# VIABILITY PROBLEM WITH PERTURBATION IN HILBERT SPACE 

MYELKEBIR AITALIOUBRAHIM AND SAID SAJID

University Hassan II-Mohammedia, U.F.R Mathematics and applications, F.S.T, BP 146, Mohammedia, Morocco.<br>E-mail:saidsajid@hotmail.com and aitalifr@yahoo.fr

Abstract. This paper deals with the existence result of viable solutions of the differential inclusion

$$
\begin{gathered}
\dot{x}(t) \in f(t, x(t))+F(x(t)) \\
x(t) \in K \text { on }[0, T],
\end{gathered}
$$

where $K$ is a locally compact subset in separable Hilbert space $H,(f(s, \cdot))_{s}$ is an equicontinuous family of measurable functions with respect to $s$ and $F$ is an upper semi-continuous set-valued mapping with compact values contained in the Clarke subdifferential $\partial_{c} V(x)$ of an uniformly regular function $V$.

Key words: Regularity, upper semi-continuous, equicontinuous perturbation, Clarke subdifferential.
Mathematics subject classification: 34A60, 49J52.

## 1. Introduction

Existence result of local solution for differential inclusion with upper semi-continuous and cyclically monotone right hand-side whose values in finite-dimensional space, was first established by Bressan, Cellina and Colombo (see [6]). The authors exploited rich properties of subdifferential of convex lower semi-continuous function; in order to overcome the weakly convergence of derivatives of approximate solutions, they used the basic relation (see [7])

$$
\frac{d}{d t} V(x(t))=\|\dot{x}(t)\|^{2}
$$

Later, Ancona, Cellina and Colombo (see [1]), under the same hypotheses as the above paper, extend this result to the perturbed problem

$$
\dot{x}(t) \in f(t, x(t))+F(x(t))
$$

where $f(\cdot, \cdot)$ is a Carathéodory function.
This program of research was pursued by a series of works. In the first one (see [9]), Truong proved a viability result for similar problem, where the perturbation $f$ is replaced by a globally continuous set-valued mapping $G$ with values in finitedimensional space. This result was extended by Bounkhel (see [4]) for a similar
problem, where $F$ is not cyclically monotone but contained in the Clarke subdifferential of locally Lipschitz uniformly regular function. However under very strong assumptions namely, the space of states is finite-dimensional and the following tangential condition

$$
(G(t, x)+F(x)) \subset T_{K}(x)
$$

where $T_{K}(x)$ is the contingent cone at $x$ to $K$.
Recently, Morchadi and Sajid (see [8]) proved an exact viability version of the work of Ancona and Colombo assuming the same hypotheses and the following tangential condition
$\forall(t, x) \in \mathbb{R} \times K, \exists v \in F(x)$ such that

$$
\begin{equation*}
\lim _{h \mapsto 0^{+}} \inf \frac{1}{h} d_{K}\left(x+h v+\int_{t}^{t+h} f(s, x) d s\right)=0 \tag{1.1}
\end{equation*}
$$

Remark that in all the above works, the convexity assumption of $V$ and/or the finite-dimensional hypothesis of the space of states were widely used in the proof.

This paper is devoted to establish a local solution of the problem

$$
\begin{gathered}
\dot{x}(t) \in f(t, x(t))+F(x(t)), \quad F(x(t)) \subset \partial_{c} V(x(t)) \\
x(t) \in K \subset H,
\end{gathered}
$$

where $K$ is a locally compact subset of a separable Hilbert space $H, F$ is an upper semi-continuous multifunction, $\partial_{c} V$ denotes the Clarke subdifferential of a locally lipschitz function $V$ and the set $\{f(s,):. s \in \mathbb{R}\}$ is equicontinuous, where for each $x \in K, s \mapsto f(s, x)$ is measurable and the same tangential condition (1.1). One case deserves mentioning: when $f$ is globally continuous, the condition (1.1) is weaker than the following

$$
(f(t, x)+F(x)) \cap T_{K}(x) \neq \emptyset
$$

To remove the convexity assumption of $V$ and the finite-dimensional hypothesis of $H$, we rely on some properties of Clarke subdifferential of uniformly regular function and the local compactness of $K$.

## 2. Preliminaries and statement of the main result

Let $H$ be a real separable Hilbert space with the norm $\|\cdot\|$ and the scalar product $<\cdot, \cdot>$. For $x \in H$ and $r>0$ let $B(x, r)$ be the open ball centered at $x$ with radius $r$ and $\bar{B}(x, r)$ be its closure and put $B=B(0,1)$.

Let us recall the definition of the Clarke subdifferential and the concept of regularity that will be used in the sequel.

Definition 2.1. Let $V: H \rightarrow \mathbb{R} \cup\{+\infty\}$ be a lower semi-continuous function and $x$ be any point where $V$ is finite. The Clarke subdifferential of $V$ at $x$ is defined by

$$
\partial_{c} V(x):=\left\{y \in H:<y, h>\leq V^{\uparrow}(x, h), \text { for all } h \in H\right\},
$$

where $V^{\dagger}(x, h)$ is the generalized Rockafellar directional derivative given by

$$
V^{\uparrow}(x, h):=\limsup _{x^{\prime} \rightarrow x, V\left(x^{\prime}\right) \rightarrow V(x), t \rightarrow 0} \inf _{h^{\prime} \rightarrow h} \frac{V\left(x^{\prime}+t h^{\prime}\right)-V\left(x^{\prime}\right)}{t}
$$

EJQTDE, 2007 No. 7, p. 2

Definition 2.2. Let $V: H \rightarrow \mathbb{R} \cup\{+\infty\}$ be a lower semi-continuous function and let $U \subset$ DomV be a nonempty open subset. We will say that $V$ is uniformly regular over $U$ if there exists a positive number $\beta$ such that for all $x \in U$ and for all $\xi \in \partial_{p} V(x)$ one has

$$
<\xi, x^{\prime}-x>\leq V\left(x^{\prime}\right)-V(x)+\beta\left\|x^{\prime}-x\right\|^{2} \quad \text { for all } x^{\prime} \in U .
$$

