L_{\text{loc}}(J), \ 1 \le r \le n-1; \\ q_{r,s} = 0 \text{ a.e. } J, \ 2 \le r+1 < s \le n \\ q_{r,s} \in L_{\text{loc}}(J), \ s \ne r+1, \ 1 \le r \le n-1 \right\}.$$

For  $Q \in Z_n(J)$ , in [3] define the quasi-derivatives  $y^{[r]}$   $(0 \le r \le n)$  below:

$$V_{0} := \{y : J \to \mathbb{C}, y \text{ is measurable}\}, \qquad y^{[0]} := y \ (y \in V_{0}),$$
$$V_{r} := \{y \in V_{r-1} : y^{[r-1]} \in (AC_{\text{loc}}(J))\},$$
$$y^{[r]} = q_{r,r+1}^{-1} \left\{y^{[r-1]'} - \sum_{s=1}^{r} q_{r,s} y^{[s-1]}\right\} \qquad (y \in V_{r}, \ r = 1, 2, \dots, n).$$

where  $q_{n,n+1} = 1$ . Finally we set

$$My = i^n y^{[n]}, \qquad y \in V_n,$$

these expressions  $M = M_Q$  are generated by or associated with Q and for  $V_n$  we also use the notations D(Q) and V(M). Since the quasi-derivatives depends on Q, we sometimes write  $y_Q^{[r]}$  instead of  $y^{[r]}$ , r = 1, 2, ..., n.

**Remark 2.1.** If  $Q \in Z_n(J)$  has the format

$$q_{r,r+1} = 1, \qquad r = 1, 2, \dots, n-1, q_{r,s} = 0, \qquad 1 \le r \le n-1, \ s \ne r+1,$$
(2.1)

then  $M_Q$  will reduce to an ordinary differential expression M with  $y^{[r]} = y^{(r)}$ , r = 1, 2, ..., n - 1, the quasi-derivatives and ordinary derivatives are equal for r = 1, 2, ..., n - 1, when  $y \in D(Q)$ , and moreover

$$M_Q y = i^n y^{[n]} = i^n \left\{ y^{(n)} - \sum_{s=1}^n q_{n,s} y^{(s-1)} \right\}.$$
(2.2)

Hence, in this case,  $M_Q$  is merely an ordinary differential expression M, see (1.1), with  $p_n(x) = i^n$  on J. And conversely every such differential expression can be rewritten in the form of a quasi-differential expression.

In [11,17] the expression M is called a Lagrange symmetric (or just a symmetric) differential expression if the matrix Q satisfies

$$Q = -E_n^{-1} Q^* E_n, (2.3)$$

where  $E_n$  is the symplectic matrix of order *n* given by (1.5). However, (2.3) is not generally satisfied by the companion-type matrices (2.1).

For the Lagrange symmetric  $M_Q$ , the Green's formula has the form

$$\int_{[\alpha,\beta]} \{My\overline{z} - y\overline{Mz}\}dx = [y,z](\beta) - [y,z](\alpha) \qquad (y, z \in D(Q))$$

for any compact sub-interval  $[\alpha, \beta]$  of (a, b). Here the skew-symmetric sesquilinear form  $[\cdot, \cdot]$  maps  $D(Q) \times D(Q) \to \mathbb{C}$ . The explicit form of  $[\cdot, \cdot]$  is given by

$$[y,z](x) = i^n \sum_{r=1}^n (-1)^{r-1} y^{[n-r]}(x) \overline{z^{[r-1]}(x)} = (-1)^{k+1} Z^* E_n Y,$$
(2.4)

where Z(x), Y(x) are the column vector function

$$Y = (y^{[0]}(x) \ y^{[1]}(x) \ \cdots \ y^{[n-1]}(x))^T, \ Z = (z^{[0]}(x) \ z^{[1]}(x) \ \cdots \ z^{[n-1]}(x))^T, \ x \in [\alpha, \beta].$$

The expression  $w^{-1}M_Q = \lambda y$ ,  $\lambda \in \mathbb{R}$  defines or generates a linear operator *S*, once the domain D(S) is suitably  $S_{\min}$  with their respective domains  $D_{\max}$  and  $D_{\min}$ . In general, the minimal operator  $S_{\min}$  is a nonself-adjoint operator, otherwise  $S_{\min} = S_{\min}^* = S_{\max}$ . So if *S* is a self-adjoint operator on D(S), then  $S_{\min} \subset S = S^* \subset S_{\max}$ , and

$$\int_{J} \{My\overline{z} - y\overline{Mz}\}dx = 0$$
(2.5)

for all  $y, z \in D_{\max}$ .

The GKN (Glazeman–Krein–Naimark) Theorem [4] which characterizes all self-adjoint extensions of  $T_{Q,0}$  in H.

**Theorem 2.2** (GKN). Let d be the deficiency index of minimal operator  $S_{min}$ , then a linear submanifold  $D(S) \subset D_{max}$  is the domain of a self-adjoint extension S of  $S_{min}$  in  $H = L^2(J, w)$  if and only if there exist functions  $v_1, v_2, \ldots, v_d$  in  $D_{max}$  such that

(i)  $v_1, v_2, \dots, v_d$  are linearly independent modulo  $D_{min}$ , i.e. no nontrivial linear combination of  $v_1, v_2, \dots, v_d$  is in  $D_{min}$ .

(*ii*) 
$$[v_i, v_j](b) - [v_i, v_j](a) = 0, i, j = 1, 2, \cdots, d;$$

(*iii*)  $D(S) = \{y \in D_Q : [y, v_j](b) - [y, v_j](a) = 0, j = 1, 2, \dots, d\}.$ 

The GKN characterization depends on the maximal domain functions  $v_j$ , j = 1, ..., d. These functions depend on the coefficients of the differential equation and this dependence is implicit and complicated.

