

Location of solutions for quasi-linear elliptic equations with general gradient dependence

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Abstract. Existence and location of solutions to a Dirichlet problem driven by (p,q)-Laplacian and containing a (convection) term fully depending on the solution and its gradient are established through the method of subsolution-supersolution. Here we substantially improve the growth condition used in preceding works. The abstract theorem is applied to get a new result for existence of positive solutions with a priori estimates.

Keywords: quasi-linear elliptic equations, gradient dependence, (p,q)-Laplacian, subsolution-supersolution, positive solution.

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1 Introduction

The aim of this paper is to study the following nonlinear elliptic boundary value problem

$$\begin{cases} -\Delta_p u - \mu \Delta_q u = f(x, u, \nabla u) & \text{ in } \Omega\\ u = 0 & \text{ on } \partial \Omega \end{cases}$$
 (P_µ)

by means of the method of subsolution-supersolution on a bounded domain $\Omega \subset \mathbb{R}^N$. For regularity reasons we assume that the boundary $\partial \Omega$ is of class C^2 . In order to simplify the presentation we suppose that $N \geq 3$. The lower dimensional cases N = 1, 2 are simpler and can be treated by slightly modified arguments.

In the statement of problem (P_{μ}), there are given real numbers $\mu \ge 0$ and 1 < q < p. The leading differential operator in (P_{μ}) is described by the *p*-Laplacian and *q*-Laplacian, namely $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2}\nabla u)$ and $\Delta_q u = \operatorname{div}(|\nabla u|^{q-2}\nabla u)$. Hence if $\mu = 0$, problem (P_{μ}) is governed by the *p*-Laplacian Δ_p , whereas if $\mu = 1$, it is driven by the (p, q)-Laplacian $\Delta_p + \Delta_q$, which is an essentially different type of nonlinear operator.

The right-hand side of the elliptic equation in (P_{μ}) is expressed through a Carathéodory function $f : \Omega \times \mathbb{R} \times \mathbb{R}^N \to \mathbb{R}$, i.e., $f(\cdot, s, \xi)$ is measurable for all $(s, \xi) \in \mathbb{R} \times \mathbb{R}^N$ and $f(x, \cdot, \cdot)$

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is continuous for a.e. $x \in \Omega$. We emphasize that the term $f(x, u, \nabla u)$ (often called convection term) depends not only on the solution u, but also on its gradient ∇u . This fact produces serious difficulties of treatment mainly because the convection term generally prevents to have a variational structure for problem (P_{μ}), so the variational methods are not applicable.

Existence results for problem (P_{μ}) or for systems of equations of this form have been obtained in [1,4–7,10–12]. Location of solutions through the method of subsolution-supersolution in the case of systems involving *p*-Laplacian operators has been investigated in [3]. Here, in the case of an equation possibly involving the (p,q)-Laplacian, we focus on the location of solutions within ordered intervals determined by pairs of subsolution-supersolution of problem (P_{μ}) under a much more general growth condition on the right-hand side $f(x, u, \nabla u)$ (see hypothesis (H) below). We also provide a new result guaranteeing the existence of positive solutions to (P_{μ}).

The functional space associated to problem (P_{μ}) is the Sobolev space $W_0^{1,p}(\Omega)$ endowed with the norm

$$||u|| = \left(\int_{\Omega} |\nabla u|^p \, dx\right)^{\frac{1}{p}}.$$

Its dual space is $W^{-1,p'}(\Omega)$, with p' = p/(p-1), and the corresponding duality pairing is denoted $\langle \cdot, \cdot \rangle$.

A solution of problem (P_{μ}) is understood in the weak sense, that is any function $u \in W_0^{1,p}(\Omega)$ such that

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla v \, dx + \mu \int_{\Omega} |\nabla u|^{q-2} \nabla u \nabla v \, dx = \int_{\Omega} f(x, u, \nabla u) v \, dx$$

for all $v \in W_0^{1,p}(\Omega)$.