$\partial_{p} V(x)$ denotes the proximal subdifferential of $V$ at $x$ which is the set of all $y \in H$ for which there exist $\delta, \sigma>0$ such that for all $x^{\prime} \in x+\delta \bar{B}$

$$
<y, x^{\prime}-x>\leq V\left(x^{\prime}\right)-V(x)+\sigma\left\|x^{\prime}-x\right\|^{2} .
$$

We say that $V$ is uniformly regular over closed set $S$ if there exists an open set $U$ containing $S$ such that $V$ is uniformly regular over $U$. For more details on the concept of regularity, we refer the reader to [4].

Proposition 2.3. [3, 4] Let $V: H \rightarrow \mathbb{R}$ be a locally Lipschitz function and $S$ a nonempty closed set. If $V$ is uniformly regular over $S$, then the following conditions holds:
(a) The proximal subdifferential of $V$ is closed over $S$, that is, for every $x_{n} \rightarrow$ $x \in S$ with $x_{n} \in S$ and every $\xi_{n} \rightarrow \xi$ with $\xi_{n} \in \partial_{p} V\left(x_{n}\right)$ one has $\xi \in$ $\partial_{p} V(x)$.
(b) The proximal subdifferential of $V$ coincides with the Clarke subdifferential of $V$ for any point $x$.
(c) The proximal subdifferential of $V$ is upper hemicontinuous over $S$, that is, the support function $x \mapsto \sigma\left(v, \partial_{p} V(x)\right)$ is u.s.c. over $S$ for every $v \in H$.

Now let us state the main result.
Let $V: H \rightarrow \mathbb{R}$ be a locally Lipschitz function and $\beta$-uniformly regular over $K \subset H$. Assume that
(H1) $K$ is a nonempty locally compact subset in $H$;
(H2) $F: K \rightarrow 2^{H}$ is an upper semi-continuous set valued map with compact values satisfying

$$
F(x) \subset \partial_{c} V(x) \text { for all } x \in K
$$

(H3) $f: \mathbb{R} \times H \rightarrow H$ is a function with the following properties:
(1) For all $x \in H, t \mapsto f(t, x)$ is measurable,
(2) The family $\{f(s,):. s \in \mathbb{R}\}$ is equicontinuous,
(3) For all bounded subset $S$ of $H$, there exists $M>0$ such that

$$
\|f(t, x)\| \leq M, \forall(t, x) \in \mathbb{R} \times S
$$

(H4) (Tangential condition) $\forall(t, x) \in \mathbb{R} \times K, \exists v \in F(x)$ such that

$$
\lim _{h \mapsto 0^{+}} \inf \frac{1}{h} d_{K}\left(x+h v+\int_{t}^{t+h} f(s, x) d s\right)=0
$$

EJQTDE, 2007 No. 7, p. 3

For any $x_{0} \in K$, consider the problem:

$$
\left\{\begin{array}{l}
\dot{x}(t) \in f(t, x(t))+F(x(t)) \quad \text { a.e }  \tag{2.1}\\
x(0)=x_{0} \\
x(t) \in K
\end{array}\right.
$$

Theorem 2.4. If assumptions (H1)-(H4) are satisfied, then there exists $T>0$ such that the problem (2.1) admits a solution on $[0, T]$.

## 3. Proof of the main result

Choose $r>0$ such that $K_{0}=K \cap\left(x_{0}+r \bar{B}\right)$ is compact and $V$ is Lipschitz continuous on $x_{0}+r \bar{B}$ with Lipschitz constant $\lambda>0$. Then $\partial_{c} V(x) \subset \lambda \bar{B}$ for every $x \in K_{0}$. Let $M>0$ such that

$$
\begin{equation*}
\|f(t, x)\| \leq M, \forall(t, x) \in \mathbb{R} \times\left(x_{0}+r \bar{B}\right) \tag{3.1}
\end{equation*}
$$

Set

$$
\begin{equation*}
T=\frac{r}{2(\lambda+1+M)} . \tag{3.2}
\end{equation*}
$$

In the sequel, we will use the following important Lemma. It will play a crucial role in the proof of the main result.

Lemma 3.1. If assumptions (H1)-(H4) are satisfied, then for all $0<\varepsilon<\inf (T, 1)$, there exists $\eta>0(\eta<\varepsilon)$ such that $\forall(t, x) \in[0, T] \times K_{0}, \exists h_{t, x} \in[\eta, \varepsilon], u \in F(x)+\frac{1}{h_{t, x}} \int_{t}^{t+h_{t, x}} f(s, x) d s+\frac{\varepsilon}{T} B, y_{t, x} \in K_{0}$ and $v \in F\left(y_{t, x}\right)$ such that

$$
\left(x+h_{t, x} u\right) \in K \cap B\left(x+h_{t, x} v+\int_{t}^{t+h_{t, x}} f(s, x) d s, \lambda+M+1\right)
$$

Proof. Let $(t, x) \in[0, T] \times K_{0}$, be fixed, let $0<\varepsilon<\inf (T, 1)$. Since $F$ is u.s.c on $x$, then there exists $\delta_{x}>0$ such that

$$
F(y) \subset F(x)+\frac{\varepsilon}{2 T} B, \text { for all } y \in B\left(x, \delta_{x}\right)
$$

Let $(s, y) \in[0, T] \times K_{0}$. By the tangential condition, there exists $v \in F(y)$ and $\left.\left.h_{s, y} \in\right] 0, \varepsilon\right]$ such that

$$
d_{K}\left(y+h_{s, y} v+\int_{s}^{s+h_{s, y}} f(\tau, y) d \tau\right)<h_{s, y} \frac{\varepsilon}{4 T}
$$