When both endpoints of *J* are regular, this dependence can be eliminated and an explicit characterization can be given in terms of two-point boundary conditions involving only solutions and their quasi-derivatives at the endpoints. This has the form:

$$D(S) = \{ y \in D_{\max} : AY(a) + BY(b) = 0 \},$$
(2.6)

where the complex  $n \times n$  matrices *A*, *B* satisfy

$$\operatorname{rank}(A:B) = n, \tag{2.7}$$

and

$$AE_n A^* = BE_n B^*. (2.8)$$

It is much more explicit than the GKN Theorem and it can lead to a canonical form for self-adjoint boundary conditions such as the well known form in the second order Sturm–Liouville case, see formulas (4.2.3), (4.2.4) and (4.2.7) in [20]. Through the long history of Sturm–Liouville problems, these canonical representations have led to a comprehensive understanding, both theoretically and numerically, of the dependence of the eigenvalues on the boundary conditions. In [10,15] canonical representations for regular problems of n = 4 are known. We will also go on with these canonical forms in our subsequent papers.

Notice that (2.4) and (2.8) hold for the constant matrix  $E_n$  satisfying  $E_n^{-1} = -E_n = E_n^*$ , this paper considers these forms for every general regular skew-diagonal constant matrix  $C = (c_{r,s})_{r,s=1}^n$  satisfying  $C^{-1} = -C = C^*$ . Thus we have the following definition.

**Definition 2.3.** Let  $Q \in Z_n(J)$ . Define

$$y_Q^{[0]} := y, \quad y \in V_0,$$
  

$$y_Q^{[r]} = q_{r,r+1}^{-1} \left\{ y_Q^{[r-1]'} - \sum_{s=1}^r q_{r,s} y_Q^{[s-1]} \right\}, \quad y \in V_r, \ r = 1, \dots, n,$$
(2.9)

where  $q_{n,n+1} := c_{n,1}$ .

We set

$$My = M_0 y = i^n y^{[n]}, (2.10)$$

with the domain  $D(M_Q)$ , which we usually write as D(Q). The expression  $M = M_Q$  is called the quasi-differential expression generated by or associated with Q. Suppose that

$$Q = Q^+ = -C_n^{-1}Q^*C_n, (2.11)$$

i.e.,

$$q_{r,s} = c_{r,n+1-r} \bar{q}_{n+1-s,n+1-r} c_{n+1-s,s}, \qquad (2.12)$$

then *Q* is said to be a *C*-symmetric matrix. In this case  $M_Q$  is called a *C*-symmetric quasidifferential expression. Note that  $Q^{++} = Q$ ,  $M_Q^{++} = M_Q$ , where  $M_Q^+ := M_{Q^+}$ , we call  $Q^+$  the *C*-adjoint matrix of *Q* and  $M_Q^+$  the *C*-adjoint expression of  $M_Q$ .

It is of special interest to note that if  $C_n = E_n$ , then

$$Q = -E_n^{-1}Q^*E_n$$

and the expression  $M = M_Q$  is reduced to the Lagrange symmetric differential expression.

**Remark 2.4.** What we really need to emphasize is that the constant matrix  $C_n$  is not only a skew-diagonal matrix satisfying

$$C_n^{-1} = -C_n = C_n^*, (2.13)$$

but plays a key role in the construction of symmetric quasi-differential expressions as well as in the self-adjoint domain characterization for *C*-symmetric differential operators. In addition, the *C*-symmetric condition on the matrix *Q* means that *Q* is invariant under the composition of the following three operators: "flips" about the secondary diagonal, conjugation, multiplying  $q_{r,s}$  by  $(-1)^{r+s+1}$  (i.e., changing the sign of  $q_{r,s}$  if r + s is even).

### **Remark 2.5.** The operator $M : D(Q) \longrightarrow L_{loc}(J)$ is linear.

From Definition 2.3 we have the symmetric condition

$$Q = -C_n^{-1}Q^*C_n.$$

Set

$$C_n = \begin{pmatrix} 0_{k \times k} & C_{12} \\ C_{21} & 0_{k \times k} \end{pmatrix}, \qquad C_{21}, C_{12} \in M_k(\mathbb{C}).$$

Then

$$C_{21} = -C_{12}^*, \ C_{12}^{-1} = C_{12}^*$$

i.e.,

$$C_n = \begin{pmatrix} 0_{k \times k} & C_{12} \\ -C_{12}^* & 0_{k \times k} \end{pmatrix}$$
(2.14)

and  $C_{12}$  is a skew-diagonal unitary matrix, that is,

$$c_{r,s}\overline{c}_{r,s} = 1, \quad \text{for } r+s = n+1, \ 1 \le r \le k,$$
  
$$c_{r,s} = 0, \quad \text{otherwise.}$$
(2.15)

Set

$$c_{r,n-r+1}=e^{i\theta_r}, \qquad -\pi<\theta_r\leq \pi, \ r=1,2,\ldots,k,$$

Thus  $C_n$  can be rewritten as

$$C_n = \text{skew-diagonal}(e^{i\theta_1}, e^{i\theta_2}, \dots, e^{i\theta_k}, -e^{-i\theta_k}, \dots, -e^{-i\theta_2}, -e^{-i\theta_1}).$$
(2.16)

Let

$$Q = \begin{pmatrix} Q_{11} & Q_{12} \\ Q_{21} & Q_{22} \end{pmatrix} \in Z_n(J),$$

 $Q_{ij} \in M_k(\mathbb{C})$ , i, j = 1, 2, then

$$Q^{+} = \begin{pmatrix} -C_{12}Q_{22}^{*}C_{12}^{*} & C_{12}Q_{12}^{*}C_{12} \\ C_{12}^{*}Q_{21}^{*}C_{12}^{*} & -C_{12}^{*}Q_{11}^{*}C_{12} \end{pmatrix}.$$

From  $Q = Q^+$ , we have the *C*-symmetric matrix

$$Q = \begin{pmatrix} Q_{11} & Q_{12} \\ Q_{21} & -C_{12}^* Q_{11}^* C_{12} \end{pmatrix},$$
(2.17)

where  $Q_{12} = C_{12}Q_{12}^*C_{12}$ ,  $Q_{21} = C_{12}^*Q_{21}^*C_{12}^*$ , i.e.,  $C_{12}^*Q_{12}$ ,  $C_{12}Q_{21}$  are symmetric matrices. By direct calculation, the C-symmetric matrices  $Q \in Z_n(J)$  have the form