Our study of problem (P_{μ}) is based on the method of subsolution-supersolution. We refer to [2, 9] for details related to this method. We recall that a function $\overline{u} \in W^{1,p}(\Omega)$ is a *supersolution* for problem (P_{μ}) if $\overline{u} \ge 0$ on $\partial\Omega$ and

$$\int_{\Omega} \left(|\nabla \overline{u}|^{p-2} \nabla \overline{u} + \mu |\nabla \overline{u}|^{q-2} \nabla \overline{u} \right) \nabla v \, dx \ge \int_{\Omega} f(x, \overline{u}, \nabla \overline{u}) v \, dx$$

for all $v \in W_0^{1,p}(\Omega)$, $v \ge 0$ a.e. in Ω . A function $\underline{u} \in W^{1,p}(\Omega)$ is a *subsolution* for problem (P_{μ}) if $\underline{u} \le 0$ on $\partial \Omega$ and

$$\int_{\Omega} \left(|\nabla \underline{u}|^{p-2} \nabla \underline{u} + \mu |\nabla \underline{u}|^{q-2} \nabla \underline{u} \right) \nabla v \, dx \le \int_{\Omega} f(x, \underline{u}, \nabla \underline{u}) v \, dx$$

for all $v \in W_0^{1,p}(\Omega)$, $v \ge 0$ a.e. in Ω .

In the sequel we suppose that N > p (if $N \le p$ the treatment is easier). Then the critical Sobolev exponent is $p^* = \frac{Np}{N-p}$.

Given a subsolution $\underline{u} \in W^{1,p}(\Omega)$ and a supersolution $\overline{u} \in W^{1,p}(\Omega)$ for problem (P_{μ}) with $\underline{u} \leq \overline{u}$ a.e. in Ω , we assume that $f : \Omega \times \mathbb{R} \times \mathbb{R}^N \to \mathbb{R}$ satisfies the growth condition:

(*H*) There exist a function $\sigma \in L^{\gamma'}(\Omega)$ for $\gamma' = \frac{\gamma}{\gamma-1}$ with $\gamma \in (1, p^*)$ and constants a > 0 and $\beta \in [0, \frac{p}{(p^*)'})$ such that

$$|f(x,s,\xi)| \le \sigma(x) + a|\xi|^{\beta}$$
 for a.e. $x \in \Omega$, all $s \in [\underline{u}(x), \overline{u}(x)], \xi \in \mathbb{R}^N$.

Notice that, under assumption (*H*), the integrals in the definitions of the subsolution \underline{u} and the supersolution \overline{u} exist.

Our main goal is to obtain a solution $u \in W_0^{1,p}(\Omega)$ of problem (P_{μ}) with the location property $\underline{u} \leq u \leq \overline{u}$ a.e. in Ω . This is done through an auxiliary truncated problem termed $(T_{\lambda,\mu})$ depending on a positive parameter λ (for any fixed $\mu \geq 0$). It is shown in Theorem 2.1 that whenever $\lambda > 0$ is sufficiently large, problem $(T_{\lambda,\mu})$ is solvable. The next principal step is performed in Theorem 3.1, where it is proven by adequate comparison that every solution $u \in$ $W_0^{1,p}(\Omega)$ of problem $(T_{\lambda,\mu})$ is within the ordered interval $[\underline{u}, \overline{u}]$ determined by the subsolutionsupersolution, that is $\underline{u} \leq u \leq \overline{u}$ a.e. in Ω . Then the expression of the equation in $(T_{\lambda,\mu})$ enables us to conclude that u is actually a solution of the original problem (P_{μ}) verifying the location property $\underline{u} \leq u \leq \overline{u}$ a.e. in Ω . We emphasize that Theorem 2.1 improves all the growth conditions for the convection term $f(x, u, \nabla u)$ considered in the preceding works. Finally, in Theorem 4.1, the procedure to construct solutions located in ordered intervals $[\underline{u}, \overline{u}]$ is conducted to guarantee the existence of a positive solution to problem (P_{μ}) . It is also worth mentioning that this result provides a priori estimates for the obtained solution.

2 Auxiliary truncated problem

This section is devoted to the study of an auxiliary problem related to problem (P_{μ}) . We start with some notation. The Euclidean norm on \mathbb{R}^N is denoted by $|\cdot|$ and the Lebesgue measure on \mathbb{R}^N by $|\cdot|_N$. For every $r \in \mathbb{R}$, we set $r^+ = \max\{r, 0\}$, $r^- = \max\{-r, 0\}$, and if r > 1, $r' = \frac{r}{r-1}$.

