# ON SOME BOUNDARY VALUE PROBLEMS FOR SYSTEMS OF LINEAR FUNCTIONAL DIFFERENTIAL EQUATIONS 

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## 1. Introduction

1.1. Statement of the Problem. On the segment $I=[a, b]$ consider the system of linear functional differential equations

$$
\begin{equation*}
x_{i}^{\prime}(t)=\sum_{k=1}^{n} \ell_{i k}\left(x_{k}\right)(t)+q_{i}(t) \quad(i=1, \ldots, n) \tag{1}
\end{equation*}
$$

and its particular case

$$
x_{i}^{\prime}(t)=\sum_{k=1}^{n} p_{i k}(t) x_{k}\left(\tau_{i k}(t)\right)+q_{i}(t) \quad(i=1, \ldots, n)
$$

with the boundary conditions

$$
\begin{equation*}
\int_{a}^{b} x_{i}(t) d \varphi_{i}(t)=c_{i} \quad(i=1, \ldots, n) \tag{2}
\end{equation*}
$$

Here $\ell_{i k}: C(I ; \mathbb{R}) \rightarrow L(I ; \mathbb{R})$ are linear bounded operators, $p_{i k}$ and $q_{i} \in L(I ; \mathbb{R})$, $c_{i} \in \mathbb{R}(i, k=1, \ldots, n), \varphi_{i}: I \rightarrow \mathbb{R}(i=1, \ldots, n)$ are the functions with bounded variations, and $\tau_{i k}: I \rightarrow I(i, k=1, \ldots, n)$ are measurable functions.

The simple but important particular case of the conditions (2) are the two-point boundary conditions

$$
\begin{equation*}
x_{i}(b)=\lambda_{i} x_{i}(a)+c_{i} \quad(i=1, \ldots, n), \tag{3}
\end{equation*}
$$

[^0]the periodic boundary conditions
\[

$$
\begin{equation*}
x_{i}(b)=x_{i}(a)+c_{i} \quad(i=1, \ldots, n), \tag{4}
\end{equation*}
$$

\]

and the initial conditions

$$
\begin{equation*}
x_{i}\left(t_{0}\right)=c_{i} \quad(i=1, \ldots, n), \tag{5}
\end{equation*}
$$

where $t_{0} \in I$ and $\lambda_{i} \in \mathbb{R}(i=1, \ldots, n)$.
By a solution of the system (1) (of the system (1')) we understand an absolutely continuous vector function $\left(x_{i}\right)_{i=1}^{n}: I \rightarrow \mathbb{R}$ which satisfies the system (1) (the system $\left.\left(1^{\prime}\right)\right)$ almost everywhere on $I$. A solution of the system (1) (of the system ( $\left.1^{\prime}\right)$ ) which satisfies the condition $(j)$, where $j \in\{2,3,4,5\}$, is said to be a solution of the problem (1), (j).

As for the differential system

$$
x_{i}^{\prime}(t)=\sum_{k=1}^{n} p_{i k}(t) x_{k}(t)+q_{i}(t) \quad(i=1, \ldots, n),
$$

the boundary value problems have been studied in detail (see [4,5,8-10] and references therein). There are also a lot of interesting results concerning the problems (1), ( $k$ ) and $\left(1^{\prime}\right),(k)(k=2,3,4,5)$ (see $\left.[2,3,6,7,11-13]\right)$. In this paper, the optimal conditions for the unique solvability of the problems (1), (2) and ( $1^{\prime}$ ), (2) are established which are different from the previous results.
1.2. Basic Notation. Throughout this paper the following notation and terms are used:
$I=[a, b], \mathbb{R}=]-\infty,+\infty\left[, \mathbb{R}_{+}=[0,+\infty[;\right.$
$\delta_{i k}$ is the Kronecker's symbol, i.e.,

$$
\delta_{i k}= \begin{cases}1 & \text { for } i=k \\ 0 & \text { for } i \neq k\end{cases}
$$

