### Stability in discrete equations with variable delays

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#### Abstract

In this paper we study the stability of the zero solution of difference equations with variable delays. In particular we consider the scalar delay equation

$$\Delta x(n) = -a(n)x(n - \tau(n))$$

and its generalization

$$\Delta x(n) = -\sum_{j=1}^{N} a_j(n) x(n - \tau_j(n)).$$

Fixed point theorems are used in the analysis.

Key words: Fixed point; Contraction mapping; Asymptotic stability Mathematics subject classifications: 34K13,34C25, 34G20.

## 1 Introduction

Let  $\mathbb{R}$  denote the real numbers,  $\mathbb{R}^+ = [0, \infty)$ ,  $\mathbb{Z}$  the integers,  $\mathbb{Z}^-$  the negative integers, and  $\mathbb{Z}^+ = \{x \in \mathbb{Z} \mid x \geq 0\}$ . In this paper we study the asymptotic stability of the zero solution of the scalar delay equation

$$\Delta x(n) = -a(n)x(n - \tau(n)) \tag{1.1}$$

and its generalization

$$\Delta x(n) = -\sum_{j=1}^{N} a_j(n) x(n - \tau_j(n)).$$
(1.2)

where  $a, a_j : \mathbb{Z}^+ \to \mathbb{R}$  and  $\tau, \tau_j : \mathbb{Z}^+ \to \mathbb{Z}^+$  with  $n - \tau(n) \to \infty$  as  $n \to \infty$ . For each  $n_0$ , define  $m_j(n_0) = \inf\{s - \tau_j(s) : s \ge n_0\}, m(n_0) = \min\{m_j(n_0) : 1 \le j \le N\}$ . Note that (1.2) becomes (1.1) for N = 1.

Recently, in [11], Raffoul studied the stability of the zero solution of (1.1) when

 $\tau(n) = r$ . Our objective in this research is to generalize the stability results in [11] to (1.2) for variable  $\tau_j(n)$ 's. For more on stability using fixed point theory we refer to [1],[7],[9],[11],[12] and for basic results on difference calculus we refer to [2] and [8]. We also refer to [3],[4],[5],[6] and [10] for other results on stability for difference equations.

**Remark 1.1** In [7], the author and Islam showed that the zero solution of the equation

$$x(n+1) = b(n)x(n) + a(n)x(n-\tau(n))$$

is asymptotically stable with one of the assumptions being that

$$\prod_{s=0}^{n-1} b(s) \to 0 \text{ as } n \to \infty.$$
(1.3)

However, as pointed out in [11], condition (1.3) cannot hold for (1.2) since b(n) = 1, for all  $n \in \mathbb{Z}$ . The results we obtain in this paper overcome the requirement of (1.3).

Let  $D(n_0)$  denote the set of bounded sequences  $\psi : [m(n_0), n_0] \to \mathbb{R}$  with the maximum norm ||.||. Also, let (B, ||.||) be the Banach space of bounded sequences  $\varphi : [m(n_0), \infty) \to \mathbb{R}$  with the maximum norm. Define the inverse of  $n - \tau_i(n)$  by  $g_i(n)$  if it exists and set

$$Q(n) = \sum_{j=1}^{N} b(g_j(n)),$$

where

$$\sum_{j=1}^{N} b(g_j(n)) = 1 - \sum_{j=1}^{N} a(g_j(n)).$$

For each  $(n_0, \psi) \in \mathbb{Z}^+ \times D(n_0)$ , a solution of (1.2) through  $(n_0, \psi)$  is a function  $x : [m(n_0), n_0 + \alpha) \to \mathbb{R}^n$  for some positive constant  $\alpha > 0$  such that x(t) satisfies (1.2) on  $[n_0, n_0 + \alpha)$  and  $x(n) = \psi(n)$  for  $n \in [m(n_0), n_0]$ . We denote such a solution by  $x(n) = x(n, n_0, \psi)$ . For a fixed  $n_0$ , we define

$$||\psi|| = \max\{|\psi(n)| : m(n_0) \le n \le n_0\}.$$

# 2 Stability

In this section we obtain conditions for the zero solution of (1.2) to be asymptotically stable.