Let \underline{u} and \overline{u} be a subsolution and a supersolution for problem (P_{μ}) , respectively, with $\underline{u} \leq \overline{u}$ a.e. in Ω such that hypothesis (H) is satisfied. We consider the truncation operator $T: W_0^{1,p}(\Omega) \to W_0^{1,p}(\Omega)$ defined by

$$Tu(x) = \begin{cases} \overline{u}(x), & u(x) > \overline{u}(x), \\ u(x), & \underline{u}(x) \le u(x) \le \overline{u}(x), \\ \underline{u}(x), & u(x) < \underline{u}(x), \end{cases}$$
(2.1)

which is known to be continuous and bounded.

By means of the constant β in hypothesis (*H*) we introduce the cut-off function $\pi : \Omega \times \mathbb{R} \to \mathbb{R}$ defined by

$$\pi(x,s) = \begin{cases} (s - \overline{u}(x))^{\frac{\beta}{p-\beta}}, & s > \overline{u}(x), \\ 0, & \underline{u}(x) \le s \le \overline{u}(x), \\ -(\underline{u}(x) - s)^{\frac{\beta}{p-\beta}}, & s < \underline{u}(x). \end{cases}$$
(2.2)

We observe that π satisfies the growth condition

$$|\pi(x,s)| \le c|s|^{\frac{\beta}{p-\beta}} + \varrho(x) \quad \text{for a.e. } x \in \Omega, \text{ all } s \in \mathbb{R},$$
(2.3)

with a constant c > 0 and a function $\varrho \in L^{\frac{p}{\beta}}(\Omega)$. Here it is used that $\underline{u}, \overline{u} \in W^{1,p}(\Omega) \subset L^{p^*}(\Omega)$ and $\beta < \frac{p}{(p^*)'}$. By (2.3), the fact that $\beta < \frac{p}{(p^*)'}$ and Rellich–Kondrachov compactness embedding theorem, it follows that the Nemytskij operator $\Pi : W_0^{1,p}(\Omega) \to W^{-1,p'}(\Omega)$ given

by $\Pi(u) = \pi(\cdot, u(\cdot))$ is completely continuous. Moreover, (2.2) leads to

$$\int_{\Omega} \pi(x, u(x))u(x) \, dx \ge r_1 \|u\|_{L^{\frac{p}{p-\beta}}(\Omega)}^{\frac{p}{p-\beta}} - r_2 \quad \text{for all } u \in W_0^{1,p}(\Omega), \tag{2.4}$$

with positive constants r_1 and r_2 .

Next we consider the Nemytskij operator $N : [\underline{u}, \overline{u}] \to W^{-1,p'}(\Omega)$ determined by the function f in (P_u) , that is

$$N(u)(x) = f(x, u(x), \nabla u(x)),$$

which is well defined by virtue of hypothesis (H).

With the data above, for any $\lambda > 0$ let the auxiliary truncated problem associated to (P_{μ}) be formulated as follows

$$-\Delta_p u - \mu \Delta_q u + \lambda \Pi(u) = N(Tu). \tag{T}_{\lambda,\mu}$$

For problem $(T_{\lambda,\mu})$ we have the following result.

Theorem 2.1. Let \underline{u} and \overline{u} be a subsolution and a supersolution of problem (P_{μ}) , respectively, with $\underline{u} \leq \overline{u}$ a.e. in Ω such that hypothesis (H) is fulfilled. Then there exists $\lambda_0 > 0$ such that whenever $\lambda \geq \lambda_0$ there is a solution $u \in W_0^{1,p}(\Omega)$ of the auxiliary problem $(T_{\lambda,\mu})$.

Proof. For every $\lambda > 0$ we introduce the nonlinear operator $A_{\lambda} : W_0^{1,p}(\Omega) \to W^{-1,p'}(\Omega)$ defined by

$$A_{\lambda}u = -\Delta_p u - \mu \Delta_q u + \lambda \Pi(u) - N(Tu).$$
(2.5)

Due to (2.3) and (*H*), the operator A_{λ} is bounded.