Consider the subset

$$
N(s, y)=\left\{(t, z) \in \mathbb{R} \times H / d_{K}\left(z+h_{s, y} v+\int_{t}^{t+h_{s, y}} f(\tau, z) d \tau\right)<h_{s, y} \frac{\varepsilon}{4 T}\right\}
$$

Since

$$
\|f(\tau, z)\| \leq M, \forall(\tau, z) \in \mathbb{R} \times \bar{B}\left(x_{0}, r\right)
$$

EJQTDE, 2007 No. 7, p. 4
then the dominated convergence theorem applied to the sequence $\left(\chi_{\left[t, t+h_{s, y}\right]} f(\cdot, \cdot)\right)_{t}$ of functions shows that the function

$$
(l, z) \mapsto z+h_{s, y} v+\int_{l}^{l+h_{s, y}} f(\tau, z) d \tau
$$

is continuous. So that, the function

$$
(l, z) \mapsto d_{K}\left(z+h_{s, y} v+\int_{l}^{l+h_{s, y}} f(\tau, z) d \tau\right)
$$

is continuous and consequently $N(s, y)$ is open. Moreover, since $(s, y)$ belongs to $N(s, y)$, there exists a ball $B\left((s, y), \eta_{s, y}\right)$ of radius $\eta_{s, y}<\delta_{x}$ contained in $N(s, y)$, therefore, the compact subset $[0, T] \times K_{0}$ can be covered by $q$ such balls $B\left(\left(s_{i}, y_{i}\right)\right.$, $\eta_{s_{i}, y_{i}}$ ). For simplicity, we set

$$
h_{s_{i}, y_{i}}:=h_{i} \text { and } \eta_{i}:=\eta_{s_{i}, y_{i}}, i=1, \ldots, q .
$$

Put $\eta=\min \left\{h_{i} / 1 \leq i \leq q\right\}$ and let $i \in\{1, \ldots, q\}$ such that $(t, x) \in B\left(\left(s_{i}, y_{i}\right), \eta_{i}\right)$, hence $(t, x) \in N\left(s_{i}, y_{i}\right)$. Then there exists $v_{i} \in F\left(y_{i}\right)$ such that

$$
d_{K}\left(x+h_{i} v_{i}+\int_{t}^{t+h_{i}} f(\tau, x) d \tau\right)<h_{i} \frac{\varepsilon}{4 T}
$$

Let $x_{i} \in K$ such that
$\frac{1}{h_{i}}\left\|x_{i}-\left(x+h_{i} v_{i}+\int_{t}^{t+h_{i}} f(\tau, x) d \tau\right)\right\| \leq \frac{1}{h_{i}} d_{K}\left(x+h_{i} v_{i}+\int_{t}^{t+h_{i}} f(\tau, x) d \tau\right)+\frac{\varepsilon}{4 T}$.
Hence

$$
\left\|\frac{x_{i}-x}{h_{i}}-\left(v_{i}+\frac{1}{h_{i}} \int_{t}^{t+h_{i}} f(\tau, x) d \tau\right)\right\|<\frac{\varepsilon}{2 T} .
$$

Set

$$
u=\frac{x_{i}-x}{h_{i}}
$$

then $x_{i}=x+h_{i} u \in K$ and

$$
u \in\left(\frac{1}{h_{i}} \int_{t}^{t+h_{i}} f(\tau, x) d \tau+F\left(y_{i}\right)+\frac{\varepsilon}{2 T} B\right) .
$$

Since $\left\|x-y_{i}\right\|<\eta_{i}<\delta_{x}$ we have

$$
F\left(y_{i}\right) \subset F(x)+\frac{\varepsilon}{2 T} B,
$$

then

$$
u \in\left(\frac{1}{h_{i}} \int_{t}^{t+h_{i}} f(\tau, x) d \tau+F(x)+\frac{\varepsilon}{T} B\right)
$$

On the other hand, since $x \in K$, we have

$$
\left\|x_{i}-\left(x+h_{i} v_{i}+\int_{t}^{t+h_{i}} f(\tau, x) d \tau\right)\right\| \leq d_{K}\left(x+h_{i} v_{i}+\int_{t}^{t+h_{i}} f(\tau, x) d \tau\right)+\frac{\varepsilon}{4 T}
$$

$$
\begin{aligned}
& \leq\left\|h_{i} v_{i}+\int_{t}^{t+h_{i}} f(\tau, x) d \tau\right\|+\frac{\varepsilon}{4 T} \\
& \leq h_{i}(\lambda+M)+1<\lambda+M+1
\end{aligned}
$$

Thus $x_{i} \in B\left(x+h_{i} v_{i}+\int_{t}^{t+h_{i}} f(\tau, x) d \tau, \lambda+M+1\right)$.

Now, we are able to prove the main result. Our approach consists of constructing, in a first step, a sequence of approximate solutions and deduce, in a second step, from available estimates that a subsequence converges to a solution of (2.1).