$\mathbb{R}^{n}$ is the space of $n$-dimensional column vectors $x=\left(x_{i}\right)_{i=1}^{n}$ with the components $x_{i} \in \mathbb{R}(i=1, \ldots, n)$ and the norm

$$
\|x\|=\sum_{i=1}^{n}\left|x_{i}\right|
$$

$\mathbb{R}^{n \times n}$ is the space of $n \times n$-matrices $X=\left(x_{i k}\right)_{i, k=1}^{n}$ with the components $x_{i k} \in \mathbb{R}$ $(i, k=1, \ldots, n)$ and the norm

$$
\|X\|=\sum_{i, k=1}^{n}\left|x_{i k}\right| ;
$$

$\mathbb{R}_{+}^{n}=\left\{\left(x_{i}\right)_{i=1}^{n} \in \mathbb{R}^{n}: x_{i} \geq 0, i=1, \ldots, n\right\} ;$
$\mathbb{R}_{+}^{n \times n}=\left\{\left(x_{i k}\right)_{i, k=1}^{n} \in \mathbb{R}^{n \times n}: x_{i k} \geq 0, i, k=1, \ldots, n\right\} ;$
the inequalities between vectors $x$ and $y \in \mathbb{R}^{n}$, and between matrices $X$ and $Y \in \mathbb{R}^{n \times n}$ are considered componentwise, i.e.,

$$
x \leq y \Leftrightarrow(y-x) \in \mathbb{R}_{+}^{n}, \quad X \leq Y \Leftrightarrow(Y-X) \in \mathbb{R}_{+}^{n \times n}
$$

$r(X)$ is the spectral radius of the matrix $X \in \mathbb{R}^{n \times n}$;
$X^{-1}$ is the inverse matrix to $X \in \mathbb{R}^{n \times n}$;
$E$ is the unit matrix;
$C\left(I ; \mathbb{R}^{n}\right)$ is the space of continuous ${ }^{1}$ vector functions $x: I \rightarrow \mathbb{R}^{n}$ with the norm

$$
\|x\|_{C}=\sup \{\|x(t)\|: t \in I\}
$$

$C\left(I ; \mathbb{R}_{+}^{n}\right)=\left\{x \in C\left(I ; \mathbb{R}^{n}\right): x(t) \in \mathbb{R}_{+}^{n}\right.$ for $\left.t \in I\right\} ;$
$L\left(I ; \mathbb{R}^{n}\right)$ is the space of summable vector functions $x: I \rightarrow \mathbb{R}^{n}$ with the norm

$$
\|x\|_{L}=\int_{I}\|x(t)\| d t
$$

$\underset{\widetilde{C}}{L}\left(I ; \mathbb{R}_{+}^{n}\right)=\left\{x \in L\left(I ; \mathbb{R}^{n}\right): x(t) \in \mathbb{R}_{+}^{n}\right.$ for almost all $\left.t \in I\right\} ;$
$\widetilde{C}\left(I ; \mathbb{R}^{n}\right)$ is the space of absolutely continuous vector functions $x: I \rightarrow \mathbb{R}^{n}$ with the norm

$$
\|x\|_{\Theta}=\|x\|_{C}+\left\|x^{\prime}\right\|_{L}
$$

$\mathcal{P}_{\mathcal{I}}$ is the set of linear operators $\ell: C(I ; \mathbb{R}) \rightarrow L(I ; \mathbb{R})$ mappings $C\left(I ; \mathbb{R}_{+}\right)$into $L\left(I ; \mathbb{R}_{+}\right)$;
$\mathcal{L}_{\mathcal{I}}$ is the set of linear continuous operators $\ell: C(I ; \mathbb{R}) \rightarrow L(I ; \mathbb{R})$, for each of them there exists an operator $\bar{\ell} \in \mathcal{P}_{\mathcal{I}}$ such that for any $u \in C(I ; \mathbb{R})$ the inequalities

$$
|\ell(u)(t)| \leq \bar{\ell}(|u|)(t)
$$

holds almost everywhere on $I$;
for any $u \in L(I ; \mathbb{R})$

$$
\eta(u)(t, s)=\int_{t}^{s} u(\xi) d \xi
$$

[^1]1.3. Criterion on the Unique Solvability of the Problem (1), (2). The results in general theory of boundary value problems (see [12], Theorems 1.1 and 1.4) yield the following