$(q_{11})$	<i>q</i> <sub>12</sub>	0	• • •	•••	0		
<i>q</i> <sub>21</sub>	<i>q</i> 22	q <sub>23</sub>	•••	••••	:		(2.18)
	:	÷	÷	:	:	,	
$q_{n-2,1}$	<i>q</i> <sub>n-2,2</sub>	•••	•••	$-\overline{c}_{3,n-2}c_{2,n-1}\overline{q}_{23}$	0	ŕ	
$q_{n-1,1}$	$q_{n-1,2}$	•••	•••	$-\overline{q}_{22}$	$-\overline{c}_{2,n-1}c_{1,n}\overline{q}_{12}$		
$\langle q_{n,1}$	$\overline{c}_{1,n}\overline{c}_{2,n-1}\overline{q}_{n-1,1}$	•••	•••	$-\overline{c}_{1,n}c_{2,n-1}\overline{q}_{21}$	$-\overline{q}_{11}$ /		

where  $q_{n,1} = \overline{c}_{1,n}^2 \overline{q}_{n,1}$ ,  $q_{n-1,2} = \overline{c}_{2,n-1}^2 \overline{q}_{n-1,2}$ ,  $\cdots$ ,  $q_{k+1,k} = \overline{c}_{k,k+1}^2 \overline{q}_{k+1,k}$ ,  $q_{k,k+1} = c_{k,k+1}^2 \overline{q}_{k,k+1}$ . The self-adjoint operators *S* in the Hilbert space  $L^2(J, w)$  generated by the equation

$$My = M_Q y = \lambda w y$$
 on  $J$ ,

where Q has the form (2.18). Then S satisfy

$$S_{\min} \subset S = S^* \subset S_{\max}.$$
 (2.19)

So it is clear that these operators *S* differ from each other only by their domains. These domains D(S) are characterized by Theorem 1.1 and the proof is given in next section.

## 3 Characterization of self-adjoint domains

In this section, we prove the main results in this paper: characterization of self-adjoint domains for general regular even order *C*-symmetric quasi-differential operators. Our starting point for this characterization is the Lagrange identity which plays a critical important role in the characterization of self-adjoint domains.

To prove Lagrange identity, we use the following two lemmas.

**Lemma 3.1.** Let  $Q_n$ ,  $P_n \in Z_n(J)$ . Let F, G be  $n \times 1$  function matrices on J. If  $Y' = Q_nY + F$  and  $Z' = P_nZ + G$  and the constant matrix  $C_n \in M_n(\mathbb{C})$  satisfies

$$C_n^* = -C_n = C_n^{-1}.$$

Then

$$(Z^*C_nY)' = Z^*(P_n^*C_n + C_nQ_n)Y + Z^*C_nF + G^*C_nY,$$
(3.1)

where

$$Y = \left(y^{[0]} \ y^{[1]} \ \cdots \ y^{[n-1]}
ight)^T$$
,  $Z = \left(z^{[0]} \ z^{[1]} \ \cdots \ z^{[n-1]}
ight)^T$ 

Proof. From the differentiation of function matrix, we have

$$(Z^*C_nY)' = (Z^*)'C_nY + Z^*C'_nY + Z^*C_nY'$$
  
=  $(Z')^*C_nY + Z^*C_nY'$   
=  $(P_nZ + G)^*C_nY + Z^*C_n(Q_nY + F)$   
=  $(Z^*P_n^* + G^*)C_nY + Z^*C_nQ_nY + Z^*C_nF$   
=  $Z^*(P_n^*C_n + C_nQ_n)Y + G^*C_nY + Z^*C_nF.$ 

This completes the proof.

**Lemma 3.2.** Assume  $Q_n \in Z_n(J)$  and  $P_n = -C_n^{-1}Q_n^*C_n$ , then  $P_n \in Z_n(J)$  and if  $Y' = Q_nY + F$  and  $Z' = P_nZ + G$  on J, where F, G be  $n \times 1$  function matrices on J. Then

$$(Z^*C_nY)' = Z^*C_nF + G^*C_nY.$$
(3.2)

*Proof.* Let  $Q_n = (q_{r,s})_{r,s=1}^n \in Z_n(J)$  and  $P_n = (p_{r,s})_{r,s=1}^n = -C_n^{-1}Q_n^*C_n$ , then we have

$$p_{r,s} = \sum_{l=1}^{n} (\sum_{j=1}^{n} c_{r,j} \overline{q}_{l,j}) c_{l,s} = c_{r,n-r+1} \overline{q}_{n-s+1,n-r+1} c_{n-s+1,s}, \qquad r,s = 1, 2, \cdots, n$$

So for  $1 \le r \le n-1$ ,

$$p_{r,r+1} = c_{r,n-r+1}\overline{q}_{n-r,n-r+1}c_{n-r,r+1}$$

is invertible a.e. on *J*.

Since for  $2 \le r+1 < s \le n$ , r+1-s = (n-s-1)+1-(n-r+1) < 0,  $q_{n-s-1,n-r+1} = 0$ , then

$$p_{r,s} = c_{r,n-r+1}\overline{q}_{n-s+1,n-r+1}c_{n-s+1,s} = 0$$

This concludes that  $P_n \in Z_n(J)$ .

From  $C_n$  satisfy (2.13), and  $C_n P_n = -Q_n^* C_n = -(C_n^* Q_n)^*$ , we have  $C_n Q_n = -(C_n^* Q_n) = (C_n P_n)^* = -P_n^* C_n$ . Hence from (3.1) in Lemma 3.1, (3.2) is established.

We obtain a new general version of the Lagrange identity as follows.