We claim that A_{λ} in (2.5) is a pseudomonotone operator. In order to show this, let a sequence $\{u_n\} \subset W_0^{1,p}(\Omega)$ satisfy

$$u_n \rightharpoonup u \quad \text{in } W_0^{1,p}(\Omega)$$
 (2.6)

and

$$\limsup_{n \to \infty} \langle A_{\lambda} u_n, u_n - u \rangle \le 0.$$
(2.7)

Recalling from (*H*) that $\sigma \in L^{\gamma'}(\Omega)$ with $\gamma < p^*$, by Hölder's inequality, (2.6) and the Rellich–Kondrachov compact embedding theorem we get

$$\int_{\Omega} \sigma |u_n - u| \, dx \le \|\sigma\|_{L^{\gamma'}(\Omega)} \|u_n - u\|_{L^{\gamma}(\Omega)} \to 0 \quad \text{as } n \to +\infty.$$
(2.8)

Let us show that

$$\int_{\Omega} |\nabla(Tu_n)|^{\beta} |u_n - u| \, dx \to 0 \quad \text{as } n \to +\infty.$$
(2.9)

The definition of the truncation operator $T: W_0^{1,p}(\Omega) \to W_0^{1,p}(\Omega)$ in (2.1) yields

$$\begin{split} \int_{\Omega} |\nabla(Tu_n)|^{\beta} |u_n - u| \, dx &= \int_{\{u_n < \underline{u}\}} |\nabla \underline{u}|^{\beta} |u_n - u| \, dx \\ &+ \int_{\{\underline{u} \le u_n \le \overline{u}\}} |\nabla u_n|^{\beta} |u_n - u| \, dx + \int_{\{u_n > \overline{u}\}} |\nabla \overline{u}|^{\beta} |u_n - u| \, dx. \end{split}$$

Using Hölder's inequality, (2.6) and the Rellich–Kondrachov compact embedding theorem, as well as the inequality $\frac{p}{p-\beta} < p^*$, enables us to find that

$$\int_{\{u_n < \underline{u}\}} |\nabla \underline{u}|^{\beta} |u_n - u| \, dx \le \|\nabla \underline{u}\|_{L^p(\Omega)}^{\beta} \|u_n - u\|_{L^{\frac{p}{p-\beta}}(\Omega)} \to 0$$

$$\begin{split} &\int_{\{\underline{u}\leq u_n\leq\overline{u}\}}|\nabla u_n|^{\beta}|u_n-u|\,dx\leq \|\nabla u_n\|_{L^p(\Omega)}^{\beta}\|u_n-u\|_{L^{\frac{p}{p-\beta}}(\Omega)}\to 0,\\ &\int_{\{u_n>\overline{u}\}}|\nabla\overline{u}|^{\beta}|u_n-u|\,dx\leq \|\nabla\overline{u}\|_{L^p(\Omega)}^{\beta}\|u_n-u\|_{L^{\frac{p}{p-\beta}}(\Omega)}\to 0. \end{split}$$

Therefore (2.9) holds true.

Taking into account (2.8), (2.9), hypothesis (*H*) and the fact that $\underline{u} \leq Tu_n \leq \overline{u}$ a.e. in Ω for every *n*, it turns out that

$$\lim_{n \to \infty} \int_{\Omega} f(x, Tu_n, \nabla(Tu_n))(u_n - u) \, dx = 0.$$
(2.10)

Using (2.3), (2.6) and the inequality $\frac{p}{p-\beta} < p^*$, the same type of arguments yields

$$\lim_{n \to \infty} \int_{\Omega} \pi(x, u_n)(u_n - u) \, dx = 0.$$
(2.11)

Due to (2.10) and (2.11), inequality (2.7) becomes

$$\limsup_{n\to\infty}\langle -\Delta_p u_n-\mu\Delta_q u_n,u_n-u\rangle\leq 0.$$

Through the $(S)_+$ -property of the operator $-\Delta_p - \mu \Delta_q$ (see [9, pp. 39–40]) and (2.6), we obtain the strong convergence $u_n \to u$ in $W_0^{1,p}(\Omega)$, thus

$$-\Delta_p u_n - \mu \Delta_q u_n \to -\Delta_p u - \mu \Delta_q u. \tag{2.12}$$

Taking into account (2.12) and that $u_n \to u$ in $W_0^{1,p}(\Omega)$, we get

$$A_{\lambda}u_n \rightharpoonup A_{\lambda}u, \quad \langle A_{\lambda}u_n, u_n \rangle \rightarrow \langle A_{\lambda}u, u \rangle,$$

which ensures that the operator A_{λ} is pseudomonotone.