Theorem 1. If $\ell_{i k} \in \mathcal{L}_{I}(i, k=1, \ldots, n)$, then the boundary value problem (1), (2) with arbitrary $c_{i} \in \mathbb{R}$ and $q_{i} \in L(I ; \mathbb{R})(i=1, \ldots, n)$ is uniquely solvable if and only if the corresponding homogeneous problem

$$
\begin{align*}
x_{i}^{\prime}(t)=\sum_{k=1}^{n} \ell_{i k}\left(x_{k}\right)(t) & (i=1, \ldots, n),  \tag{0}\\
\int_{a}^{b} x_{i}(s) d \varphi_{i}(s)=0 & (i=1, \ldots, n) \tag{0}
\end{align*}
$$

has only the trivial solution. If the latter condition is fulfilled, then the solution of the problem (1), (2) admits the representation

$$
\begin{equation*}
x_{i}(t)=\sum_{k=1}^{n} y_{i k}(t) c_{k}+g_{i}\left(q_{1}, \ldots, q_{n}\right)(t) \quad(i=1, \ldots, n), \tag{6}
\end{equation*}
$$

where $y_{i k} \in \widetilde{C}(I ; \mathbb{R})(i, k=1, \ldots, n)$, and $g_{i}: L\left(I ; \mathbb{R}^{n}\right) \rightarrow \widetilde{C}(I ; \mathbb{R})(i=1, \ldots, n)$ are linear continuous operators such that the vector function $\left(\sum_{k=1}^{n} y_{i k} c_{k}\right)_{i=1}^{n}$ is the solution of the problem $\left(1_{0}\right),(2)$, and the vector function $\left(g_{i}\left(q_{1}, \ldots, q_{n}\right)\right)_{i=1}^{n}$ is the solution of the problem (1), ( $2_{0}$ ).
Remark 1. The operator $\left(g_{i}\right)_{i=1}^{n}: L\left(I ; \mathbb{R}^{n}\right) \rightarrow \widetilde{C}\left(I ; \mathbb{R}^{n}\right)$ is called the Green's operator of the problem $\left(1_{0}\right),\left(2_{0}\right)$. According to Danford-Pettis Theorem (see [1], Ch. XI, §1, Theorem 6), there exists the unique matrix function $G=\left(g_{i k}\right)_{i, k=1}^{n}: I \times I \rightarrow \mathbb{R}^{n \times n}$ with the essentially bounded components $g_{i k}: I \times I \rightarrow \mathbb{R}(i, k=1, \ldots, n)$ such that

$$
g_{i}\left(q_{1}, \ldots, q_{n}\right)(t) \equiv \sum_{k=1}^{n} \int_{a}^{b} g_{i k}(t, s) q_{k}(s) d s \quad(i=1, \ldots, n)
$$

Consequently, the formula (6) can be rewritten as follows:

$$
x_{i}(t)=\sum_{k=1}^{n} y_{i k}(t) c_{k}+\sum_{k=1}^{n} \int_{a}^{b} g_{i k}(t, s) q_{k}(s) d s \quad(i=1, \ldots, n) .
$$

This formula is called the Green's formula for the problem (1), (2), and the matrix $G$ is called the Green's matrix of the problem $\left(1_{0}\right),\left(2_{0}\right)$.

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The aim of the following is to find effective criteria for the unique solvability of the above formulated problems. With a view to achieve this goal, we will need one lemma which is proved in Section 2.

## 2. Lemma on Boundary Value Problem for the System of Functional Differential Equations

Consider the system of differential inequalities

$$
\begin{equation*}
\left|y_{i}^{\prime}(t)-\ell_{i}\left(y_{i}\right)(t)\right| \leq \sum_{k=1}^{n} h_{i k}(t)\left\|y_{k}\right\|_{C} \quad(i=1, \ldots, n) \tag{7}
\end{equation*}
$$

with the boundary conditions

$$
\begin{equation*}
\int_{a}^{b} y_{i}(s) d \varphi_{i}(s)=0 \quad(i=1, \ldots, n) \tag{8}
\end{equation*}
$$

where

$$
\ell_{i} \in \mathcal{L}_{I}, \quad h_{i k} \in L\left(I ; \mathbb{R}_{+}\right) \quad(i, k=1, \ldots, n)
$$

$c_{i} \in \mathbb{R}(i=1, \ldots, n)$, and $\varphi_{i}: I \rightarrow \mathbb{R}(i=1, \ldots, n)$ are functions with bounded variations.

Along with (7), (8) for every $i \in\{1, \ldots, n\}$ consider the homogeneous problem

$$
\begin{equation*}
y^{\prime}(t)=\ell_{i}(y)(t), \quad \int_{a}^{b} y(s) d \varphi_{i}(s)=0 \tag{i}
\end{equation*}
$$

Lemma 1. Let for every $i \in\{1, \ldots, n\}$ the homogeneous problem $\left(9_{i}\right)$ have only the trivial solution and there exist a matrix $A=\left(a_{i k}\right)_{i, k=1}^{n} \in \mathbb{R}_{+}^{n \times n}$ such that

$$
\begin{equation*}
r(A)<1 \tag{10}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{a}^{b}\left|g_{i}(t, s)\right| h_{i k}(s) d s \leq a_{i k} \quad \text { for } t \in I \quad(i, k=1, \ldots, n), \tag{11}
\end{equation*}
$$

where $g_{i}$ is the Green's function of the problem (9i). Then the problem (7), (8) has only the trivial solution.

