# Optimal decay estimates for solutions to damped second order ODE's 

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Received 7 March 2017, appeared4 June 2018
Communicated by Alberto Cabada


#### Abstract

In this paper we derive optimal decay estimates for solutions to second order ordinary differential equations with weak damping. The main assumptions are Kurdyka-Łojasiewicz gradient inequality and its inverse.


Keywords: Kurdyka-Łojasiewicz inequality, rate of convergence to equilibrium, second order equation with damping.
2010 Mathematics Subject Classification: 34D05.

## 1 Introduction

In this paper we study long-time behavior for solutions of damped second order ordinary differential equations

$$
\begin{equation*}
\ddot{u}+g(\dot{u})+\nabla E(u)=0, \tag{SOP}
\end{equation*}
$$

where $E \in C^{2}(\Omega), \Omega$ being an open connected subset of $\mathbb{R}^{n}$ and $g: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ is a $C^{1}$-function satisfying $\langle g(v), v\rangle \geq 0$ on $\mathbb{R}^{n}$. This last condition means that the term $g(\dot{u})$ in (SOP) has a damping effect. It is easy to see that energy

$$
\mathcal{E}(u, \dot{u})=\frac{1}{2}\|\dot{u}\|^{2}+E(u)
$$

is nonincreasing along solutions. In fact, if $u$ is a classical solution to (SOP), then

$$
\frac{d}{d t} \mathcal{E}(u(t), \dot{u}(t))=-\langle g(v), v\rangle \leq 0
$$

If $u:[0,+\infty) \rightarrow \Omega$ is a global solution and $\varphi$ belongs to the $\omega$-limit set of $u$, then $\mathcal{E}(u(t), \dot{u}(t)) \rightarrow \mathcal{E}(\varphi, 0)=E(\varphi)$ as $t \rightarrow+\infty$. In this paper, we derive the exact rate of convergence of $\mathcal{E}(u(t), \dot{u}(t))$ to $E(\varphi)$.

Our main assumption is the Kurdyka-Łojasiwicz gradient inequality (see [10])

$$
\begin{equation*}
\Theta(|E(u)-E(\varphi)|) \leq\|\nabla E(u)\| . \tag{KLI}
\end{equation*}
$$

[^0]For linear $g$, the optimal decay estimate was derived in [2]. For nonlinear $g$ (typically satisfying $g^{\prime}(0)=0$ ) some decay estimates were shown in $[3,7,8]$. Here we derive better decay estimates under additional assumptions on $E$ and we show that these estimates are optimal. We will assume that $E$ satisfies an inverse to (KLI) and some estimates on the second gradient and that $g$ has certain behavior near zero. The present result generalizes the one from [5, Theorem 20] where we worked with the Łojasiewicz gradient inequality, i.e. (KLI) with $\Theta(s)=s^{1-\theta}$ for a constant $\theta \in\left(0, \frac{1}{2}\right.$ ] (see [11]). It also generalizes the result by Haraux (see [9]) and Abdelli, Anguiano, Haraux (see [1]). The present result applies e.g. to functions $E$ and $g$ having the growth near origin as

$$
\begin{equation*}
s^{a} \ln ^{r_{1}}(1 / s) \ln ^{r_{2}}(\ln (1 / s)) \ldots \ln ^{r_{k}}(\ln \ldots \ln (1 / s)) \tag{1.1}
\end{equation*}
$$

for some constants $a, r_{1}, \ldots, r_{k}$. It also applies to functions $E$ with a non-strict local minimum in $\varphi$.

The paper is organized as follows. In Section 2 we present our notations, basic definitions and the main result. Section 3 contains the proof of the main result.