**Theorem 3.3** (Lagrange identity). Let  $Q \in Z_n(J)$ , and  $P = -C_n^{-1}Q^*C_n$ ,  $C_n$  is defined by (2.14) (or (2.16)). Then  $P \in Z_n(J)$  and for any  $y \in D(Q)$  and  $z \in D(P)$ , we have

$$\overline{z}M_Q y - y\overline{M_P z} = [y, z]', \qquad [y, z] = \widetilde{Z}^* C_n \widetilde{Y}, \tag{3.3}$$

and

$$\widetilde{Z}^* C_n \widetilde{Y} = \sum_{r=0}^{n-1} c_{n-r,r+1} \overline{z_p^{[n-r-1]}} y_Q^{[r]} = \sum_{r=1}^k \left\{ c_{r,n-r+1} \overline{z_p^{[r-1]}} y_Q^{[n-r]} - \overline{c}_{r,n-r+1} \overline{z_p^{[n-r]}} y_Q^{[r-1]} \right\}, \quad (3.4)$$

where  $\widetilde{Y} = (y^{[0]} y^{[1]} \cdots y^{[n-1]})^T$ ,  $\widetilde{Z} = (z^{[0]} z^{[1]} \cdots z^{[n-1]})^T$  are generated by Q and P respectively. *Proof.* Set  $f = -\overline{c}_{1,n} y_Q^{[n]}$ ,  $g = -\overline{c}_{1,n} z_P^{[n]}$ , then we have

$$\widetilde{Y}' = Q\widetilde{Y} + F, \qquad \widetilde{Z}' = P\widetilde{Z} + G,$$

where

$$F = (0 \dots 0 f)^T$$
,  $G = (0 \dots 0 g)^T$ .

So from the Lemma 3.2, we have

$$\begin{aligned} (\widetilde{Z}^* C_n \widetilde{Y})' &= \widetilde{Z}_P^* C_n F + G^* C_n \widetilde{Y}_Q \\ &= c_{1n} \overline{z^{[0]}} f - \overline{c}_{1n} \overline{g} y^{[0]} \\ &= -\overline{z^{[0]}} y_Q^{[n]} + \overline{z}_P^{[n]} y^{[0]} \\ &= -(-i)^n \{ \overline{z^{[0]}} M_Q y - y^{[0]} \overline{M_P z} \} \end{aligned}$$

After integrating both sides of the above equation on any subinterval  $[\alpha, \beta] \subset J$ , we get

$$[y,z]^{\beta}_{\alpha} = \int_{\alpha}^{\beta} \overline{z} M_{Q} y dx - \int_{\alpha}^{\beta} y \overline{M_{P} z} dx = (-1)^{k+1} \widetilde{Z}^{*} C_{n} \widetilde{Y} \mid_{\alpha}^{\beta}.$$

Hence from the arbitrariness of  $\alpha$ ,  $\beta \in J$  we have

$$\overline{z}M_Q y - y\overline{M_P z} = [y, z]',$$

and

$$[y,z] = (-1)^{k+1} \widetilde{Z}^* C_n \widetilde{Y}.$$

By calculation (3.4) is also established. This completes the proof.

#### Remark 3.4.

(1) If in (2.16) for odd number in  $1 \le j \le k$ , we set  $\theta_j = \pi$  and for even number in  $1 \le j \le k$ ,  $\theta_j = 0$ , then  $C_n = E_n$  and we have the classical Lagrange identity in the references [12, 17, 21] below:

Assume  $Q \in Z_n(J)$ , and  $P = -E_n^{-1}Q^*E_n$ , then  $P \in Z_n(J)$  and for any  $y \in D(Q)$  and  $z \in D(P)$ , we have

$$\overline{z}M_Q y - y\overline{M_P z} = [y, z]',$$

and

$$[y,z] = (-1)^k \sum_{r=0}^{n-1} (-1)^{n+1-r} \overline{z^{[n-r-1]}} y^{[r]} = (-1)^{k+1} Z^* E_n Y.$$
(3.5)

(2) If we set  $\theta_j = 0$ , j = 1, 2, 3, ..., k in (2.16), then  $C_n = -F_n$ , and we have the another classical type of Lagrange identity in the Naimark book [14] as follows:

Let  $Q \in Z_n(J)$ , and  $P = -F_n^{-1}Q^*F_n$ , then  $P \in Z_n(J)$  and for any  $y \in D(Q)$  and  $z \in D(P)$ , we have

$$\overline{z}M_Q y - y\overline{M_P z} = [y, z]',$$

and

$$[y,z] = (-1)^k \sum_{r=1}^k \{ y^{[r-1]} \overline{z^{[n-r]}} - y^{[n-r]} \overline{z^{[r-1]}} \} = (-1)^k \widehat{Z}^* F_n \widehat{Y},$$
(3.6)

where

$$F_n = \begin{pmatrix} 0_{k \times k} & -J_k \\ J_k & 0_{k \times k} \end{pmatrix}, \qquad J_k = (\delta_{r,k+1-s})_{r,s=1}^k.$$
(3.7)

Theorem 1.1 characterizes all self-adjoint realizations of the operators generated by differential equation

$$My = \lambda wy$$
, on  $J = (a, b)$ ,  $-\infty < a < b < \infty$ , (3.8)

where *M* is *C*-symmetric quasi-differential expression.

Let (3.8) has the two-point boundary condition

$$A\widetilde{Y}(a) + B\widetilde{Y}(b) = 0, \qquad \widetilde{Y} = (y^{[0]} \ y^{[1]} \ \cdots \ y^{[n-1]})^T,$$
(3.9)

in the Hilbert space  $H = L^2(J, w)$ . Then according to Lemma 3.1, Lemma 3.2 and Theorem 3.3 we have the following proof of Theorem 1.1.

*Proof.* From Theorem 3.3 we have

$$\int_{a}^{b} \overline{z} M y dx - \int_{a}^{b} \overline{Mz} y dx = [y, z]_{a}^{b} = \widetilde{Z}^{*}(b) C_{n} \widetilde{Y}(b) - \widetilde{Z}^{*}(a) C_{n} \widetilde{Y}(a) = 0,$$

then

$$\widetilde{D}(S) = \left\{ y \in D_{\max} : A\widetilde{Y}(a) + B\widetilde{Y}(b) = 0 \right\}$$

is a self-adjoint domain if and only if

$$AC_nA^* = BC_nB^*.$$

Thus Theorem 1.1 is established.

**Remark 3.5.** If  $A, B \in M_n(\mathbb{R})$ , then the condition (1.7) reduces to det(A) = det(B). However, not all the real self-adjoint boundary conditions are generated in this way.