Proof. Let $\left(y_{i}\right)_{i=1}^{n}$ be a solution of (7), (8). Then for every $i \in\{1, \ldots, n\}$, the function $y_{i}$ is the solution of the problem

$$
\begin{equation*}
y^{\prime}(t)-\ell_{i}(y)(t)=q_{i}(t), \quad \int_{a}^{b} y(s) d \varphi_{i}(s)=0 \tag{12}
\end{equation*}
$$

where

$$
\begin{equation*}
q_{i}(t) \stackrel{\text { def }}{=} y_{i}^{\prime}(t)-\ell_{i}\left(y_{i}\right)(t) . \tag{13}
\end{equation*}
$$

By the Green's formula we have

$$
\begin{equation*}
y_{i}(t)=\int_{a}^{b} g_{i}(t, s) q_{i}(s) d s \quad \text { for } t \in I \quad(i=1, \ldots, n), \tag{14}
\end{equation*}
$$

Due to (7) and (13),

$$
\int_{a}^{b}\left|g_{i}(t, s)\left\|q_{i}(s)\left|d s \leq \sum_{k=1}^{n} \int_{a}^{b}\right| g_{i}(t, s) \mid h_{i k}(s)\right\| y_{k} \|_{C} d s \quad \text { for } t \in I \quad(i=1, \ldots, n)\right.
$$

In view of (11) and the last inequalities from (14) we obtain

$$
\begin{equation*}
\left|y_{i}(t)\right| \leq \sum_{k=1}^{n} a_{i k}\left\|y_{k}\right\|_{C} \quad \text { for } t \in I \quad(i=1, \ldots, n) \tag{15}
\end{equation*}
$$

Consequently, (15) yields

$$
\begin{equation*}
(E-A)\left(\left\|y_{i}\right\|_{C}\right)_{i=1}^{n} \leq 0 . \tag{16}
\end{equation*}
$$

Since $A$ is a nonnegative matrix satisfying (10), there exists the nonnegative inverse matrix $(E-A)^{-1}$. Then by (16) we obtain $y_{i}(t) \equiv 0(i=1, \ldots, n)$.

## 3. Existence and Uniqueness Theorems

Throughout the following we will assume that $\ell_{i k} \in \mathcal{L}_{I}(i, k=1, \ldots, n)$ and for any $u \in C(I ; \mathbb{R})$ the inequalities

$$
\left|\ell_{i k}(u)(t)\right| \leq \bar{\ell}_{i k}(|u|)(t) \quad(i, k=1, \ldots, n)
$$

hold almost everywhere on $I$, where $\bar{\ell}_{i k} \in \mathcal{P}_{\mathcal{I}}(i, k=1, \ldots, n)$.
Theorem 2. Let there exist operators $\ell_{i}, \widetilde{\ell}_{i k} \in \mathcal{L}_{I}(i, k=1, \ldots, n)$, functions $h_{i k} \in$ $L\left(I ; \mathbb{R}_{+}\right)(i, k=1, \ldots, n)$, and a matrix $A=\left(a_{i k}\right)_{i, k=1}^{n} \in \mathbb{R}_{+}^{n \times n}$ satisfying (10) such that:
(i) any solution of the system ( $1_{0}$ ) is also a solution of the system

$$
\begin{equation*}
x_{i}^{\prime}(t)=\ell_{i}\left(x_{i}\right)(t)+\sum_{k=1}^{n} \widetilde{\ell}_{i k}\left(x_{k}\right)(t) \quad(i=1, \ldots, n) ; \tag{17}
\end{equation*}
$$