## 2 Notations and the main result

By $\|\cdot\|$ and $\langle\cdot, \cdot\rangle$ we denote the usual norm and scalar product on $\mathbb{R}^{d}$. For nonnegative functions $f, g: G \subset \mathbb{R}^{d} \rightarrow \mathbb{R}$ we write $g(x)=O(f(x))$ on $G$ if there exists $C>0$ such that $g(x) \leq C f(x)$ for all $x \in G$. We say that $g(x)=O(f(x))$ for $x \rightarrow a$ if $g(x)=O(f(x))$ on a neighborhood of $a$. If $f(x)=O(g(x))$ and $g(x)=O(f(x))$, we write $f \sim g$.

We say that a function $f: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$satisfying $f(0)=0$ and $f(s)>0$ for $s>0$

- is admissible if $f$ is nondecreasing and there exists $c>0$ such that $s f_{ \pm}^{\prime}(s) \leq c f(s)$ for all $s>0$,
- has property ( $K$ ) if for every $K>0$ there exists $C(K)>0$ such that $f(K s) \leq C(K) f(s)$ holds for all $s>0$,
- is C-sublinear if there exists $C>0$ such that $f(t+s) \leq C(f(t)+f(s))$ holds for all $t$, $s>0$.

It is easy to see that admissible functions are C -sublinear and have property ( K ) (for proof see Appendix of [4]). Further, for nondecreasing functions property (K) is equivalent to $C$-sublinearity. Moreover, every concave function $f: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$is admissible and satisfies $s f_{ \pm}^{\prime}(s) \leq f(s)$.

Let us introduce the inverse Kurdyka-Łojasiewicz inequality

$$
\begin{equation*}
\Theta_{1}(|E(u)-E(\varphi)|) \geq\|\nabla E(u)\| \tag{IKLI}
\end{equation*}
$$

and an inequality for the second gradient

$$
\begin{equation*}
\left\|\nabla^{2} E(u)\right\| \leq \Gamma(\|\nabla E(u)\|) . \tag{2.1}
\end{equation*}
$$

When we say that inequality (KLI) (resp. (IKLI), (2.1)) holds on a set $U$ it means that the inequality holds for all $u \in U$ with a given fixed $\varphi$ and $\Theta$ (resp. $\left.\Theta_{1}, \Gamma\right)$.

By a solution to (SOP) we always mean a classical solution defined on $[0,+\infty)$. By $R(u)=$ $\{u(t): t \geq 0\}$ we denote the range of $u$. We say that a solution is precompact if $R(u)$ is precompact in $\Omega$ (the domain of $E$ ). The $\omega$-limit set of $u$ is

$$
\omega(u)=\left\{\varphi \in \Omega: \exists t_{n} \nearrow+\infty, u\left(t_{n}\right) \rightarrow \varphi\right\} .
$$

By $c, C, \tilde{c}, \tilde{C}$ we denote generic constants, their values can change from line to line or from expression to expression.

The main result of the present paper is the following.
Theorem 2.1. Let $u$ be a precompact solution to (SOP) and $\varphi \in \omega(u)$. Let $E(\cdot) \geq E(\varphi)$ on $R(u)$ and let E satisfy (KLI), (IKLI) and (2.1) on $R(u)$ with admissible functions $\Theta, \Theta_{1}$ and $\Gamma$, such that $\Theta(s) \sim \Theta_{1}(s)$ and $\Gamma(\Theta(s)) \sim \Theta(s) \Theta^{\prime}(s)$ for $s \rightarrow 0+$. Let $g$ satisfies

$$
\begin{equation*}
\langle g(v), v\rangle \geq \operatorname{ch}(\|v\|)\|v\|^{2}, \quad\|g(v)\| \leq \operatorname{Ch}(\|v\|)\|v\| \tag{2.2}
\end{equation*}
$$

with an admissible function $h$ satisfying

$$
\begin{equation*}
\Theta(s) \geq c \sqrt{s} h(\sqrt{s}) \tag{2.3}
\end{equation*}
$$

for some $c>0$ and all $s \geq 0$. Let $u$ s denote

$$
\begin{equation*}
\chi(s)=\operatorname{sh}(\sqrt{s}), \quad \Phi_{\chi}=\int \frac{1}{\chi(s)} d s \tag{2.4}
\end{equation*}
$$