#### Remark 3.6.

(1) In [4,6] and [17,21] Everitt and Zettl et al. define a formally self-adjoint differential equation  $M_Q$  by

$$Q = Q^+ = -E_n^{-1}Q^*E_n, \qquad Q \in Z_n(J),$$

where constant  $n \times n$  matrix  $E_n$  is defined by (1.5).  $E_n$  is a skew-diagonal matrix satisfying  $E_n^{-1} = -E_n = E_n^*$ , i.e., it is a special case of  $C_n$ . Then *S* is a self-adjoint extension of minimal operator generated by  $M_Q$  if and only if

$$D(S) = \{ y \in D_{\max} : AY(a) + BY(b) = 0, A, B \in M_n(\mathbb{C}) \},$$
(3.10)

where

$$\operatorname{rank}(A:B) = n, \qquad AE_n A^* = BE_n B^*. \tag{3.11}$$

(2) In [14, Chapter V] the formally self-adjoint differential expressions are generated by the matrices

$$\widehat{Q} = -F_n^{-1}\widehat{Q}^*F_n, \ \widehat{Q} \in Z_n(J).$$
(3.12)

Notice that  $F_n$  is a constant skew-diagonal matrix and satisfy  $F_n^{-1} = -F_n = F_n^*$ , it is a special case of  $C_n$ . Let  $M = M_{\widehat{O}}$  is generated by (3.12), then the domain defined by

$$D(\widehat{S}) = \left\{ y \in D_{\max} : A\widehat{Y}(a) + B\widehat{Y}(b) = 0, \ A, \ B \in M_n(\mathbb{C}) \right\},$$
(3.13)

is a self-adjoint domain, i.e.,

$$\widehat{S}_{\min} \subset \widehat{S} = \widehat{S}^* \subset \widehat{S}_{\max}$$

if and only if

$$\operatorname{rank}(A:B) = n, \qquad AF_n A^* = BF_n B^*. \tag{3.14}$$

(3) Theorem 1.1 unifies and generalizes the statement of (1)–(2). Furthermore the different characterizations of self-adjoint domains among (1.6), (3.10) and (3.13) are caused by the use of different definition of the quasi-derivatives. In fact, the self-adjoint characterization of *C*-symmetric differential operators are generalization of previously known characterizations [4–6, 8, 13, 14, 17, 18, 21].

**Remark 3.7.** In general, the matrices which determine symmetric differential expressions are not unique, two different matrices may determine the same quasi-symmetric differential expressions. Frentzen [9] extended the Shin–Zettl set of matrices  $Z_n(J)$  and Everitt and Race [6] studied the relationship between the matrices in this extended set which generate the same symmetric expressions. Theorem 1.1 shows that, given any constant skew-symmetric matrix *C* satisfying  $C^{-1} = -C = C^*,$ 

the matrix

$$Q = -C^{-1}Q^*C$$

is C-symmetric. And, remarkably, this same matrix C determines all self-adjoint boundary conditions, i.e.,  $S_{\min}$  and  $S_{\max}$  denote the minimal and maximal operators determined by Q, respectively, then all self-adjoint extensions of  $S_{\min}$  (or equivalently self-adjoint restrictions of  $S_{\max}$ ), i.e. all operators S in  $L^2(J, w)$  satisfying

$$S_{\min} \subset S = S^* \subset S_{\max}$$

are determined by the boundary conditions (1.6), (1.7). In addition to the examples  $C = E_n$ ,  $C = F_n$ , the general generator of the symplectic group

$$C = \left(\begin{array}{cc} 0 & -I \\ I & 0 \end{array}\right),$$

where *I* is the identity matrix of order *k*, is another example. See also the example

$$C = \begin{pmatrix} 0 & 0 & 0 & e^{i\theta_1} \\ 0 & 0 & e^{i\theta_2} & 0 \\ 0 & -e^{-i\theta_2} & 0 & 0 \\ -e^{-i\theta_1} & 0 & 0 & 0 \end{pmatrix}$$

below.

### 4 Examples

In order to get a better understanding about our main results in this section we give some simple examples for the special case n = 2, 4, 6.

**Example 4.1.** Let  $C_2 = \begin{pmatrix} 0 & c_{12} \\ c_{21} & 0 \end{pmatrix} \in M_2(\mathbb{C})$  satisfy

$$C_2^{-1} = -C_2 = C_2^*,$$

then

$$C_2 = \begin{pmatrix} 0 & c_{12} \\ -\overline{c}_{12} & 0 \end{pmatrix} = \begin{pmatrix} 0 & e^{i\theta} \\ -e^{-i\theta} & 0 \end{pmatrix}, \quad -\pi < \theta \le \pi.$$
(4.1)

Now, let  $Q \in Z_2(J)$  satisfy

$$Q = Q^+ := -C_2^{-1}Q^*C_2.$$
(4.2)

Then

$$Q^+ = \begin{pmatrix} -\overline{q}_{22} & c_{12}^2 \overline{q}_{12} \\ \overline{c}_{12}^2 \overline{q}_{21} & -\overline{q}_{11} \end{pmatrix},$$

and we have a second order C-symmetric matrix

$$Q = \begin{pmatrix} q_{11} & q_{12} \\ q_{21} & -\bar{q}_{11} \end{pmatrix},$$
 (4.3)

where  $q_{12} = c_{12}^2 \bar{q}_{12}$ ,  $q_{21} = \bar{c}_{12}^2 \bar{q}_{21}$ . The *C*-symmetric quasi-derivatives generated by (4.3) are:

$$y^{[0]} = y, \ y^{[1]} = \frac{1}{q_{12}} \{ (y^{[0]})' - q_{11}y \},$$

$$y^{[2]} = -c_{12} \{ (y^{[1]})' - q_{21}y^{[0]} + \overline{q}_{11}y^{[1]} \} = -e^{i\theta} \{ (y^{[1]})' - q_{21}y^{[0]} + \overline{q}_{11}y^{[1]} \},$$
(4.4)

and  $M = M_Q$  is given by

$$My = i^2 y^{[2]} = e^{i\theta} \left\{ \left[ \frac{1}{q_{12}} (y' - q_{11}y) \right]' - q_{21}y + \frac{\overline{q}_{11}}{q_{12}} (y' - q_{11}y) \right\}.$$
(4.5)