(ii) for any $y \in \widetilde{C}(I ; \mathbb{R})$, the inequalities

$$
\begin{equation*}
\left|\widetilde{\ell}_{i k}(y)(t)\right| \leq h_{i k}(t)\|y\|_{C} \quad(i, k=1, \ldots, n) \tag{18}
\end{equation*}
$$

holds almost everywhere on I;
(iii) for every $i \in\{1, \ldots, n\}$ the problem $\left(9_{i}\right)$ has only the trivial solution and the inequalities (11) are fulfilled, where $g_{i}$ is the Green's function of the problem $\left(9_{i}\right)$.
Then the problem (1), (2) has a unique solution.
Proof. Let $\left(y_{i}\right)_{i=1}^{n}$ be a solution of the problem $\left(1_{0}\right),\left(2_{0}\right)$. Then by (17) and (18) it is also a solution of the problem (7), (8). Now it is obvious that all the assumptions of Lemma 1 are fulfilled. Therefore $y_{i}(t) \equiv 0(i=1, \ldots, n)$. Thus the homogeneous problem $\left(1_{0}\right),\left(2_{0}\right)$ has only the trivial solution and consequently, by Theorem 1, the problem (1), (2) has a unique solution.

Corollary 1. Let there exist operators $\ell_{i} \in \mathcal{L}_{I}(i=1, \ldots, n)$, functions $h_{i k} \in$ $L\left(I ; \mathbb{R}_{+}\right)(i, k=1, \ldots, n)$, and a matrix $A=\left(a_{i k}\right)_{i, k=1}^{n} \in \mathbb{R}_{+}^{n \times n}$ satisfying (10) such that:
(i) for any $y \in \widetilde{C}(I ; \mathbb{R})$, the inequalities

$$
\begin{gathered}
\left|\ell_{i i}(y)(t)-\ell_{i}(y)(t)\right| \leq h_{i i}(t)\|y\|_{C} \quad(i=1, \ldots, n), \\
\left|\ell_{i k}(y)(t)\right| \leq h_{i k}(t)\|y\|_{C} \quad(i \neq k ; i, k=1, \ldots, n)
\end{gathered}
$$

holds almost everywhere on $I$;
(ii) for every $i \in\{1, \ldots, n\}$ the problem $\left(9_{i}\right)$ has only the trivial solution and the inequalities (11) are fulfilled, where $g_{i}$ is the Green's function of the problem $\left(9_{i}\right)$. Then the problem (1), (2) has a unique solution.

Proof. Put

$$
\begin{gathered}
\widetilde{\ell}_{i i}(y)(t) \equiv \ell_{i i}(y)(t)-\ell_{i}(y)(t) \quad(i=1, \ldots, n), \\
\widetilde{\ell}_{i k}(y)(t) \equiv \ell_{i k}(y)(t) \quad(i \neq k ; i, k=1, \ldots, n) .
\end{gathered}
$$

Then the assumptions of Theorem 2 are fulfilled. Consequently, the problem (1), (2) has a unique solution.

Corollary 2. Let

$$
\begin{equation*}
\int_{a}^{b} \exp \left(\int_{a}^{s} \ell_{i i}(1)(\xi) d \xi\right) d \varphi_{i}(s) \neq 0 \quad(i=1, \ldots, n) \tag{19}
\end{equation*}
$$

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and there exist a matrix $A=\left(a_{i k}\right)_{i, k=1}^{n} \in \mathbb{R}_{+}^{n \times n}$ satisfying (10) such that (11) is fulfilled, where $g_{i}$ is the Green's function of the problem

$$
\begin{equation*}
y^{\prime}(t)=\ell_{i i}(1)(t) y(t), \quad \int_{a}^{b} y(s) d \varphi_{i}(s)=0 \tag{i}
\end{equation*}
$$

and

$$
\begin{equation*}
h_{i k}(t)=\bar{\ell}_{i i}\left(\left|\eta\left(\bar{\ell}_{i k}(1)\right)(t, \cdot)\right|\right)(t)+\left(1-\delta_{i k}\right) \bar{\ell}_{i k}(1)(t) \quad(i, k=1, \ldots, n) . \tag{21}
\end{equation*}
$$

Then the problem (1), (2) has a unique solution.
Proof. The condition (19) is necessary and sufficient for the problem $\left(20_{i}\right)$ to have only the trivial solution for every $i \in\{1, \ldots, n\}$.