and assume that $\psi(s)=s^{2} h(s)$ is convex. Then

$$
c\left(-\Phi_{\chi}\right)^{-1}(C t) \leq \mathcal{E}(u(t), \dot{u}(t))-\mathcal{E}(\varphi, 0) \leq C\left(-\Phi_{\chi}\right)^{-1}(c t)
$$

for some c, C $>0$ and all targe enough.
Let us first mention that if $E(u)=\|u\|^{p}, p \geq 2$, then (KLI), (IKLI) hold with $\Theta(s) \sim$ $\Theta_{1}(s)=C s^{1-\theta}, \theta=\frac{1}{p}$ and (2.1) holds with $\Gamma(s)=C s^{\frac{1-2 \theta}{1-\theta}}$. If $h(s)=s^{\alpha}, \alpha \in(0,1)$, then condition (2.3) becomes $\alpha \geq 1-2 \theta$ and $\left(-\Phi_{\chi}\right)^{-1}(c t)=C t^{-\frac{2}{\alpha}}$. In this case, we obtain the same result as [5, Theorem 20] and also [9].

## Remark 2.2.

1. If $\left(\Phi_{\chi}\right)^{-1}$ has property $(K)$, then the statement of Theorem 2.1 can be written as $\mathcal{E}(u(t), \dot{u}(t))-E(\varphi) \sim\left(-\Phi_{\chi}\right)^{-1}(t)$.
2. We can see that the energy decay depends on $h$ only. In particular, it is independent of $\Theta$.
3. It is enough to assume that all the assumptions except $\langle g(v), v\rangle>0$ for all $v \neq 0$ hold on a small neigborhood of zero, resp. a small neighborhood of $\omega(u)$.
4. It follows from (KLI) and [2, Proposition 2.8] that $\Theta(s)=O(\sqrt{s})$. Hence, by (2.3) function $h$ must be bounded on a neighborhood of zero and $\Phi_{\chi}(t) \rightarrow-\infty$ as $t \rightarrow 0+$. So, it is not important which primitive function $\Phi_{\chi}$ we take and we have $\left(-\Phi_{\chi}\right)^{-1}(t) \rightarrow 0$ as $t \rightarrow+\infty$.
5. Theorem 2.1 does not imply that $u(t) \rightarrow \varphi$ as $t \rightarrow+\infty$. In fact, in [6, Theorem 4] we have shown that $u(t) \rightarrow \varphi$ if $h$ is large enough, in particular if $\int_{0}^{\varepsilon} \frac{1}{\Theta(s) h(\Theta(s))}<+\infty$. If this condition is not satisfied, it may happen that $\omega(u)$ contains more than one point.
6. If $\varphi$ is an asymptotically stable equilibrium for the gradient system $\dot{u}+\nabla E(u)=0$ (e.g. if $E$ has a strict local minimum in $\varphi$ and is convex on a neighborhood of $\varphi$ ) and (KLI), (IKLI) hold on a neighborhood of $\varphi$, then by [5, Corollary 5] we have $\|x-\varphi\| \sim \Phi_{\Theta}(E(x)-E(\varphi))$ on a neighborhood of $\varphi$ where $\Phi_{\Theta}(t)=\int_{0}^{t} \frac{1}{\Theta}$. In this case, for any solution starting in a neighborhood of $\varphi$ we have

$$
c\left(-\Phi_{\chi}\right)^{-1}(C t) \leq\|v(t)\|^{2}+\Phi_{\Theta}^{-1}(\|u(t)-\varphi\|) \leq C\left(-\Phi_{\chi}\right)^{-1}(c t)
$$

and, especially,

$$
\|u(t)-\varphi\| \leq \Phi_{\Theta}\left(C\left(-\Phi_{\chi}\right)^{-1}(c t)\right),
$$

so $u(t) \rightarrow \varphi$. We do not have the estimate for $\|u(t)-\varphi\|$ from below since, at least in onedimensional case, the solution oscillates and $u\left(t_{n}\right)=\varphi$ for a sequence $t_{n} \nearrow+\infty$ (see [9]).