Now we prove that the operator $A_{\lambda} : W_0^{1,p}(\Omega) \to W^{-1,p'}(\Omega)$ is coercive meaning that

$$\lim_{\|u\|\to+\infty}\frac{\langle A_{\lambda}u,u\rangle}{\|u\|}=+\infty$$

The expression of A_{λ} in (2.5) allows us to find

$$\langle A_{\lambda}u,u\rangle \geq \|\nabla u\|_{L^{p}(\Omega)}^{p} + \lambda \int_{\Omega} \pi(x,u)u\,dx - \int_{\Omega} f(x,Tu,\nabla(Tu))u\,dx.$$
(2.13)

Notice that by virtue of (2.1), it holds $\underline{u} \leq Tu \leq \overline{u}$ a.e. in Ω for every $u \in W_0^{1,p}(\Omega)$, so we can use hypothesis (H) with s = (Tu)(x) for a.e. $x \in \Omega$. Then, combining with Young's inequality and Sobolev embedding theorem, we infer for each $\varepsilon > 0$ that

$$\begin{aligned} \left| \int_{\Omega} f(x, Tu, \nabla(Tu)) u \, dx \right| \\ &\leq \int_{\Omega} \left(\sigma |u| + a |\nabla(Tu)|^{\beta} |u| \right) \, dx \\ &\leq \|\sigma\|_{L^{\gamma'}(\Omega)} \|u\|_{L^{\gamma}(\Omega)} + \varepsilon \|\nabla u\|_{L^{p}(\Omega)}^{p} + c_{1}(\varepsilon) \|u\|_{L^{\frac{p}{p-\beta}}(\Omega)}^{\frac{p}{p-\beta}} + c_{2} \|u\|_{L^{\frac{p}{p-\beta}}(\Omega)} \\ &\leq \varepsilon \|u\|^{p} + c_{1}(\varepsilon) \|u\|_{L^{\frac{p}{p-\beta}}(\Omega)}^{\frac{p}{p-\beta}} + d\|u\|, \end{aligned}$$

$$(2.14)$$

with positive constants $c_1(\varepsilon)$ (depending on ε), c_2 , d.

Inserting (2.4) and (2.14) in (2.13), it turns out that

$$\langle A_{\lambda}u,u\rangle \geq (1-\varepsilon)\|u\|^{p} + (\lambda r_{1} - c_{1}(\varepsilon))\|u\|_{L^{\frac{p}{p-\beta}}(\Omega)}^{\frac{p}{p-\beta}} - d\|u\| - \lambda r_{2}.$$

$$(2.15)$$

Choose $\varepsilon \in (0,1)$ and $\lambda > \frac{c_1(\varepsilon)}{r_1}$. Then (2.15) implies that the operator A_{λ} is coercive. Since the operator $A : W_0^{1,p}(\Omega \to W^{-1,p'}(\Omega))$ is bounded, pseudomonotone and coercive,

Since the operator $A : W_0^{1,p}(\Omega \to W^{-1,p'}(\Omega))$ is bounded, pseudomonotone and coercive, it is surjective (see [2, p. 40]). Therefore we can find $u \in W_0^{1,p}(\Omega)$ that solves equation $(T_{\lambda,\mu})$, which completes the proof.

3 Main result

We state our main abstract result on problem (P_{μ}).

Theorem 3.1. Let \underline{u} and \overline{u} be a subsolution and a supersolution of problem (P_{μ}) , respectively, with $\underline{u} \leq \overline{u}$ a.e. in Ω such that hypothesis (H) is fulfilled. Then problem (P_{μ}) possesses a solution $u \in W_0^{1,p}(\Omega)$ satisfying the location property $\underline{u} \leq u \leq \overline{u}$ a.e. in Ω .

Proof. Theorem 2.1 guarantees the existence of a solution of the truncated auxiliary problem $(T_{\lambda,\mu})$ provided $\lambda > 0$ is sufficiently large. Fix such a constant λ and let $u \in W_0^{1,p}(\Omega)$ be a solution of $(T_{\lambda,\mu})$.