Step 1. Approximate solutions. Let $x_{0} \in K_{0}$ and $0<\varepsilon<\inf (T, 1)$. By Lemma 3.1, there exist $\eta>0, h_{0} \in[\eta, \varepsilon], u_{0} \in\left(\frac{1}{h_{0}} \int_{0}^{h_{0}} f\left(s, x_{0}\right) d s+F\left(x_{0}\right)+\frac{\varepsilon}{T} B\right)$, $y_{0} \in K_{0}$ and $v_{0} \in F\left(y_{0}\right)$ such that

$$
x_{1}=x_{0}+h_{0} u_{0} \in K \cap B\left(x_{0}+h_{0} v_{0}+\int_{0}^{h_{0}} f\left(s, x_{0}\right) d s, \lambda+M+1\right) .
$$

Then by (H2), (3.1) and (3.2), we have

$$
\left\|x_{1}-x_{0}\right\|=\left\|h_{0} u_{0}\right\| \leq(\lambda+1+M) T<r
$$

and thus $x_{1} \in K_{0}$. Set $h_{-1}=0$. By induction, for $q \geq 2$ and for every $p=$ $1, \ldots, q-1$, we construct the sequences $\left(h_{p}\right)_{p} \subset[\eta, \varepsilon],\left(\left(x_{p}\right)_{p},\left(y_{p}\right)_{p}\right) \subset K_{0} \times K_{0}$ and $\left(\left(u_{p}\right)_{p},\left(v_{p}\right)_{p}\right) \subset H \times H$ such that $\sum_{p=1}^{q-1} h_{p} \leq T$ and

$$
\left\{\begin{array}{l}
x_{p}=x_{p-1}+h_{p-1} u_{p-1} ; \\
x_{p} \in K \cap B\left(x_{p-1}+h_{p-1} v_{p-1}+\int_{\sum_{i=0}^{p-2} h_{i}}^{\sum_{i=0}^{p-1} h_{i}} f\left(s, x_{p-1}\right) d s, \lambda+M+1\right) \\
u_{p} \in\left(\frac{1}{h_{p}} \int_{\sum_{i=0}^{p-1} h_{i}}^{\sum_{i=0}^{p} h_{i}} f\left(s, x_{p}\right) d s+F\left(x_{p}\right)+\frac{\varepsilon}{T} B\right) \\
v_{p} \in F\left(y_{p}\right)
\end{array}\right.
$$

Since $h_{i} \geq \eta>0$ there exists an integer $s$ such that

$$
\sum_{i=0}^{s-1} h_{i}<T \leq \sum_{i=0}^{s} h_{i} .
$$

Then we have constructed the sequences $\left(h_{p}\right)_{p} \subset[\eta, \varepsilon],\left(\left(x_{p}\right)_{p},\left(y_{p}\right)_{p}\right) \subset K_{0} \times K_{0}$ and $\left(\left(u_{p}\right)_{p},\left(v_{p}\right)_{p}\right) \subset H \times H$ such that for every $p=1, \ldots, s$, we have
(i) $x_{p}=x_{p-1}+h_{p-1} u_{p-1}$;
(ii) $x_{p} \in K \cap B\left(x_{p-1}+h_{p-1} v_{p-1}+\int_{\sum_{i=0}^{p-2} h_{i}}^{\sum_{i=0}^{p-1} h_{i}} f\left(s, x_{p-1}\right) d s, \lambda+M+1\right)$;

EJQTDE, 2007 No. 7, p. 6
(iii) $u_{p} \in F\left(x_{p}\right)+\frac{1}{h_{p}} \int_{\sum_{i=0}^{p-1} h_{i}}^{\sum_{i=0}^{p} h_{i}} f\left(s, x_{p}\right) d s+\frac{\varepsilon}{T} B$;
(iv) $v_{p} \in F\left(y_{p}\right)$.

By induction, for all $p=1, \ldots, s$ we have

$$
x_{p}=x_{0}+\sum_{i=0}^{p-1} h_{i} u_{i} .
$$

Moreover by (iii), (H2), (3.1), (3.2) and because $\sum_{i=0}^{p-1} h_{i}<T$, we have

$$
\begin{equation*}
\left\|x_{p}-x_{0}\right\|=\left\|\sum_{i=0}^{p-1} h_{i} u_{i}\right\| \leq \sum_{i=0}^{p-1} h_{i}\left\|u_{i}\right\| \leq \sum_{i=0}^{p-1} h_{i}(\lambda+1+M)<r, \tag{3.3}
\end{equation*}
$$

hence $x_{p} \in K_{0}$.
For any nonzero integ $k$ and for every integer $q=0, \ldots, s-1$ denote by $h_{q}^{k}$ a real associated to $\varepsilon=\frac{1}{k}$ and $x=x_{q}$ given by Lemma 3.1. Consider the sequence $\left(\tau_{k}^{q}\right)_{k}$ defined as the following

$$
\left\{\begin{array}{l}
\tau_{k}^{0}=0, \tau_{k}^{s+1}=T \\
\tau_{k}^{q}=h_{0}^{k}+\ldots+h_{q-1}^{k} \quad \text { if } 1 \leq q \leq s
\end{array}\right.
$$

and define on $[0, T]$ the sequence of functions $\left(x_{k}(.)\right)_{k}$ by

$$
\left\{\begin{array}{l}
x_{k}(t)=x_{q-1}+\left(t-\tau_{k}^{q-1}\right) u_{q-1}, \quad \forall t \in\left[\tau_{k}^{q-1}, \tau_{k}^{q}\right] \\
x_{k}(0)=x_{0}
\end{array}\right.
$$

Step 2. Convergence of approximate solutions. By definition of $x_{k}($.$) , for all$ $t \in\left[\tau_{k}^{q-1}, \tau_{k}^{q}\right]$ we have $\dot{x}_{k}(t)=u_{q-1}$. By (iii), (H2), (3.1), for a. e. $t \in[0, T]$, we have

$$
\left\|\dot{x}_{k}(t)\right\| \leq \lambda+1+M
$$

On the other hand, by (ii), (iv), (H2), (3.1) and (3.3) we have

$$
\begin{aligned}
\left\|x_{q}\right\| \leq & \left\|x_{q}-\left(x_{q-1}+h_{q-1}^{k} v_{q-1}+\int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s\right)\right\| \\
& +\left\|x_{q-1}+h_{q-1}^{k} v_{q-1}+\int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s\right\| \\
\leq & \lambda+M+1+\left\|x_{0}-\left(x_{0}-x_{q-1}\right)+h_{q-1}^{k} v_{q-1}+\int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s\right\| \\
\leq & \lambda+M+1+\left\|x_{0}\right\|+\left\|x_{0}-x_{q-1}\right\|+h_{q-1}^{k}\left\|v_{q-1}\right\|+h_{q-1}^{k} M \\
\leq & \lambda+M+1+\left\|x_{0}\right\|+r+\lambda+M \\
< & 2(\lambda+M+1)+\left\|x_{0}\right\|+r=R
\end{aligned}
$$