We begin by rewriting (1.2) as

$$\Delta x(n) = -\sum_{j=1}^{N} a_j(g_j(n))x(n) + \Delta_n \sum_{j=1}^{N} \sum_{s=n-\tau_j(n)}^{n-1} a_j(g_j(s))x(s)$$
(2.1)

where  $\Delta_n$  represents that the difference is with respect to *n*. If we let

$$\sum_{j=1}^{N} b_j(g_j(n)) = 1 - \sum_{j=1}^{N} a_j(g_j(n)),$$

then (2.1) is equivalent to

$$x(n+1) = \sum_{j=1}^{N} b_j(g_j(n))x(n) + \Delta_n \sum_{j=1}^{N} \sum_{s=n-\tau_j(n)}^{n-1} a_j(g_j(s))x(s)$$
(2.2)

**Lemma 2.1** Suppose that  $Q(n) \neq 0$  for all  $n \in \mathbb{Z}^+$  and the inverse function  $g_j(n)$  of  $n - \tau_j(n)$  exists. Then x(n) is a solution of (2.2) if and only if

$$x(n) = \left(x(n_0) - \sum_{j=1}^N \sum_{s=n_0-\tau_j(n_0)}^{n_0-1} a_j(g_j(s))x(s)\right) \prod_{s=n_0}^{n-1} Q(s) + \sum_{j=1}^N \sum_{s=n-\tau_j(n)}^{n-1} a_j(g_j(s))x(s)$$
$$- \sum_{s=n_0}^{n-1} \left([1 - Q(s)] \prod_{k=s+1}^{n-1} Q(k) \sum_{j=1}^N \sum_{u=s-\tau_j(s)}^{s-1} a_j(g_j(u))x(u)\right), \ n \ge n_0.$$

**Proof.** By the variation of parameters formula we obtain

$$x(n) = x(n_0) \prod_{s=n_0}^{n-1} Q(s) + \sum_{k=0}^{n-1} \left( \prod_{s=k}^{n-1} Q(s) \Delta_k \sum_{j=1}^N \sum_{s=k-\tau_j(k)}^{k-1} a_j(g_j(s)) x(s) \right). (2.3)$$

Using the summation by parts formula we obtain

$$\sum_{k=0}^{n-1} \left( \prod_{s=k}^{n-1} Q(s) \Delta_k \sum_{j=1}^{N} \sum_{s=k-\tau_j(k)}^{k-1} a_j(g_j(s)) x(s) \right)$$
  
=  $\sum_{j=1}^{N} \sum_{s=n-\tau_j(n)}^{n-1} a_j(g_j(s)) x(s)$   
-  $\prod_{s=n_0}^{n-1} Q(s) \sum_{j=1}^{N} \sum_{s=n_0-\tau_j(n_0)}^{n_0-1} a_j(g_j(s)) x(s)$   
-  $\sum_{s=n_0}^{n-1} \left( [1-Q(s)] \prod_{k=s+1}^{n-1} Q(k) \sum_{j=1}^{N} \sum_{u=s-\tau_j(s)}^{s-1} a_j(g_j(u)) x(u) \right).$  (2.4)

Substituting (2.5) into (2.3) gives the desired result. This completes the proof of Lemma 2.1.

We next state and prove our main results.

**Theorem 2.1** Suppose that the inverse function  $g_j(n)$  of  $n - \tau_j(n)$  exists, and assume there exists a constant  $\alpha \in (0, 1)$  such that

$$\sum_{j=1}^{N} \sum_{s=n-\tau_j(n)}^{n-1} |a_j(g_j(s))| + \sum_{s=n_0}^{n-1} \left( \left| [1-Q(s)] \right| \right| \prod_{k=s+1}^{n-1} Q(k) \left| \sum_{j=1}^{N} \sum_{u=s-\tau_j(s)}^{s-1} |a_j(g_j(u))| \right) \le \alpha.$$
(2.5)

Moreover, assume that there exists a positive constant M such that

$$\Big|\prod_{s=n_0}^{n-1} Q(s)\Big| \le M.$$

Then the zero solution of (1.2) is stable.