We prove that $u \leq \overline{u}$ a.e. in Ω . Acting with $(u - \overline{u})^+ \in W_0^{1,p}(\Omega)$ as a test function in the definition of the supersolution \overline{u} of (P_{μ}) and in the definition of the solution u for the auxiliary truncated problem $(T_{\lambda,\mu})$ results in

$$\langle -\Delta_p \overline{u} - \mu \Delta_q \overline{u}, (u - \overline{u})^+ \rangle \ge \int_{\Omega} f(x, \overline{u}, \nabla \overline{u}) (u - \overline{u})^+ dx$$
 (3.1)

and

$$\langle -\Delta_p u - \mu \Delta_q u, (u - \overline{u})^+ \rangle + \lambda \int_{\Omega} \Pi(u) (u - \overline{u})^+ dx = \int_{\Omega} f(x, Tu, \nabla(Tu)) (u - \overline{u})^+ dx.$$
(3.2)

From (3.1), (3.2) and (2.1) we derive

$$\int_{\Omega} (|\nabla u|^{p-2} \nabla u - |\nabla \overline{u}|^{p-2} \nabla \overline{u}) \nabla (u - \overline{u})^{+} dx
+ \mu \int_{\Omega} (|\nabla u|^{q-2} \nabla u - |\nabla \overline{u}|^{q-2} \nabla \overline{u}) \nabla (u - \overline{u})^{+} dx + \lambda \int_{\Omega} \pi(x, u) (u - \overline{u})^{+} dx
\leq \int_{\Omega} (f(x, Tu, \nabla (Tu)) - f(x, \overline{u}, \nabla \overline{u})) (u - \overline{u})^{+} dx
= \int_{\{u > \overline{u}\}} (f(x, Tu, \nabla (Tu)) - f(x, \overline{u}, \nabla \overline{u})) (u - \overline{u}) dx = 0.$$
(3.3)

Since

$$\begin{split} \int_{\Omega} (|\nabla u|^{p-2} \nabla u - |\nabla \overline{u}|^{p-2} \nabla \overline{u}) \nabla (u - \overline{u})^+ \, dx \\ &= \int_{\{u > \overline{u}\}} (|\nabla u|^{p-2} \nabla u - |\nabla \overline{u}|^{p-2} \nabla \overline{u}) (\nabla u - \nabla \overline{u}) \, dx \ge 0 \end{split}$$

and

$$\int_{\Omega} (|\nabla u|^{q-2} \nabla u - |\nabla \overline{u}|^{q-2} \nabla \overline{u}) \nabla (u - \overline{u})^+ dx$$
$$= \int_{\{u > \overline{u}\}} (|\nabla u|^{q-2} \nabla u - |\nabla \overline{u}|^{q-2} \nabla \overline{u}) (\nabla u - \nabla \overline{u}) dx \ge 0$$

we are able to derive from (2.2) and (3.3) that

$$\int_{\{u>\overline{u}\}} (u-\overline{u})^{\frac{p}{p-\beta}} dx = \int_{\Omega} \pi(x,u)(u-\overline{u})^+ dx \le 0.$$

It follows that $u \leq \overline{u}$ a.e in Ω .

In an analogous way, by suitable comparison we can show that $\underline{u} \leq u$ a.e in Ω . Consequently, the solution u of the auxiliary truncated problem $(T_{\lambda,\mu})$ satisfies Tu = u and $\Pi(u) = 0$ (see (2.1) and (2.2)), so it becomes a solution of the original problem (P_{μ}) , which completes the proof.

4 Existence of positive solutions

In this section we focus on the existence of positive solutions to problem (P_{μ}). The idea is to construct a subsolution $\underline{u} \in W^{1,p}(\Omega)$ and a supersolution $\overline{u} \in W^{1,p}(\Omega)$ with $0 < \underline{u} \leq \overline{u}$ a.e. in Ω for which Theorem 3.1 can be applied. In this respect, inspired by [6,8], we suppose the following assumptions on the right-hand side f of (P_{μ}):