On the other hand, every solution $\left(x_{i}\right)_{i=1}^{n}$ of the system $\left(1_{0}\right)$ satisfies

$$
\begin{gather*}
x_{i}^{\prime}(t)=\ell_{i i}(1)(t) x_{i}(t)+\ell_{i i}\left(x_{i}(\cdot)-x_{i}(t)\right)(t)+\sum_{k=1}^{n}\left(1-\delta_{i k}\right) \ell_{i k}\left(x_{k}\right)(t)=  \tag{22}\\
=\ell_{i i}(1)(t) x_{i}(t)+\sum_{k=1}^{n}\left[\ell_{i i}\left(\left|\eta\left(\ell_{i k}\left(x_{k}\right)\right)(t, \cdot)\right|\right)(t)+\left(1-\delta_{i k}\right) \ell_{i k}\left(x_{k}\right)(t)\right] \quad(i=1, \ldots, n) .
\end{gather*}
$$

Put

$$
\begin{gathered}
\ell_{i}(y)(t) \equiv \ell_{i i}(1)(t) y(t) \quad(i=1, \ldots, n) \\
\tilde{\ell}_{i k}(y)(t) \equiv \ell_{i i}\left(\left|\eta\left(\ell_{i k}(y)\right)(t, \cdot)\right|\right)(t)+\left(1-\delta_{i k}\right) \ell_{i k}(y)(t) \quad(i, k=1, \ldots, n) .
\end{gathered}
$$

Then any solution of the system (10) is also a solution of the system (17). Now it is obvious that all the assumptions of Theorem 2 are fulfilled. Consequently, the problem (1), (2) has a unique solution.
If

$$
\ell_{i k}(y)(t) \equiv p_{i k} y\left(\tau_{i k}(t)\right) \quad(i, k=1, \ldots, n)
$$

then the system (1) has the form ( $1^{\prime}$ ). In that case

$$
\begin{gathered}
\bar{\ell}_{i k}(y)(t) \equiv\left|p_{i k}\right| y\left(\tau_{i k}(t)\right) \quad(i, k=1, \ldots, n), \\
\bar{\ell}_{i i}\left(\left|\eta\left(\bar{\ell}_{i k}(1)\right)(t, \cdot)\right|\right)(t) \equiv\left|p_{i i}(t) \int_{t}^{\tau_{i i}(t)}\right| p_{i k}(s)|d s| .
\end{gathered}
$$

Therefore from Corollary 2 it follows

Corollary $\mathbf{2}^{\prime}$. Let

$$
\int_{a}^{b} \exp \left(\int_{a}^{s} p_{i i}(\xi) d \xi\right) d \varphi_{i}(s) \neq 0 \quad(i=1, \ldots, n)
$$

and there exist a matrix $A=\left(a_{i k}\right)_{i, k=1}^{n} \in \mathbb{R}_{+}^{n \times n}$ satisfying (10) such that (11) is fulfilled, where $g_{i}$ is the Green's function of the problem

$$
y^{\prime}(t)=p_{i i}(t) y(t), \quad \int_{a}^{b} y(s) d \varphi_{i}(s)=0
$$

and

$$
h_{i k}(t)=\left|p_{i i}(t) \int_{t}^{\tau_{i i}(t)}\right| p_{i k}(s)|d s|+\left(1-\delta_{i k}\right)\left|p_{i k}(t)\right|
$$

$$
(i, k=1, \ldots, n) .
$$

Then the problem (1'), (2) has a unique solution.
Corollary 3. Let $\lambda_{i} \neq 1, \mu_{i}=\max \left\{1,\left|\lambda_{i}\right|\right\}(i=1, \ldots, n)$ and the matrix

$$
A=\left(\frac{\mu_{i}}{\left|1-\lambda_{i}\right|} \int_{a}^{b} \bar{\ell}_{i k}(1)(s) d s\right)_{i, k=1}^{n}
$$

satisfies (10). Then the problem (1), (3) has a unique solution.
Proof. Since $\lambda_{i} \neq 1(i=1, \ldots, n)$, for every $i \in\{1, \ldots, n\}$ the problem

$$
\begin{equation*}
y^{\prime}(t)=0, \quad y(b)=\lambda_{i} y(a) \tag{i}
\end{equation*}
$$

has only the trivial solution. Moreover, the Green's function of $\left(23_{i}\right)$ is of the form

$$
g_{i}(t, s)= \begin{cases}\frac{\lambda_{i}}{\lambda_{i}-1} & \text { for } a \leq s \leq t \leq b \\ \frac{1}{\lambda_{i}-1} & \text { for } a \leq t<s \leq b\end{cases}
$$

Put

$$
\ell_{i}(y)(t) \equiv 0, \quad \widetilde{\ell}_{i k}(y)(t) \equiv \ell_{i k}(y)(t), \quad h_{i k}(t) \equiv \bar{\ell}_{i k}(1)(t) \quad(i, k=1, \ldots, n)
$$