Example 2.3. Let us consider $E(u)=F(\|u\|)$ with a real function $F$ having a strict local minimum $F(0)=0$ and satisfying on a right neighborhood of zero $C F(s) \geq s F^{\prime}(s) \geq$ $(1+\varepsilon) F(s)$ and $s F^{\prime \prime}(s) \sim F^{\prime}(s)$. Moreover, we assume that $\left(F^{\prime}\right)^{-1}$ has property (K). (It is easy to show that any analytic function $F(s)=\sum_{k=2 m}^{\infty} a_{k} s^{k}, a_{2 m}>0$ and any function of the form (1.1) with $a>2, r_{i} \in \mathbb{R}$ or $a=2, r_{1}=\cdots=r_{j-1}=0, r_{j}<0, r_{j+1}, \ldots, r_{k} \in \mathbb{R}$ satisfy these assumptions.) Then (KLI), (IKLI) holds with $\Theta(s)=C_{\overline{F^{-1}(s)}}$, since

$$
\Theta(E(u))=\Theta(F(\|u\|))=C \frac{F(\|u\|)}{\|u\|} \sim F^{\prime}(\|u\|)=\|\nabla E(u)\| .
$$

Further, (2.1) holds with $\Gamma(s)=C \frac{s}{\left(F^{\prime}\right)^{-1}(s)}$ since

$$
\left\|\nabla^{2} E(u)\right\| \leq C F^{\prime \prime}(\|u\|) \sim \frac{F^{\prime}(\|u\|)}{\|u\|} \sim \Gamma\left(F^{\prime}(\|u\|)\right)=\Gamma(\|\nabla E(u)\|),
$$

where the first inequality is due to the fact that the diagonal resp. nondiagonal terms of $\nabla^{2} E(u)$ are

$$
F^{\prime \prime}(\|u\|) \frac{u_{i}^{2}}{\|u\|^{2}} \quad \text { resp. } \quad \frac{u_{i} u_{j}}{\|u\|^{2}}\left(F^{\prime \prime}(\|u\|)-\frac{F^{\prime}(\|u\|)}{\|u\|}\right),
$$

so they are estimated by $C F^{\prime \prime}(\|u\|)$. Further, we have

$$
\Theta^{\prime}(F(s))=\frac{\frac{d}{d s} \Theta(F(s))}{F^{\prime}(s)}=\frac{\frac{d}{d s} \frac{F(s)}{s}}{F^{\prime}(s)}=\frac{F^{\prime}(s) s-F(s)}{s^{2} F^{\prime}(s)}=\frac{1}{s}\left(1-\frac{F(s)}{s F^{\prime}(s)}\right) \sim \frac{1}{s^{\prime}}
$$

so

$$
\Theta(F(s)) \Theta^{\prime}(F(s)) \sim \frac{1}{s} \Theta(F(s)) \sim \frac{1}{s^{2}} F(s)
$$

and

$$
\Gamma(\Theta(F(s))) \sim \frac{\Theta(F(s))}{\left(F^{\prime}\right)^{-1}(\Theta(F(s)))} \sim \frac{F(s)}{s\left(F^{\prime}\right)^{-1}\left(\frac{F(s)}{s}\right)} \sim \frac{F(s)}{s\left(F^{\prime}\right)^{-1}\left(F^{\prime}(s)\right)}=\frac{F(s)}{s^{2}},
$$

hence $\Gamma(\Theta(s)) \sim \Theta(s) \Theta^{\prime}(s)$. Then, for any $g$ satisfying (2.2) with a function $h$ small enough (such that (2.3) holds) Theorem 2.1 can be applied and we obtain the exact energy decay which depends on $h$ only and not on $F$. In particular, if $h(s)=s^{\alpha}$ we have $\mathcal{E}(u(t), v(t)) \sim t^{-\frac{2}{\alpha}}$ and if $h$ is of the form (1.1), we have by [4, Lemmas 6.5, 6.6]

$$
\mathcal{E}(u(t), v(t)) \sim t^{-\frac{2}{a}} \ln ^{-\frac{r_{1}}{a}}(\ln 1 / t) \ldots \ln ^{-\frac{r_{k}}{a}}(\ln \ldots \ln 1 / t) .
$$