(*H*1) There exist constants $a_0 > 0$, b > 0, $\delta > 0$ and r > 0, with $r if <math>\mu = 0$ and r < q - 1 if $\mu > 0$, such that

$$\left(\frac{a_0}{b}\right)^{\frac{1}{p-r-1}} < \delta \tag{4.1}$$

and

$$f(x,s,\xi) \ge a_0 s^r - b s^{p-1} \quad \text{for a.e. } x \in \Omega, \text{ all } 0 < s < \delta, \xi \in \mathbb{R}^N.$$
(4.2)

(*H*2) There exists a constant $s_0 > \delta$, with $\delta > 0$ in (*H*1), such that

$$f(x, s_0, 0) \le 0 \quad \text{for a.e. } x \in \Omega. \tag{4.3}$$

Our result on the existence of positive solutions for problem (P_{μ}) is as follows.

Theorem 4.1. Assume (H1), (H2) and that

 $|f(x,s,\xi)| \leq \sigma(x) + a|\xi|^{\beta}$ for a.e. $x \in \Omega$, all $s \in [0,s_0]$, $\xi \in \mathbb{R}^N$,

with a function $\sigma \in L^{\gamma'}(\Omega)$ for $\gamma \in [1, p^*)$ and constants a > 0 and $\beta \in [0, \frac{p}{(p^*)'})$. Then, for every $\mu \ge 0$, problem (P_{μ}) possesses a positive smooth solution $u \in C_0^1(\overline{\Omega})$ satisfying the a priori estimate $u(x) \le s_0$ for all $x \in \Omega$ (s_0 is the constant in (H2)).

Proof. With the notation in hypothesis (H1), consider the following auxiliary problem

$$\begin{cases} -\Delta_p u - \mu \Delta_q u + b|u|^{p-2}u = a_0(u^+)^r & \text{ in } \Omega, \\ u = 0 & \text{ on } \partial\Omega. \end{cases}$$
(4.4)

We are going to show that there exists a solution $\underline{u} \in C_0^1(\overline{\Omega})$ of problem (4.4) satisfying $\underline{u} > 0$ in Ω and

$$b\|\underline{u}\|_{L^{\infty}(\Omega)}^{p-r-1} \le a_0.$$
(4.5)

To this end, we consider the Euler functional associated to (4.5), that is the C^1 -function $I : W_0^{1,p}(\Omega) \to \mathbb{R}$ defined by

$$I(u) = \frac{1}{p} \int_{\Omega} (|\nabla u|^{p} + b|u|^{p}) \, dx + \frac{\mu}{q} \int_{\Omega} |\nabla u|^{q} \, dx - \frac{a_{0}}{r+1} \int_{\Omega} (u^{+})^{r+1} \, dx$$

whenever $u \in W_0^{1,p}(\Omega)$. From the assumption on *r* in hypothesis (*H*1) and Sobolev embedding theorem, it is easy to prove that *I* is coercive. Since *I* is also sequentially weakly lower semicontinuous, there exists $\underline{u} \in W_0^{1,p}(\Omega)$ such that

$$I(\underline{u}) = \inf_{u \in W_0^{1,p}(\Omega)} I(u)$$

On the basis of the conditions r < p-1 if $\mu = 0$ and r < q-1 if $\mu > 0$ (see hypothesis (*H*1)), it is seen that for any positive function $v \in W_0^{1,p}(\Omega)$ and with a sufficiently small t > 0, there holds I(tv) < 0, so $\inf_{u \in W_0^{1,p}(\Omega)} I(u) < 0$. This enables us to deduce that \underline{u} is a nontrivial solution of (4.4). Testing equation (4.4) with $-\underline{u}^-$ yields $\underline{u} \ge 0$. By the nonlinear regularity theory and strong maximum principle we obtain that $\underline{u} \in C_0^1(\overline{\Omega})$ and $\underline{u} > 0$ in Ω .

According to the latter properties, we can utilize $\underline{u}^{\alpha+1}$, with any $\alpha > 0$, as a test function in (4.4). Through Hölder's inequality and because r + 1 < p, this leads to

$$b\|\underline{u}\|_{L^{p+\alpha}(\Omega)}^{p+\alpha} \leq a_0 \int_{\Omega} \underline{u}^{r+\alpha+1} dx \leq a_0 \|\underline{u}\|_{L^{p+\alpha}(\Omega)}^{r+\alpha+1} |\Omega|_N^{(p-r-1)/(p+\alpha)}.$$

Letting $\alpha \to +\infty$ in the inequality

$$b\|\underline{u}\|_{L^{p+\alpha}(\Omega)}^{p-r-1} \le a_0|\Omega|_N^{(p-r-1)/(p+\alpha)}$$

we arrive at (4.5).