Then $x_{q} \in K_{0} \cap \bar{B}(0, R)=K_{1}$. By construction, for all $t \in\left[\tau_{k}^{q-1}, \tau_{k}^{q}\right]$ we have

$$
x_{k}(t)=x_{q-1}+\left(t-\tau_{k}^{q-1}\right) u_{q-1}=x_{q-1}+\frac{\left(t-\tau_{k}^{q-1}\right)}{h_{q-1}^{k}}\left(x_{q}-x_{q-1}\right) .
$$

EJQTDE, 2007 No. 7, p. 7

Also since $0 \leq t-\tau_{k}^{q-1} \leq \tau_{k}^{q}-\tau_{k}^{q-1}=h_{q-1}^{k}$, we have

$$
0 \leq \frac{\left(t-\tau_{k}^{q-1}\right)}{h_{q-1}^{k}} \leq 1
$$

Then

$$
\frac{\left(t-\tau_{k}^{q-1}\right)}{h_{q-1}^{k}}\left(x_{q}-x_{q-1}\right) \in \overline{c o}\left\{\{0\} \cup\left(K_{1}-K_{0}\right)\right\}
$$

hence $x_{k}(t) \in K_{0}+\overline{c o}\left\{\{0\} \cup\left(K_{1}-K 0\right)\right\}$ which is compact. Therefore, we can select a subsequence, again denoted by $\left(x_{k}(.)\right)_{k}$ which converges uniformly to an absolutely continuous function $x($.$) on [0, T]$, moreover $\dot{x}_{k}($.$) converges weakly to$ $\dot{x}($.$) in L^{2}([0, T], H)$. The family of approximate solution $x_{k}($.$) satisfies the following$ property.

Proposition 3.2. For every $t \in[0, T]$, there exists $q \in\{1, \ldots, s+1\}$ such that

$$
\lim _{k \rightarrow+\infty} d_{g r F}\left(\left(x_{k}(t), \dot{x}_{k}(t)-\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s\right)\right)=0 .
$$

Proof. Let $t \in[0, T]$, there exists $q \in\{1, \ldots, s+1\}$ such that $t \in\left[\tau_{k}^{q-1}, \tau_{k}^{q}\right]$ and $\lim _{k \rightarrow+\infty} \tau_{k}^{q-1}=t$. Since

$$
\begin{equation*}
\dot{x}_{k}(t)-\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s \in F\left(x_{q-1}\right)+\frac{1}{k T} B \tag{3.4}
\end{equation*}
$$

we have

$$
d_{g r F}\left(\left(x_{k}(t), \dot{x}_{k}(t)-\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s\right)\right) \leq\left\|x_{k}(t)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|+\frac{1}{k T}
$$

hence

$$
\lim _{k \rightarrow+\infty} d_{g r F}\left(\left(x_{k}(t), \dot{x}_{k}(t)-\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s\right)\right)=0
$$

## Claim 3.3.

$$
\lim _{k \rightarrow+\infty} \frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s=f(t, x(t))
$$

Proof. Fix any $t \in[0, T]$, there exists $q \in\{1, \ldots, s+1\}$ such that $t \in\left[\tau_{k}^{q-1}, \tau_{k}^{q}\right]$, $\lim _{k \rightarrow+\infty} \tau_{k}^{q-1}=\lim _{k \rightarrow+\infty} \tau_{k}^{q}=t$ and $\lim _{k \rightarrow+\infty} x_{k}\left(\tau_{k}^{q-1}\right)=x(t)$. Put

$$
G(t, y)=\int_{0}^{t} f(s, y) d s
$$

Note that the function $G$ is differentiable on $t$ and

$$
\frac{d G}{d t}(t, y)=f(t, y)
$$

We have

$$
\begin{aligned}
& \left\|\frac{G\left(\tau_{k}^{q}, x(t)\right)-G\left(\tau_{k}^{q-1}, x(t)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}}-f(t, x(t))\right\| \\
\leq & \left\|\frac{G\left(\tau_{k}^{q}, x(t)\right)-G\left(\tau_{k}^{q-1}, x(t)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}}-\frac{G(t, x(t))-G\left(\tau_{k}^{q-1}, x(t)\right)}{t-\tau_{k}^{q-1}}\right\| \\
& +\left\|\frac{G(t, x(t))-G\left(\tau_{k}^{q-1}, x(t)\right)}{t-\tau_{k}^{q-1}}-f(t, x(t))\right\| .
\end{aligned}
$$

On the other hand

$$
\begin{aligned}
& \left\|\frac{G\left(\tau_{k}^{q}, x(t)\right)-G\left(\tau_{k}^{q-1}, x(t)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}}-\frac{G(t, x(t))-G\left(\tau_{k}^{q-1}, x(t)\right)}{t-\tau_{k}^{q-1}}\right\| \\
= & \left\|\frac{\tau_{k}^{q}-t}{\tau_{k}^{q}-\tau_{k}^{q-1}}\left(\frac{G\left(\tau_{k}^{q}, x(t)\right)-G(t, x(t))}{\tau_{k}^{q}-t}-\frac{G\left(\tau_{k}^{q-1}, x(t)\right)-G(t, x(t))}{\tau_{k}^{q-1}-t}\right)\right\| \\
\leq & \left\|\frac{G\left(\tau_{k}^{q}, x(t)\right)-G(t, x(t))}{\tau_{k}^{q}-t}-f(t, x)\right\| \\
& +\left\|\frac{G\left(\tau_{k}^{q-1}, x(t)\right)-G(t, x(t))}{\tau_{k}^{q-1}-t}-f(t, x(t))\right\| .
\end{aligned}
$$