**Proof.** Let  $\epsilon > 0$  be given. Choose  $\delta > 0$  such that

$$(M + M\alpha)\delta + \alpha\epsilon \le \epsilon.$$

Let  $\psi \in D(n_0)$  such that  $|\psi(n)| \leq \delta$ . Define

$$\mathbb{S} = \{ \varphi \in B : \varphi(n) = \psi(n) \text{ if } n \in [m(n_0), n_0], \ ||\varphi|| \le \epsilon \}.$$

Then  $(\mathbb{S}, ||.||)$  is a complete metric space where, ||.|| is the maximum norm.

Define the mapping  $P:S\to S$  by

$$(P\varphi)(n) = \psi(n) \text{ for } n \in [m(n_0), n_0]$$

and

$$(P\varphi)(n) = \left(\psi(n_0) - \sum_{j=1}^N \sum_{s=n_0-\tau_j(n_0)}^{n_0-1} a_j(g_j(s))\psi(s)\right) \prod_{s=n_0}^{n-1} Q(s) + \sum_{j=1}^N \sum_{s=n-\tau_j(n)}^{n-1} a_j(g_j(s))\varphi(s) - \sum_{s=n_0}^{n-1} \left( [1-Q(s)] \prod_{k=s+1}^{n-1} Q(k) \sum_{j=1}^N \sum_{u=s-\tau_j(s)}^{s-1} a_j(g_j(u))\varphi(u) \right).$$
(2.6)

Clearly,  $\mathbb{P}\varphi$  is continuous. We first show that P maps from S to S. By (2.6)

$$\begin{aligned} |(P\varphi)(n)| &\leq M\delta + M\alpha\delta + \Big\{\sum_{j=1}^{N}\sum_{s=n-\tau_j(n)}^{n-1}a_j(g_j(s)) \\ &+ \sum_{s=n_0}^{n-1}\left([1-Q(s)]\prod_{k=s+1}^{n-1}Q(k)\sum_{j=1}^{N}\sum_{u=s-\tau_j(s)}^{s-1}a_j(g_j(u))\varphi(u)\Big\}||\varphi|| \\ &\leq (M+M\alpha)\delta + \alpha\epsilon \\ &\leq \epsilon. \end{aligned}$$

Thus P maps from S into itself. We next show that P is a contraction. Let  $\zeta, \eta \in S$ . Then

$$\begin{aligned} |(P\zeta)(t) &- (P\eta)(t)| &\leq \Big\{ \sum_{j=1}^{N} \sum_{s=n-\tau_j(n)}^{n-1} |a_j(g_j(s))| \\ &+ \sum_{s=n_0}^{n-1} \Big( |[1-Q(s)]| \Big| \prod_{k=s+1}^{n-1} Q(k) \Big| \sum_{j=1}^{N} \sum_{u=s-\tau_j(s)}^{s-1} |a_j(g_j(u))| \Big) \Big\} ||\zeta - \eta|| \\ &\leq \alpha ||\zeta - \eta|| \end{aligned}$$

This shows that P is a contraction. Thus, by the contraction mapping principle, P has a unique fixed point in S which solves (1.2) and for any  $\varphi \in S$ ,  $||P\varphi|| \leq \epsilon$ . This proves that the zero solution of (1.2) is stable.

**Theorem 2.2** Assume that the hypotheses of Theorem 2.1 hold. Also assume that

$$\prod_{k=n_0}^{n-1} Q(k) \to 0 \text{ as } n \to \infty.$$
(2.7)

Then the zero solution of (1.2) is asymptotically stable.

**Proof.** We have already proved that the zero solution of (1.2) is stable. Let  $\psi \in D(n_0)$  such that  $|\psi(n)| \leq \delta$  and define

$$\mathbb{S}^* = \{ \varphi \in B : \varphi(n) = \psi(n) \text{ if } n \in [m(n_0), n_0], \ ||\varphi|| \le \epsilon \text{ and } \varphi(n) \to 0, \text{ as } n \to \infty \}.$$

Define  $P: S^* \to S^*$  by (2.6). From the proof of Theorem 2.2, the map P is a contraction and for every  $\varphi \in S^*$ ,  $||(P\varphi)|| \leq \epsilon$ .