We claim that \underline{u} is a subsolution for problem (P_{μ}). Specifically, due to (4.1) and (4.5), we can insert $s = \underline{u}(x)$ and $\xi = \nabla \underline{u}(x)$ in (4.2), which in conjunction with (4.4) for $u = \underline{u}$ reads as

$$\int_{\Omega} \left(|\nabla \underline{u}|^{p-2} \nabla \underline{u} + \mu |\nabla \underline{u}|^{q-2} \nabla \underline{u} \nabla v \right) \nabla v \, dx = \int_{\Omega} (a_0 \underline{u}^r - b \underline{u}^{p-1}) v \, dx$$
$$\leq \int_{\Omega} f(x, \underline{u}, \nabla \underline{u}) v \, dx$$

whenever $v \in W_0^{1,p}(\Omega)$, $v \ge 0$ a.e. in Ω . Thereby the claim is proven.

Now we notice that hypothesis (*H*2) guarantees that $\overline{u} = s_0$ is a supersolution of problem (P_{μ}). Indeed, in view of (4.3), we obtain

$$\int_{\Omega} \left(|\nabla \overline{u}|^{p-2} \nabla \overline{u} + \mu |\nabla \overline{u}|^{q-2} \nabla \overline{u} \right) \nabla v \, dx = 0 \ge \int_{\Omega} f(x, s_0, 0) v \, dx$$
$$= \int_{\Omega} f(x, \overline{u}, \nabla \overline{u}) v \, dx$$

for all $v \in W_0^{1,p}(\Omega)$, $v \ge 0$ a.e. in Ω . We point out from assumption (*H*2) that $s_0 > \delta$, which in conjunction with (4.1) and (4.5), entails that $\underline{u} < \overline{u}$ in Ω .

We also note that hypothesis (H) holds true for the constructed subsolution-supersolution $(\underline{u}, \overline{u})$ of problem (P_{μ}) . Therefore Theorem 3.1 applies ensuring the existence of a solution $u \in W_0^{1,p}(\Omega)$ to problem (P_{μ}) , which satisfies the enclosure property $\underline{u} \leq u \leq \overline{u}$ a.e. in Ω . Taking into account that $\underline{u} > 0$, we conclude that the solution u is positive. Moreover, the regularity up to the boundary invoked for problem (P_{μ}) renders $u \in C_0^1(\overline{\Omega})$, whereas the inequality $u \leq \overline{u}$ implies the estimate $u(x) \leq s_0$ for all $x \in \Omega$. This completes the proof. \Box

Remark 4.2. Proceeding symmetrically, a counterpart of Theorem 4.1 for negative solutions can be established.

We illustrate the applicability of Theorem 4.1 by a simple example.

Example 4.3. Let $f : \Omega \times \mathbb{R} \times \mathbb{R}^N \to \mathbb{R}$ be defined by

$$f(x,s,\xi) = |s|^r - |s|^{p-1} + (2^{\frac{p-r}{p-r-1}} - s)|\xi|^\beta \text{ for all } (x,s,\xi) \in \Omega \times \mathbb{R} \times \mathbb{R}^N,$$

where the constants r, p, β are as in conditions (H) and (H1). For simplicity, we have dropped the dependence with respect to $x \in \Omega$. Hypothesis (H1) is verified by taking for instance $a_0 = b = 1$ and $\delta = 2^{\frac{p-r}{p-r-1}}$ (see (4.1) and (4.2)). Hypothesis (H2) is fulfilled for every $s_0 > \delta = 2^{\frac{p-r}{p-r-1}}$. It is also clear that the growth condition for f on $\Omega \times [0, s_0] \times \mathbb{R}^N$ required in the statement of Theorem 4.1 is satisfied, too. Consequently, Theorem 4.1 applies to problem (P_{μ}) with the chosen function $f(x, s, \xi)$ giving rise to a positive solution belonging to $C_0^1(\overline{\Omega})$.

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