Let us mention that if $h$ is equal to (1.1) and such that $c s \leq h(s) \leq c$ near zero (i.e. $a \in[0,1]$ and if $a \in\{0,1\}$ we have a sign condition on the first nonzero number $\left.r_{i}\right)$, then $\psi(s)=s^{2} h(s)$ is convex near zero.

## 3 Proof of Theorem 2.1

Let us write $v(t)$ instead of $\dot{u}(t)$ and $\mathcal{E}(t)$ instead of $\mathcal{E}(u(t), v(t))$. We also often write $u, v$ instead of $u(t), v(t)$.

First of all, since $u$ is precompact $\{E(u(t)): t \geq 0\}$ is bounded. Therefore, $\{\mathcal{E}(t): t \geq 0\}$ is bounded, hence $v$ is bounded and by (SOP) also $\ddot{u}=\dot{v}$ is bounded. Since

$$
\int_{0}^{t}\langle g(v), v\rangle=\mathcal{E}(0)-\mathcal{E}(t) \leq K
$$

we have $\langle g(v), v\rangle \in L^{1}((0,+\infty))$. Then boundedness of $\dot{v}$ yields convergence of $\langle g(v(t)), v(t)\rangle$ to 0 . Hence $v(t) \rightarrow 0$ as $t \rightarrow+\infty$ and it follows that $\mathcal{E}(t) \rightarrow \mathcal{E}(\varphi, 0)$. So, we can assume without loss of generality that $E(\varphi)=0, \mathcal{E}(\varphi, 0)=0$.

In the rest of the proof we will work with

$$
H(t)=\mathcal{E}(t)+\varepsilon B(E(u(t)))\langle\nabla E(u(t)), v\rangle,
$$

where

$$
B(s)= \begin{cases}\frac{1}{\Theta(s)^{2}} \operatorname{sh}(\sqrt{s}) & s>0 \\ 0 & s=0\end{cases}
$$

and $\varepsilon>0$ is small enough. Let us mention that $B$ can be unbounded in a neighborhood of zero, but due to (2.3) we have $\Theta(s) B(s) \leq C \sqrt{s}$, hence $H$ is continuous even in the points where $E(u(t))=0$ and in these points we have $H(t)=\mathcal{E}(t)$. Let us denote $M:=\{t \geq 0$ : $E(u(t))>0\}$ and $M^{c}=\{t \geq 0: E(u(t))=0\}$.

We show that $H(t) \sim \mathcal{E}(t)$. On $M^{c}$ it is trivial. On $M$ we apply (IKLI), Cauchy-Schwarz and Young inequalities and $\Theta(s) B(s) \leq C \sqrt{s}$ and we obtain

$$
\begin{aligned}
|\varepsilon B(E(u))\langle\nabla E(u(t)), v\rangle| & \leq \varepsilon C B(E(u)) \Theta(E(u))\|v\| \\
& \leq \varepsilon C B(E(u))^{2} \Theta(E(u))^{2}+\varepsilon C\|v\|^{2} \\
& \leq \varepsilon C \mathcal{E}(t),
\end{aligned}
$$

hence

$$
(1-\varepsilon C) \mathcal{E}(t) \leq H(t) \leq(1+\varepsilon C) \mathcal{E}(t)
$$

and taking $\varepsilon>0$ small enough we obtain $H(t) \sim \mathcal{E}(t)$.
The next step is to show that

$$
\begin{equation*}
0 \leq-H^{\prime}(t) \sim h(\|v\|)\|v\|^{2}+E(u) h(\sqrt{E(u)}) \tag{3.1}
\end{equation*}
$$