Let  $Q \in Z_2(J)$ ,  $P = -C_2^{-1}Q^*C_2$ , then we obtain a new version of Lagrange identity for the second order case:

$$\overline{z}M_Q y - y\overline{M_P z} = [y, z]', \qquad y \in D(Q), \ z \in D(P),$$
(4.6)

where

$$[y, z] = Z^* C_2 Y = e^{i\theta} \overline{z^{[1]}} y^{[0]} - e^{-i\theta} \overline{z^{[0]}} y^{[1]}, \qquad -\pi < \theta \le \pi.$$

Let

$$My = \lambda wy$$
, on  $J = (a, b)$ , (4.7)

in Hilbert space  $L^{2}(J, w)$ , where *M* is defined by (4.5), it has the following boundary conditions

$$\widetilde{A}\left(y^{[0]}(a), y^{[1]}(a)\right)^T + \widetilde{B}\left(y^{[0]}(b), y^{[1]}(b)\right)^T = 0, \qquad \widetilde{A}, \widetilde{B} \in M_2(\mathbb{C}),$$

where  $y^{[0]}$ ,  $y^{[1]}$  are defined by (4.4).

Define

$$D(S) = \left\{ y \in D_{\max} : \widetilde{A}Y(a) + \widetilde{B}Y(b) = 0, \ Y = \left(\begin{array}{c} y^{[0]} \\ y^{[1]} \end{array}\right) \right\},\tag{4.8}$$

and *S* is generated by (4.7) satisfying  $S_{\min} \subset S \subset S_{\max}$ , then D(S) is a self-adjoint domain for the second-order C-symmetric differential operators if and only if

$$\widetilde{A}C_{2}\widetilde{A}^{*} = \widetilde{B}C_{2}\widetilde{B}^{*}, \quad \operatorname{rank}(\widetilde{A}:\widetilde{B}) = 2.$$
 (4.9)

**Remark 4.2.** If  $\theta = \pi$ , i.e.,  $C_2 = E_2$ , then (4.3) is reduced to the Lagrange symmetric matrix

$$Q = \begin{pmatrix} q_{11} & r_1 \\ r_2 & -\overline{q}_{11} \end{pmatrix}, \tag{4.10}$$

where  $r_1, r_2$  are real-valued functions.  $S_{\min}$ ,  $S_{\max}$  are determined by (4.10) and S is a selfadjoint extension of  $S_{\min}$  if and only if the domain

$$\widetilde{D}(S) = \left\{ y \in D_{\max} : \widetilde{A}\widetilde{Y}(a) + \widetilde{B}\widetilde{Y}(b) = 0, \ \widetilde{A}, \ \widetilde{B} \in M_2(\mathbb{C}) \right\}$$
(4.11)

satisfy

$$\operatorname{rank}(\widetilde{A}:\widetilde{B}) = 2$$
, and  $\widetilde{A}E_2\widetilde{A}^* = \widetilde{B}E_2\widetilde{B}^*$ , (4.12)

i.e., the well-known characterization (4.12) is a special case of (4.9).

**Example 4.3.** Let  $Q \in Z_4(J)$  be *C*-symmetric, then from Definition 2.3 we get

$$Q = Q^+ = -C_4^{-1}Q^*C_4, (4.13)$$

where  $C_4$  has the form

$$C_4 = \begin{pmatrix} 0 & 0 & 0 & c_{14} \\ 0 & 0 & c_{23} & 0 \\ 0 & -\overline{c}_{23} & 0 & 0 \\ -\overline{c}_{14} & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & e^{i\theta_1} \\ 0 & 0 & e^{i\theta_2} & 0 \\ 0 & -e^{-i\theta_2} & 0 & 0 \\ -e^{-i\theta_1} & 0 & 0 & 0 \end{pmatrix}$$

From (4.13) we have

$$Q^{+} = \begin{pmatrix} -\overline{q}_{44} & -c_{14}\overline{c}_{23}\overline{q}_{34} & 0 & 0\\ -\overline{c}_{14}c_{23}\overline{q}_{43} & -\overline{q}_{33} & c_{23}^{2}\overline{q}_{23} & 0\\ \overline{c}_{14}\overline{c}_{23}\overline{q}_{42} & \overline{c}_{23}^{2}\overline{q}_{32} & -\overline{q}_{22} & -c_{14}\overline{c}_{23}\overline{q}_{12}\\ \overline{c}_{14}^{2}\overline{q}_{41} & \overline{c}_{14}\overline{c}_{23}\overline{q}_{31} & -\overline{c}_{14}c_{23}\overline{q}_{21} & -\overline{q}_{11} \end{pmatrix},$$

and it follows that

$$Q = \begin{pmatrix} q_{11} & q_{12} & 0 & 0\\ q_{21} & q_{22} & q_{23} & 0\\ q_{31} & q_{32} & -\overline{q}_{22} & -c_{14}\overline{c}_{23}\overline{q}_{12}\\ q_{41} & \overline{c}_{14}\overline{c}_{23}\overline{q}_{31} & -\overline{c}_{14}c_{23}\overline{q}_{21} & -\overline{q}_{11} \end{pmatrix},$$
(4.14)

where  $q_{23} = c_{23}^2 \bar{q}_{23}$ ,  $q_{32} = \bar{c}_{23}^2 \bar{q}_{32}$ ,  $q_{41} = \bar{c}_{14}^2 \bar{q}_{41}$ .