We next show that  $(P\varphi)(n) \to 0$  as  $n \to \infty$ . The first term on the right side of (2.6) goes to zero because of condition (2.7). It is clear from (2.5) and the fact that  $\varphi(n) \to 0$  as  $n \to \infty$  that  $\sum_{j=1}^{N} \sum_{s=n-\tau_j(n)}^{n-1} |a_j(g_j(s))| |\varphi(s)| \to 0$  as  $n \to \infty$ .

Now we show that the last term on the right side of (2.6) goes to zero as  $n \to \infty$ . Since  $\varphi(n) \to 0$  and  $n - \tau_j(n) \to \infty$  as  $n \to \infty$ , for each  $\epsilon_1 > 0$ , there exists a  $N_1 > n_0$  such that  $s \ge N_1$  implies  $|\varphi(s - \tau_j(s))| < \epsilon_1$  for j = 1, 2, 3, ..., N. Thus for  $n \ge N_1$ , the last term,  $I_3$  in (2.6) satisfies

$$\begin{aligned} |I_{3}| &= \left| \sum_{s=n_{0}}^{n-1} \left( [1-Q(s)] \prod_{k=s+1}^{n-1} Q(k) \sum_{j=1}^{N} \sum_{u=s-\tau_{j}(s)}^{s-1} a_{j}(g_{j}(u))\varphi(u) \right) \right| \\ &\leq \left| \sum_{s=n_{0}}^{N_{1}-1} \left( |[1-Q(s)]| \right| \prod_{k=s+1}^{n-1} Q(k) \right| \sum_{j=1}^{N} \sum_{u=s-\tau_{j}(s)}^{s-1} |a_{j}(g_{j}(u))| |\varphi(u)| \right) \\ &+ \left| \sum_{s=N_{1}}^{n-1} \left( |[1-Q(s)]| \right| \prod_{k=s+1}^{n-1} Q(k) \right| \sum_{j=1}^{N} \sum_{u=s-\tau_{j}(s)}^{s-1} |a_{j}(g_{j}(u))| |\varphi(u)| \right) \\ &\leq \left| \max_{\sigma \ge m(n_{0})} |\varphi(\sigma)| \sum_{s=n_{0}}^{N_{1}-1} \left( |[1-Q(s)]| \right| \prod_{k=s+1}^{n-1} Q(k) \right| \sum_{j=1}^{N} \sum_{u=s-\tau_{j}(s)}^{s-1} |a_{j}(g_{j}(u))| \right) \\ &+ \left| \epsilon_{1} \sum_{s=N_{1}}^{n-1} \left( |[1-Q(s)]| \right| \prod_{k=s+1}^{n-1} Q(k) \right| \sum_{j=1}^{N} \sum_{u=s-\tau_{j}(s)}^{s-1} |a_{j}(g_{j}(u))| \right) \end{aligned}$$

By (2.7), there exists  $N_2 > N_1$  such that  $n \ge N_2$  implies

$$\max_{\sigma \ge m(n_0)} |\varphi(\sigma)| \sum_{s=n_0}^{N_1-1} \left( |[1-Q(s)]| \Big| \prod_{k=s+1}^{n-1} Q(k) \Big| \sum_{j=1}^N \sum_{u=s-\tau_j(s)}^{s-1} |a_j(g_j(u))| \right) < \epsilon_1.$$

Apply (2.5) to obtain  $|I_3| \leq \epsilon_1 + \epsilon_1 \alpha < 2\epsilon_1$ . Thus,  $I_3 \to 0$  as  $n \to \infty$ . Hence  $(P\varphi)(n) \to 0$  as  $n \to \infty$ , and so  $P\varphi \in S^*$ .

By the contraction mapping principle, P has a unique fixed point that solves (1.2) and goes to zero as n goes to infinity. Therefore, the zero solution of (1.2) is asymptotically stable.

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(Received November 14, 2008)