Let us first estimate $B^{\prime}(s)$. For any $s>0$ we have

$$
B^{\prime}(s)=\frac{B(s)}{s}\left(1+\frac{h^{\prime}(\sqrt{s}) \sqrt{s}}{h(\sqrt{s})}-2 \frac{s \Theta^{\prime}(s)}{\Theta(s)}\right) \in\left[\frac{B(s)}{s}(1-2 C), \frac{B(s)}{s}(1+C)\right],
$$

where the equality follows by definition of $B$ and the rest from admissibility of $h$ and $\Theta$ (the two fractions in round bracket are nonnegative and bounded above by a constant). Hence, $\left|s B^{\prime}(s)\right| \leq C B(s)$.

Let $t \in M$. Let us compute $H^{\prime}(t)$ and use the fact that $u$ solves (SOP) to get

$$
\begin{align*}
H^{\prime}(t)= & -\langle g(v), v\rangle-\varepsilon B(E(u))\|\nabla E(u)\|^{2} \\
& +\varepsilon B^{\prime}(E(u))\langle\nabla E(u), v\rangle^{2} \\
& +\varepsilon B(E(u))\left\langle\nabla^{2} E(u) v, v\right\rangle  \tag{3.2}\\
& +\varepsilon B(E(u))\langle\nabla E(u),-g(v)\rangle .
\end{align*}
$$

Due to (2.2) we have $\langle g(v), v\rangle \sim h(\|v\|)\|v\|^{2}$ and by definition of $B$, (KLI) and (IKLI) we immediately have $B(E(u))\|\nabla E(u)\|^{2} \sim E(u) h(\sqrt{E(u)})$. So,

$$
\langle g(v), v\rangle+\varepsilon B(E(u))\|\nabla E(u)\|^{2} \sim h(\|v\|)\|v\|^{2}+\varepsilon C E(u) h(\sqrt{E(u)}) .
$$

We show that the second, third and fourth lines of (3.2) are smaller than this term, then (3.1) is proved.

The second line of (3.2) is less than

$$
\varepsilon C \frac{B(E(u))}{E(u)} \Theta(E(u))^{2}\|v\|^{2} \leq \varepsilon C h(\sqrt{E(u)})\|v\|^{2} .
$$

Since $\Gamma$ has property (K) and satisfies $\Gamma(\Theta(s)) \sim \Theta(s) \Theta^{\prime}(s) \leq C s^{-1} \Theta(s)^{2}$ and due to (IKLI) and definition of $B$, the third line in (3.2) is less than

$$
\varepsilon C B(E(u)) \Gamma(\|\nabla E(u)\|)\|v\|^{2} \leq \varepsilon C h(\sqrt{E(u)})\|v\|^{2} .
$$

If $E(u) \leq 4 C\|v\|^{2}$, then ( $h$ satisfies property (K)) we have $h(\sqrt{E(u)})\|v\|^{2} \leq \tilde{C} h(\|v\|)\|v\|^{2}$ and if $E(u) \geq 4 C\|v\|^{2}$, then $h(\sqrt{E(u)})\|v\|^{2} \leq \frac{1}{4 C} h(\sqrt{E(u)}) E(u)$. So, in either case we have that lines two and three in (3.2) are less than

$$
\varepsilon C h(\|v\|)\|v\|^{2}+\frac{1}{4} \varepsilon h(\sqrt{E(u)}) E(u)
$$

so they are less than the first line in (3.2) since we can make $\varepsilon C$ small by taking $\varepsilon$ small enough. The last line in (3.2) is (by definition of $B$ and (2.3)) less than

$$
\begin{aligned}
\varepsilon C B(E(u))\|\nabla E\| h(\|v\|)\|v\| & \leq \varepsilon C \frac{1}{\Theta(E(u))} E(u) h(\sqrt{E(u)}) h(\|v\|)\|v\| \\
& \leq \varepsilon C \sqrt{E(u)} h(\|v\|)\|v\| .
\end{aligned}
$$