Hence

$$
\begin{aligned}
& \| \frac{G\left(\tau_{k}^{q}, x(t)\right)-G\left(\tau_{k}^{q-1}, x(t)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}-f(t, x(t)) \|} \begin{array}{l}
\leq\left\|\frac{G\left(\tau_{k}^{q}, x(t)\right)-G(t, x(t))}{\tau_{k}^{q}-t}-f(t, x(t))\right\| \\
+2\left\|\frac{G(t, x(t))-G\left(\tau_{k}^{q-1}, x(t)\right)}{t-\tau_{k}^{q-1}}-f(t, x(t))\right\| .
\end{array} . . \begin{array}{l}
\|
\end{array} .
\end{aligned}
$$

As

$$
\lim _{k \rightarrow+\infty} \frac{G\left(\tau_{k}^{q}, x(t)\right)-G(t, x(t))}{\tau_{k}^{q}-t}=\frac{d G}{d t}(t, x(t))=f(t, x(t))
$$

and

$$
\lim _{k \rightarrow+\infty} \frac{G\left(\tau_{k}^{q-1}, x(t)\right)-G(t, x(t))}{\tau_{k}^{q-1}-t}=\frac{d G}{d t}(t, x(t))=f(t, x(t)),
$$

we have

$$
\begin{equation*}
\lim _{k \rightarrow+\infty} \frac{G\left(\tau_{k}^{q}, x(t)\right)-G\left(\tau_{k}^{q-1}, x(t)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}}=f(t, x(t)) \tag{3.5}
\end{equation*}
$$

Put

$$
\rho_{k}=\left\|\frac{G\left(\tau_{k}^{q}, x(t)\right)-G\left(\tau_{k}^{q-1}, x(t)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}}-f(t, x(t))\right\| .
$$

On the other hand we have

$$
\begin{aligned}
& \left\|\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{k}\left(\tau_{k}^{q-1}\right)\right) d s-f(t, x(t))\right\| \\
= & \left\|\frac{G\left(\tau_{k}^{q}, x_{k}\left(\tau_{k}^{q-1}\right)\right)-G\left(\tau_{k}^{q-1}, x_{k}\left(\tau_{k}^{q-1}\right)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}}-f(t, x(t))\right\| \\
\leq & \left\|\frac{G\left(\tau_{k}^{q}, x_{k}\left(\tau_{k}^{q-1}\right)\right)-G\left(\tau_{k}^{q-1}, x_{k}\left(\tau_{k}^{q-1}\right)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}}-\frac{G\left(\tau_{k}^{q}, x(t)\right)-G\left(\tau_{k}^{q-1}, x(t)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}}\right\|+\rho_{k} \\
= & \left\|\frac{1}{\tau_{k}^{q}-\tau_{k}^{q-1}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}\left(f\left(s, x_{k}\left(\tau_{k}^{q-1}\right)\right)-f(s, x(t))\right) d s\right\|+\rho_{k} .
\end{aligned}
$$

Since the family $\{f(s, \cdot): s \in \mathbb{R}\}$ is equicontinuous, then there exists $k_{0}$ such that

$$
\left\|f\left(s, x_{k}\left(\tau_{k}^{q-1}\right)\right)-f(s, x(t))\right\| \leq \frac{1}{k} \text { for all } k \geq k_{0} \text { and for all } s \in \mathbb{R}
$$

consequently we have for $k \geq k_{0}$

$$
\left\|\frac{G\left(\tau_{k}^{q}, x_{k}\left(\tau_{k}^{q-1}\right)\right)-G\left(\tau_{k}^{q-1}, x_{k}\left(\tau_{k}^{q-1}\right)\right)}{\tau_{k}^{q}-\tau_{k}^{q-1}}-f(t, x(t))\right\| \leq \frac{1}{k}+\rho_{k}
$$

By (3.5), the last term converges to 0 . This completes the proof of the Claim.

The function $x($.$) has the following property$
Proposition 3.4. For all $t \in[0, T]$, we have $\dot{x}(t)-f(t, x(t)) \in \partial_{c} V(x(t))$.
Proof. The weak convergence of $\dot{x}_{k}($.$) to \dot{x}($.$) in L^{2}([0, T], H)$ and the Mazur's Lemma entail

$$
\dot{x}(t) \in \bigcap_{k} \overline{c o}\left\{\dot{x}_{m}(t): m \geq k\right\}, \text { for a.e. on }[0, T] .
$$

Fix any $t \in[0, T]$, there exists $q \in\{1, \ldots, s+1\}$ such that $t \in\left[\tau_{k}^{q-1}, \tau_{k}^{q}\right]$ and $\lim _{k \rightarrow+\infty} \tau_{k}^{q-1}=t$. Then for all $y \in H$

$$
<y, \dot{x}(t)>\leq \inf _{m} \sup _{k \geq m}<y, \dot{x}_{k}(t)>.
$$

Since $F(x) \subset \partial_{c} V(x)$, then by (3.4), one has

$$
\dot{x}_{k}(t) \in \partial_{c} V\left(x_{q-1}\right)+\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s+\frac{1}{k T} B .
$$

Thus for all $m$

$$
<y, \dot{x}(t)>\leq \sup _{k \geq m} \sigma\left(y, \partial_{c} V\left(x_{q-1}\right)+\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s+\frac{1}{k T} B\right)
$$

from which we deduce that

$$
<y, \dot{x}(t)>\leq \limsup _{k \rightarrow+\infty} \sigma\left(y, \partial_{c} V\left(x_{q-1}\right)+\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s+\frac{1}{k T} B\right) .
$$