Then all the assumptions of Theorem 2 are fulfilled. Consequently, the problem (1), (3) has a unique solution

Corollary $3^{\prime}$. Let $\lambda_{i} \neq 1, \mu_{i}=\max \left\{1,\left|\lambda_{i}\right|\right\}(i=1, \ldots, n)$ and the matrix

$$
A=\left(\frac{\mu_{i}}{\left|1-\lambda_{i}\right|} \int_{a}^{b}\left|p_{i k}(s)\right| d s\right)_{i, k=1}^{n}
$$

satisfies (10). Then the problem (1'), (3) has a unique solution.
Corollary 4. Let

$$
\begin{equation*}
\int_{a}^{b} \ell_{i i}(1)(s) d s \neq 0 \quad(i=1, \ldots, n) \tag{24}
\end{equation*}
$$

and there exist a matrix $A=\left(a_{i k}\right)_{i, k=1}^{n} \in \mathbb{R}_{+}^{n \times n}$ satisfying (10) such that (11) is fulfilled, where $g_{i}$ is the Green's function of the problem

$$
\begin{equation*}
y^{\prime}(t)=\ell_{i i}(1)(t) y(t), \quad y(b)=y(a) \tag{i}
\end{equation*}
$$

and $h_{i k}$ is defined by (21). Then the problem (1), (4) has a unique solution.
Proof. The condition (24) is necessary and sufficient for the problem $\left(25_{i}\right)$ to have only the trivial solution for every $i \in\{1, \ldots, n\}$ and its Green's function is of the form

$$
g_{i}(t, s)=\left\{\begin{array}{r}
\left(1-\exp \left(\int_{a}^{b} \ell_{i i}(1)(\xi) d \xi\right)\right)^{-1} \exp \left(\int_{s}^{t} \ell_{i i}(1)(\xi) d \xi\right)  \tag{i}\\
\quad \text { for } a \leq s \leq t \leq b \\
\left(\exp \left(-\int_{a}^{b} \ell_{i i}(1)(\xi) d \xi\right)-1\right)^{-1} \exp \left(\int_{s}^{t} \ell_{i i}(1)(\xi) d \xi\right) \\
\text { for } a \leq t<s \leq b
\end{array}\right.
$$

Now it is obvious that all the assumptions of Corollary 2 are fulfilled. Consequently, the problem (1), (4) has a unique solution.

Corollary $4^{\prime}$. Let

$$
\int_{a}^{b} p_{i i}(s) d s \neq 0 \quad(i=1, \ldots, n)
$$

and there exist a matrix $A=\left(a_{i k}\right)_{i, k=1}^{n} \in \mathbb{R}_{+}^{n \times n}$ satisfying (10) such that (11) is fulfilled, where $g_{i}$ is the Green's function of the problem

$$
y^{\prime}(t)=p_{i i}(t) y(t), \quad y(b)=y(a)
$$

and $h_{i k}$ is defined by (21'). Then the problem (1'), (4) has a unique solution.

Corollary 5. Let (24) be fulfilled and there exist $\left.\sigma_{i} \in\{-1,1\}, \alpha_{i} \in\right] 0,+\infty\left[, \alpha_{i k} \in\right.$ $[0,+\infty[(i, k=1, \ldots, n)$ such that the real part of every eigenvalue of the matrix $A=\left(-\delta_{i k} \alpha_{i}+\alpha_{i k}\right)_{i, k=1}^{n}$ is negative and the inequalities

$$
\begin{align*}
& \sigma_{i} \ell_{i i}(1)(t) \leq-\alpha_{i} \quad(i=1, \ldots, n)  \tag{27}\\
& \bar{\ell}_{i i}\left(\left|\eta\left(\bar{\ell}_{i k}(1)\right)(t, \cdot)\right|\right)(t)+\left(1-\delta_{i k}\right) \bar{\ell}_{i k}(1)(t) \leq \alpha_{i k}  \tag{28}\\
& \quad(i, k=1, \ldots, n)
\end{align*}
$$

hold almost everywhere on $I$. Then the problem (1), (4) has a unique solution.
Proof. At first note that according to Theorems 1.13 and 1.18 in [10] the negativeness of real parts of the eigenvalues of the matrix $A$ yields the inequality

$$
\begin{equation*}
r(\bar{A})<1 \tag{29}
\end{equation*}
$$

where

$$
\bar{A}=\left(\frac{\alpha_{i k}}{\alpha_{i}}\right)_{i, k=1}^{n} .
$$

On the other hand, from (27) it follows that for every $i \in\{1, \ldots, n\}$ the problem $\left(25_{i}\right)$ has only the trivial solution and its Green's function $g_{i}$ is given by $\left(26_{i}\right)$. Put

$$
\Delta_{i}(s, t)=\exp \left(-\sigma_{i} \alpha_{i}(t-s)\right) \quad(i=1, \ldots, n)
$$