Applying the Young inequality $a b \leq \psi(a)+\tilde{\psi}(b)$ with $\psi(s)=s^{2} h(s)$ and the convex conjugate $\tilde{\psi}$ we get

$$
\begin{aligned}
\varepsilon C \sqrt{E(u)} h(\|v\|)\|v\| & \leq \frac{1}{4} \varepsilon \psi(\sqrt{E(u)})+\varepsilon C \tilde{\psi}(\|v\| h(\|v\|)) \\
& \leq \frac{1}{4} \varepsilon E(u) h(\sqrt{E(u)})+\varepsilon C h(\|v\|)\|v\|^{2}
\end{aligned}
$$

since $\tilde{\psi}(\operatorname{sh}(s)) \leq C s^{2} h(s)$ due to Lemma 3.1 below. Now, (3.1) is proven on $M$. If $E(u(t)) \rightarrow 0$ for $t \rightarrow t_{0}$, we can see that $H^{\prime}(t) \rightarrow-\left\langle g\left(v\left(t_{0}\right)\right), v\left(t_{0}\right)\right\rangle=\mathcal{E}^{\prime}\left(t_{0}\right)$ (due to the estimates above, all
terms on the right-hand side of (3.2) except the first one tend to zero). By continuity of $H$, we have $H^{\prime}=\mathcal{E}^{\prime}$ on $M^{c}$, in particular (3.1) holds on $M^{c}$.

We show that $\chi(H(t)) \sim-H^{\prime}(t)$. In fact,

$$
\begin{aligned}
\chi(H(t)) & \left.\leq \chi\left(C\left(\|v\|^{2}+E(u)\right)\right)\right) \\
& \leq C\left(\chi\left(\|v\|^{2}\right)+\chi(E(u))\right) \\
& =C\left(h(\|v\|)\|v\|^{2}+E(u) h(\sqrt{E(u)})\right) \\
& \leq-C H^{\prime}(t)
\end{aligned}
$$

where we applied monotonicity in the first line, $C$-sublinearity and property $(\mathrm{K})$ in the second line ( $\chi$ has these properties by Lemma 3.2 below), definition of $\chi$ in the third line and (3.1) in the last inequality. On the other hand, by Lemma 3.2 also the inverse inequalities in $C$ sublinearity and property $(\mathrm{K})$ are valid, so we have

$$
\begin{aligned}
\chi(H(t)) & \left.\geq \chi\left(c\left(\|v\|^{2}+E(u)\right)\right)\right) \\
& \geq c\left(\chi\left(\|v\|^{2}\right)+\chi(E(u))\right) \\
& =c\left(h(\|v\|)\|v\|^{2}+E(u) h(\sqrt{E(u)})\right) \\
& \geq-c H^{\prime}(t),
\end{aligned}
$$

so $\chi(H(t)) \sim-H^{\prime}(t)$ is proved.
Let $T=\sup \{t \geq 0: H(t)>0\}$. For any $t \in(0, T)$ we have proved

$$
-\frac{d}{d t} \Phi_{\chi}(H(t))=-\frac{H^{\prime}(t)}{\chi(H(t))} \in[c, C] .
$$

Integrating this relation from $t_{0}$ to $t$ we obtain

$$
\begin{equation*}
c\left(t-t_{0}\right)-\Phi_{\chi}\left(H\left(t_{0}\right)\right) \leq-\Phi_{\chi}(H(t)) \leq C\left(t-t_{0}\right)-\Phi_{\chi}\left(H\left(t_{0}\right)\right) . \tag{3.3}
\end{equation*}
$$

If $T<+\infty$, then we can see that $-\Phi_{\chi}(H(t))$ is bounded on $(0, T)$, hence $0<\lim _{t \rightarrow T-} H(t)=$ $H(T)$, contradiction. Therefore, $T=+\infty$, (3.3) holds for all $t>0$ and for $t$ large enough we have

$$
\tilde{c} t \leq c\left(t-t_{0}\right)-\Phi_{\chi}\left(H\left(t_{0}\right)\right) \leq-\Phi_{\chi}(H(t)) \leq C\left(t-t_{0}\right)-\Phi_{\chi}\left(H\left(t_{0}\right)\right) \leq \tilde{C} t .
$$