By Proposition 2.3, the function $x \mapsto \sigma\left(y, \partial_{c} V(x)\right)$ is u.s.c and hence we get

$$
<y, \dot{x}(t)>\leq \sigma\left(y, \partial_{c} V(x(t))+f(t, x(t))\right)
$$

So, the convexity and the closedness of the set $\partial_{c} V(x(t))$ ensure

$$
\dot{x}(t)-f(t, x(t)) \in \partial_{c} V(x(t)) .
$$

Proposition 3.5. The application $x($.$) is a solution of the problem (2.1).$
Proof. As $x($.$) is an absolutely continuous function and \mathrm{V}$ is uniformly regular locally Lipschitz function over $K$ (hence directionally regular over $K$ (see [5])), by Theorem 2 in Valadier [10,11] and by Proposition 3.4, we obtain

$$
\frac{d}{d t} V(x(t))=<\dot{x}(t), \dot{x}(t)-f(t, x(t))>\text { a. e. on }[0, T]
$$

therefore,

$$
\begin{equation*}
V(x(T))-V\left(x_{0}\right)=\int_{0}^{T}\|\dot{x}(s)\|^{2} d s-\int_{0}^{T}<\dot{x}(s), f(s, x(s))>d s \tag{3.6}
\end{equation*}
$$

On the other hand, by construction, for all $q=1, \ldots, s+1$, we have

$$
\dot{x}_{k}(t)-\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s \in \partial_{c} V\left(x_{q-1}\right)+\frac{1}{k T} B
$$

Let $b_{q}$ such that

$$
\dot{x}_{k}(t)-\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s+\frac{1}{k T} b_{q} \in \partial_{c} V\left(x_{q-1}\right) .
$$

Since $V$ is $\beta$-uniformly regular over $K$, we have

$$
\begin{aligned}
V\left(x_{k}\left(\tau_{k}^{q}\right)\right)-V\left(x_{k}\left(\tau_{k}^{q-1}\right)\right) \geq & <x_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right), \dot{x}_{k}(t) \\
& -\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s+\frac{1}{k T} b_{q}> \\
& -\beta\left\|x_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|^{2} \\
= & <\int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} \dot{x}_{k}(s) d s, \dot{x}_{k}(t) \\
& -\frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s+\frac{1}{k T} b_{q}> \\
& -\beta\left\|_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|^{2} \\
= & \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}<\dot{x}_{k}(s), \dot{x}_{k}(s)>d s \\
& -\int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}<\dot{x}_{k}(s), \frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(\tau, x_{q-1}\right) d \tau>d s \\
& \text { EJQTDE, 2007 No. } 7, \mathrm{p} .11
\end{aligned}
$$

$$
\begin{aligned}
& +\frac{1}{k T} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}<\dot{x}_{k}(s), b_{q}>d s \\
& -\beta\left\|x_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|^{2}
\end{aligned}
$$

By adding, we obtain

$$
\begin{align*}
V\left(x_{k}(T)\right)-V\left(x_{0}\right) & \geq \int_{0}^{T}\left\|\dot{x}_{k}(s)\right\|^{2} d s \\
& -\sum_{q=1}^{s+1} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}<\dot{x}_{k}(s), \frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(\tau, x_{q-1}\right) d \tau>d s \\
& +\frac{1}{k T} \sum_{q=1}^{s+1} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}<\dot{x}_{k}(s), b_{q}>d s  \tag{3.7}\\
& -\sum_{q=1}^{s+1} \beta\left\|x_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|^{2} .
\end{align*}
$$

## Claim 3.6.

$\lim _{k \rightarrow+\infty} \sum_{q=1}^{s+1} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}<\dot{x}_{k}(s), \frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(\tau, x_{q-1}\right) d \tau>d s=\int_{0}^{T}<\dot{x}(s), f(s, x(s))>d s$.
Proof. We have

$$
\begin{aligned}
& \left\|\sum_{q=1}^{s+1} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}<\dot{x}_{k}(s), \frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(\tau, x_{q-1}\right) d \tau>d s-\int_{0}^{T}<\dot{x}(s), f(s, x(s))>d s\right\| \\
= & \left\|\sum_{q=1}^{s+1} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}\left(<\dot{x}_{k}(s), \frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(\tau, x_{q-1}\right) d \tau>-<\dot{x}(s), f(s, x(s))>\right) d s\right\| \\
\leq & \left\|\sum_{q=1}^{s+1} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}\left(<\dot{x}_{k}(s), \frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(\tau, x_{q-1}\right) d \tau>-<\dot{x}_{k}(s), f(s, x(s))>\right) d s\right\| \\
& +\left\|\sum_{q=1}^{s+1} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}\left(<\dot{x}_{k}(s), f(s, x(s))>-<\dot{x}(s), f(s, x(s))>\right) d s\right\| \\
\leq & \sum_{q=1}^{s+1} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}\left\|<\dot{x}_{k}(s), \frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(\tau, x_{q-1}\right) d \tau>-<\dot{x}_{k}(s), f(s, x(s))>\right\| d s \\
& +\left\|\int_{0}^{T}\left(<\dot{x}_{k}(s), f(s, x(s))>-<\dot{x}(s), f(s, x(s))>\right) d s\right\|
\end{aligned}
$$

Since

$$
\left\|\dot{x}_{k}(t)\right\| \leq \lambda+M+1, \lim _{k \rightarrow+\infty} \frac{1}{h_{q-1}^{k}} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}} f\left(s, x_{q-1}\right) d s=f(t, x(t))
$$

and $\dot{x}_{k}($.$) converges weakly to \dot{x}($.$) , the last term converges to 0$. This completes the proof of the Claim.