Thus the quasi-derivatives associated with the C-symmetric matrix Q are

$$y^{[0]} = y, \ y^{[1]} = \frac{1}{q_{12}} \{ (y^{[0]})' - q_{11}y \},$$

$$y^{[2]} = \frac{1}{q_{23}} \{ (y^{[1]})' - q_{21}y^{[0]} - q_{22}y^{[1]} \},$$

$$y^{[3]} = -\frac{1}{c_{14}\bar{c}_{23}\bar{q}_{12}} \{ (y^{[2]})' - q_{31}y^{[0]} - q_{32}y^{[1]} + \bar{q}_{22}y^{[2]} \},$$

$$y^{[4]} = -c_{14} \{ (y^{[3]})' - q_{41}y^{[0]} - \bar{c}_{14}\bar{c}_{23}\bar{q}_{31}y^{[1]} + \bar{c}_{14}c_{23}\bar{q}_{21}y^{[2]} + \bar{q}_{11}y^{[3]} \}_{14} \}.$$
(4.15)

So the fourth order C-symmetric quasi-differential expressions be given by

$$My = i^{4}y^{[4]} = -c_{14}\{(y^{[3]})' - q_{41}y^{[0]} - \overline{c}_{14}\overline{c}_{23}\overline{q}_{31}y^{[1]} + \overline{c}_{14}c_{23}\overline{q}_{21}y^{[2]} + \overline{q}_{11}y^{[3]}\}.$$
(4.16)

Set

$$My = \lambda wy, \tag{4.17}$$

where *M* is defined by (4.17). Then all self-adjoint extension *S* of minimal operator generated by (4.17) are characterized as follows:

$$\widetilde{D}(S) = \left\{ y \in D_{\max} : A\widetilde{Y}(a) + B\widetilde{Y}(b) = 0 \right\},$$
(4.18)

where *A*, *B* satisfy

$$\operatorname{rank}(A:B) = 4, \quad AC_4A^* = BC_4B^*, \quad A, B \in M_4(\mathbb{C}),$$
(4.19)

and the quasi-derivatives in  $\tilde{\gamma}$  are defined by (4.15).

**Remark 4.4.** Note that  $q_{11} = q_{21} = q_{22} = q_{31} = 0$  and  $q_{12} = 1$  in (4.16) yields

$$My = c_{23}[(q_{23}^{-1}y'')' - q_{32}y']' + c_{14}q_{41}y.$$
(4.20)

Moreover,

(1) if  $\theta_1 = \pi$ ,  $\theta_2 = 0$ , i.e.,  $c_{14} = -1$ ,  $c_{23} = 1$  in (4.20), then it is reduced to the real Lagrange symmetric differential expression [21]

$$My = [(q_{23}^{-1}y'')' - q_{32}y']' - q_{41}y,$$
(4.21)

where  $q_{23}^{-1}$ ,  $q_{32}$ ,  $q_{41}$  are reals.

For this Lagrange symmetric differential expression we have characterization of self-adjoint domains

$$D(S) = \left\{ y \in D_{\max} : AY(a) + BY(b) = 0, \ Y = \left( \begin{array}{c} y \\ y' \\ \frac{1}{q_{23}}y'' \\ (\frac{1}{q_{23}}y'')' - q_{32}y' \end{array} \right) \right\},$$
(4.22)

where

$$\operatorname{rank}(A:B) = 4, \ AE_4A^* = BE_4B^*, \ A, \ B \in M_4(\mathbb{C}).$$

(2) If  $\theta_1 = \theta_2 = 0$  in (4.20), then it is reduced to the modified Naimark form [14]

$$My = [(q_{23}^{-1}y'')' - q_{32}y']' + q_{41}y,$$
(4.23)

where  $q_{23}^{-1}$ ,  $q_{32}$ ,  $q_{41}$  are reals.

For this differential expression (4.23) we have the characterization of self-adjoint domains

$$\widehat{D}(S) = \left\{ y \in D_{\max} : A\widehat{Y}(a) + B\widehat{Y}(b) = 0, \ \widehat{Y} = \left( \begin{array}{c} y \\ y' \\ \frac{1}{q_{23}}y'' \\ q_{32}y' - \left(\frac{1}{q_{23}}y''\right)' \end{array} \right) \right\},$$
(4.24)

where

$$\operatorname{rank}(A:B) = 4$$
,  $AF_4A^* = BF_4B^*$ ,  $A, B \in M_4(\mathbb{C})$ .

**Example 4.5.** n = 6. Let  $Q = (q_{r,s})_{r,s=1}^6 \in Z_6(J)$  is C-symmetric, where

$$C = C_6 = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & c_{16} \\ 0 & 0 & 0 & c_{25} & 0 \\ 0 & 0 & -\overline{c}_{34} & 0 & 0 \\ 0 & -\overline{c}_{25} & 0 & 0 & 0 \\ -\overline{c}_{16} & 0 & 0 & 0 & 0 \end{pmatrix}.$$
 (4.25)

Then we obtain

$$Q = \begin{pmatrix} q_{11} & q_{12} & 0 & 0 & 0 & 0 \\ q_{21} & q_{22} & q_{23} & 0 & 0 & 0 \\ q_{31} & q_{32} & q_{33} & q_{34} & 0 & 0 \\ q_{41} & q_{42} & q_{43} & -\overline{q}_{33} & -c_{25}\overline{c}_{34}\overline{q}_{23} & 0 \\ q_{51} & q_{52} & \overline{c}_{25}\overline{c}_{34}\overline{q}_{42} & -c_{34}\overline{c}_{25}\overline{q}_{32} & -\overline{q}_{22} & -c_{16}\overline{c}_{25}\overline{q}_{12} \\ q_{61} & \overline{c}_{16}\overline{c}_{25}\overline{q}_{51} & \overline{c}_{16}\overline{c}_{34}\overline{q}_{41} & -c_{34}\overline{c}_{16}\overline{q}_{31} & -c_{25}\overline{c}_{16}\overline{q}_{21} & -\overline{q}_{11} \end{pmatrix},$$
(4.26)

where  $q_{34} = c_{34}^2 \bar{q}_{34}$ ,  $q_{43} = \bar{c}_{34}^2 \bar{q}_{43}$ ,  $q_{52} = \bar{c}_{25}^2 \bar{q}_{52}$ ,  $q_{61} = \bar{c}_{16}^2 \bar{q}_{61}$ . Then we have the *C*-symmetric quasi-derivatives below:

$$\begin{split} y^{[0]} &= y, \ y^{[1]} = \frac{1}{q_{12}} \{ (y^{[0]})' - q_{11}y \}, \\ y^{[2]} &= \frac{1}{q_{23}} \{ (y^{[1]})' - q_{21}y^{[0]} - q_{22}y^{[1]} \}, \\ y^{[3]} &= \frac{1}{q_{34}} \{ (y^{[2]})' - q_{31}y^{[0]} - q_{32}y^{[1]} - q_{33}y^{[2]} \}, \\ y^{[4]} &= -\frac{1}{c_{25}\overline{c}_{34}\overline{q}_{23}} \{ (y^{[3]})' - q_{41}y^{[0]} - q_{42}y^{[1]} - q_{43}y^{[2]} + \overline{q}_{33}y^{[3]} \}, \\ y^{[5]} &= -\frac{1}{c_{16}\overline{c}_{25}\overline{q}} \frac{1}{12} \{ (y^{[4]})' - q_{51}y^{[0]} - q_{52}y^{[1]} - \overline{c}_{25}\overline{c}_{34}\overline{q}_{42}y^{[2]} + c_{34}\overline{c}_{25}\overline{q}} \frac{1}{32}y^{[3]} + \overline{q}_{22}y^{[4]} \}, \end{split}$$

and  $My = M_Q y$  is given by

$$My = c_{16}(y^{[5]})' - c_{16}q_{61}y - \bar{c}_{25}\bar{q}_{51}y^{[1]} - \bar{c}_{34}\bar{q}_{41}y^{[2]} + c_{34}\bar{q}_{31}y^{[3]} + c_{25}\bar{q}_{21}y^{[4]} + \bar{q}_{11}y^{[5]}.$$
 (4.28)

Set

$$My = \lambda wy, \tag{4.29}$$

where M is defined by (4.28). Then all self-adjoint extension S of minimal operator generated by (4.29) are characterized as follows:

$$\widetilde{D}(S) = \left\{ y \in D_{\max} : A\widetilde{Y}(a) + B\widetilde{Y}(b) = 0, \ A, \ B \in M_6(\mathbb{C}) \right\},$$
(4.30)

where *A*, *B* satisfy

$$rank(A:B) = 6, AC_6A^* = BC_6B^*,$$

and  $\widetilde{Y}$  are defined by (4.27).

Note that  $q_{11} = q_{21} = q_{22} = q_{31} = q_{32} = q_{33} = q_{41} = q_{42} = q_{51} = 0$  and  $q_{12} = q_{23} = 1$  in (4.28) yields

$$My = \{c_{34}[(q_{34}^{-1}y''')' - q_{43}y'']' + c_{25}q_{52}y'\}' - c_{16}q_{61}y.$$
(4.31)

Furthermore we observe that  $\theta_1 = \theta_3 = \pi$  and  $\theta_2 = 0$  in (4.31) yields the Lagrange symmetric expression

$$My = \{ [(q_{34}^{-1}y''')' - q_{43}y'']' - q_{52}y'\}' - q_{61}y,$$
(4.32)

where  $q_{34}^{-1}$ ,  $q_{43}$ ,  $q_{52}$ ,  $q_{61}$  are real-valued functions. For this Lagrange symmetric differential expression we have characterization of self-adjoint domains:

$$D(S) = \{ y \in D_{\max} : AY(a) + BY(b) = 0, A, B \in M_6(\mathbb{C}) \},$$
(4.33)

where

$$\operatorname{rank}(A:B) = 6, \quad AE_6A^* = BE_6B^*, \quad Y = \begin{pmatrix} y \\ y' \\ y'' \\ \frac{1}{q_{34}}y''' \\ (\frac{1}{q_{34}}y''')' - q_{43}y'' \\ \{[q_{43}y'' - (\frac{1}{q_{34}}y''')']' - q_{52}y'\} \end{pmatrix}.$$

If  $\theta_1 = \theta_2 = \theta_3 = 0$  in (4.31), then it is reduced to the real modified Naimark form

$$My = \{ [(-q_{34}^{-1}y''')' + q_{43}y'']' - q_{52}y'\}' + q_{61}y,$$
(4.34)

where  $q_{34}^{-1}$ ,  $q_{43}$ ,  $q_{52}$ ,  $q_{61}$  are real-valued functions.

For this special expressions (4.34), we have the characterization of self-adjoint domains:

$$\widehat{D}(S) = \left\{ y \in D_{\max} : A\widehat{Y}(a) + B\widehat{Y}(b) = 0, \ A, \ B \in M_6(\mathbb{C}) \right\},\tag{4.35}$$

where

$$\operatorname{rank}(A:B) = 6, \qquad AF_6A^* = BF_6B^*, \qquad \widehat{Y} = \begin{pmatrix} y \\ y' \\ y'' \\ \frac{1}{q_{34}}y''' \\ q_{43}y'' - (\frac{1}{q_{34}}y''')' \\ q_{52}y' - [q_{43}y'' - (\frac{1}{q_{34}}y''')']' \end{pmatrix}.$$

**Remark 4.6.** (1) For n = 4 and n = 6, (4.21) and (4.32) are generated by the following matrix form [21]:

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & q_{23} & 0 \\ 0 & q_{32} & 0 & 1 \\ q_{41} & 0 & 0 & 0 \end{pmatrix}, \qquad \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & q_{34} & 0 & 0 \\ 0 & 0 & q_{43} & 0 & 1 & 0 \\ 0 & q_{52} & 0 & 0 & 0 & 1 \\ q_{61} & 0 & 0 & 0 & 0 & 0 \end{pmatrix},$$

respectively. However, (4.23) and (4.34) are generated by the G-N type matrix function [14]:

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & q_{23} & 0 \\ 0 & q_{32} & 0 & -1 \\ q_{41} & 0 & 0 & 0 \end{pmatrix}, \qquad \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & q_{34} & 0 & 0 \\ 0 & 0 & q_{43} & 0 & -1 & 0 \\ 0 & q_{52} & 0 & 0 & 0 & -1 \\ q_{51} & 0 & 0 & 0 & 0 & 0 \end{pmatrix},$$

`

respectively.

(2) For n = 4, (4.18) contains the characterization (4.22) and (4.24). For n = 6, (4.30) contains the characterization (4.33) and (4.35).

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