Hence

$$
c\left(-\Phi_{\chi}\right)^{-1}(\tilde{C} t) \leq H(t) \sim \mathcal{E}(u(t), v(t)) \leq C\left(-\Phi_{\chi}\right)^{-1}(\tilde{c} t)
$$

which completes the proof of Theorem 2.1.
Lemma 3.1. Let $\psi(s)=s^{2} h(s)$ and $\tilde{\psi}(r)=\sup \{r s-\psi(s): s \geq 0\}$ be the convex conjugate to $\psi$. Then there exists $C>0$ such that $\tilde{\psi}(\operatorname{sh}(s)) \leq C s^{2} h(s)$ for all $s \geq 0$.

Proof. Since $\psi$ is convex, the one-sided derivatives $\psi_{ \pm}^{\prime}(s)=s^{2} h_{ \pm}^{\prime}(s)+2 \operatorname{sh}(s)$ are nondecreasing functions and the interval $\left[\psi_{-}^{\prime}(s), \psi_{+}^{\prime}(s)\right]$ is nonempty. Take $s_{0}>0$ arbitrarily and take $r \in$ $\left[\psi_{-}^{\prime}\left(s_{0}\right), \psi_{+}^{\prime}\left(s_{0}\right)\right]$. Then the function $s \mapsto r s-\psi(s)$ attains its maximum in $s_{0}$, hence $\tilde{\psi}(r)=$ $r s_{0}-s_{0}^{2} h\left(s_{0}\right)$. Since $r \geq \psi_{-}^{\prime}\left(s_{0}\right)=s_{0}^{2} h_{-}^{\prime}\left(s_{0}\right)+2 s_{0} h\left(s_{0}\right) \geq s_{0} h\left(s_{0}\right)$ and $\tilde{\psi}$ is increasing, we have $\tilde{\psi}\left(s_{0} h\left(s_{0}\right)\right) \leq \tilde{\psi}(r)=r s_{0}-s_{0}^{2} h\left(s_{0}\right) \leq \psi_{+}^{\prime}\left(s_{0}\right) s_{0}-s_{0}^{2} h\left(s_{0}\right)=s_{0}^{3} h_{+}^{\prime}\left(s_{0}\right)+2 s_{0}^{2} h\left(s_{0}\right)-s_{0}^{2} h\left(s_{0}\right) \leq$ $(c+2-1) s_{0}^{2} h\left(s_{0}\right)$.

Lemma 3.2. Function $\chi(s)=\operatorname{sh}(\sqrt{s})$ is $C$-sublinear and it has property (K). Moreover, $\chi(s+t) \geq$ $\frac{1}{2}(\chi(s)+\chi(t))$ for all $s, t>0$ and for every $c>0$ there exists $\tilde{c}>0$ such that $\chi(c s) \geq \tilde{c} \chi(s)$.

Proof. Since $h$ has property (K), we have for a fixed $K>0$

$$
\chi(K s)=K s h(\sqrt{K} \sqrt{s}) \leq K s C(\sqrt{K}) h(\sqrt{s})=K C(\sqrt{K}) \chi(s) .
$$

So, $\chi$ has property (K) and since it is increasing, it is also C-sublinear. Since $\chi$ is increasing, we also have $\chi(s+t) \geq \chi(s), \chi(s+t) \geq \chi(t)$ and therefore $\chi(s+t) \geq \frac{1}{2}(\chi(s)+\chi(t))$. From property (K) we have for any fixed $c>0$

$$
\chi(s)=\chi\left(\frac{1}{c} c s\right) \leq C\left(\frac{1}{c}\right) \chi(c s)=\frac{1}{\tilde{\tilde{c}}} \chi(c s)
$$

and the last property is proven.

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