## Claim 3.7.

$$
\lim _{k \rightarrow+\infty} \sum_{q=1}^{s+1} \beta\left\|x_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|^{2}=0
$$

Proof. By construction we have

$$
\begin{aligned}
\left\|x_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right)\right\| & =\left\|\left(\tau_{k}^{q}-\tau_{k}^{q-1}\right) u_{q-1}\right\| \\
& \leq\left(\tau_{k}^{q}-\tau_{k}^{q-1}\right)\left\|u_{q-1}\right\| \\
& \leq\left(\tau_{k}^{q}-\tau_{k}^{q-1}\right)(\lambda+1+M) .
\end{aligned}
$$

Hence

$$
\begin{aligned}
\left\|x_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|^{2} & \leq\left(\tau_{k}^{q}-\tau_{k}^{q-1}\right)^{2}(\lambda+1+M)^{2} \\
& \leq\left(\tau_{k}^{q}-\tau_{k}^{q-1}\right) h_{q-1}^{k}(\lambda+1+M)^{2} \\
& \leq\left(\tau_{k}^{q}-\tau_{k}^{q-1}\right) \frac{1}{k}(\lambda+1+M)^{2} .
\end{aligned}
$$

Then

$$
\sum_{q=1}^{s+1} \beta\left\|x_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|^{2} \leq \frac{\beta T(\lambda+1+M)^{2}}{k}
$$

hence

$$
\lim _{k \rightarrow+\infty} \sum_{q=1}^{s+1} \beta\left\|x_{k}\left(\tau_{k}^{q}\right)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|^{2}=0
$$

Note that

$$
\lim _{k \rightarrow+\infty} \frac{1}{k T} \sum_{q=1}^{s+1} \int_{\tau_{k}^{q-1}}^{\tau_{k}^{q}}<\dot{x}_{k}(s), b_{q}>d s=0
$$

By passing to the limit for $k \rightarrow \infty$ in (3.7) and using the continuity of the function $V$ on the ball $B\left(x_{0}, r\right)$, we obtain

$$
V(x(T))-V\left(x_{0}\right) \geq \limsup _{k \rightarrow+\infty} \int_{0}^{T}\left\|\dot{x}_{k}(s)\right\|^{2} d s-\int_{0}^{T}<\dot{x}(s), f(s, x(s))>d s
$$

Moreover, by (3.6), we have

$$
\|\dot{x}\|_{2}^{2} \geq \limsup _{k \rightarrow+\infty}\left\|\dot{x}_{k}\right\|_{2}^{2}
$$

and by the weak l.s.c of the norm ensures

$$
\|\dot{x}\|_{2}^{2} \leq \liminf _{k \rightarrow+\infty}\left\|\dot{x}_{k}\right\|_{2}^{2}
$$

Hence we get

$$
\|\dot{x}\|_{2}^{2}=\lim _{k \rightarrow+\infty}\left\|\dot{x}_{k}\right\|_{2}^{2} .
$$

Finally, there exists a subsequence of $\left(\dot{x}_{k}(.)\right)_{k}\left(\right.$ still denoted $\left.\left(\dot{x}_{k}(.)\right)_{k}\right)$ converges pointwisely to $\dot{x}($.$) . In view of Proposition (3.2), we conclude that$

$$
d_{g r F}((x(t), \dot{x}(t)-f(t, x(t))))=0
$$

and as $F$ has a closed graph, we obtain

$$
\dot{x}(t) \in f(t, x(t))+F(x(t)) \text { a.e on }[0, T] .
$$

EJQTDE, 2007 No. 7, p. 13

Now, let $t \in[0, T]$, there exists $q \in\{1, \ldots, s+1\}$ such that $t \in\left[\tau_{k}^{q-1}, \tau_{k}^{q}\right]$ and $\lim _{k \rightarrow+\infty} \tau_{k}^{q-1}=t$. Since

$$
\lim _{k \rightarrow+\infty}\left\|x(t)-x_{k}\left(\tau_{k}^{q-1}\right)\right\|=0
$$

$x_{k}\left(\tau_{k}^{q-1}\right) \in K_{0}$ and $K_{0}$ is closed we obtain $x(t) \in K_{0} \subset K$. The proof is complete.

## References

[1] Ancona, F., Colombo, G., Existence of solutions for a class of nonconvex differential inclusions, Rend. Sem. Mat. Univ. Padova 83 (1990)
[2] Bounkhel, M., Thibault, L., On various notions of regularity of sets, Nonlinear Anal. 48(2) (2002), 223-246.
[3] Bounkhel, M., On arc-wise essentially smooth mappings between Banach spaces, J. Optimization 51 (1) (2002), 11-29.
[4] Bounkhel, M., Existence results of nonconvex differential inclusions, J. Portugaliae Mathematica 59 (3) (2002), 283-310.
[5] Bounkhel, M., Thibault, L., Subdifferential regularity of directionally Lipschitz functions, Canad. Math. Bull. 43 (1) (2000), 25-36.
[6] Bressan, A., Cellina, A., Colombo, G., Upper semicontinuous differential inclusions without convexity, Proc. Am. Math. Soc. 106 (1989), 771-775.
[7] Brezis, H., Oprateurs maximaux monotones et semi-groupes de contractions dans les espaces de Hilbert, North-Holland, Amsterdam, 1973.
[8] Morchadi, R., Sajid, S., A viability result for a first-order differential inclusions, Portugaliae Mathematica 63, fasc. 1, (2006).
[9] Truong, X. D. H., Existence of viable solutions of nonconvex differential inclusion, Atti. Semi. Mat. Modena XLVII (1999), 457-471.
[10] Valadier, M., Entrainement unilateral, lignes de descente, fonctions lipschitziennes non pathologiques, C.R.A.S. Paris 308(I) (1989), 241-244
[11] Valadier, M., Lignes de descente de fonctions lipschitziennes non pathologiques, Sém. d’Anal. Convexe. Montpellier, exposé 9, (1988)
(Received November 27, 2006)