Then for every $i \in\{1, \ldots, n\}$ from $\left(26_{i}\right)$ and (27) we obtain

$$
\left|g_{i}(t, s)\right| \leq \begin{cases}{\left[\sigma_{i}\left(1-\Delta_{i}(a, b)\right)\right]^{-1} \Delta_{i}(s, t)} & \text { for } a \leq s \leq t \leq b  \tag{30}\\ {\left[\sigma_{i}\left(1-\Delta_{i}(a, b)\right)\right]^{-1} \Delta_{i}(a, b) \Delta_{i}(s, t)} & \text { for } a \leq t<s \leq b\end{cases}
$$

Define the functions $h_{i k}$ by (21). Then from (28) and (30) we get

$$
\begin{align*}
& \int_{a}^{b}\left|g_{i}(t, s)\right| h_{i k}(s) d s \leq  \tag{31}\\
\leq & \alpha_{i k}\left[\sigma_{i}\left(1-\Delta_{i}(a, b)\right)\right]^{-1}\left(\int_{a}^{t} \Delta_{i}(s, t) d s+\Delta_{i}(a, b) \int_{t}^{b} \Delta_{i}(s, t) d s\right)= \\
= & \frac{\alpha_{i k}}{\alpha_{i}}\left[1-\Delta_{i}(a, b)\right]^{-1}\left(1-\Delta_{i}(a, t)+\Delta_{i}(a, b) \Delta_{i}(b, t)-\Delta_{i}(a, b)\right)= \\
= & \frac{\alpha_{i k}}{\alpha_{i}} \quad(i, k=1, \ldots, n) .
\end{align*}
$$

Taking into account (29) we conclude that all the assumptions of Corollary 2 are fulfilled. Consequently, the problem (1), (4) has a unique solution.

Corollary $5^{\prime}$. Let (24') be fulfilled and there exist $\left.\sigma_{i} \in\{-1,1\}, \alpha_{i} \in\right] 0,+\infty\left[, \alpha_{i k} \in\right.$ $[0,+\infty[(i, k=1, \ldots, n)$ such that the real part of every eigenvalue of the matrix $A=\left(-\delta_{i k} \alpha_{i}+\alpha_{i k}\right)_{i, k=1}^{n}$ is negative and the inequalities

$$
\begin{aligned}
& \sigma_{i} p_{i i}(t) \leq-\alpha_{i} \quad(i=1, \ldots, n), \\
& \left|p_{i i}(t) \int_{t}^{\tau_{i i}(t)}\right| p_{i k}(s)|d s|+\left(1-\delta_{i k}\right)\left|p_{i k}(t)\right| \leq \alpha_{i k}
\end{aligned}
$$

$$
(i, k=1, \ldots, n)
$$

hold almost everywhere on I. Then the problem (1'), (4) has a unique solution.
The last two corollaries concern with the Cauchy problems (1), (5) and (1'), (5).
Corollary 6. Let $t_{0} \in I$ and there exist a nonnegative integer $m_{0}$, a natural number $m>m_{0}$, and $\left.\alpha \in\right] 0,1[$ such that

$$
\begin{equation*}
\rho_{i m}(t) \leq \alpha \rho_{i m_{0}}(t) \quad \text { for } t \in I \quad(i=1, \ldots, n), \tag{32}
\end{equation*}
$$

where

$$
\begin{gathered}
\rho_{i 0}(t) \equiv 1 \quad(i=1, \ldots, n), \\
\rho_{i j}(t)=\sum_{k=1}^{n}\left|\int_{t_{0}}^{t} \bar{\ell}_{i k}\left(\rho_{k j-1}\right)(s) d s\right| \quad(i=1, \ldots, n ; j=1,2, \ldots) .
\end{gathered}
$$

Then the problem (1), (5) has a unique solution.
Proof. For every $i \in\{1, \ldots, n\}$ we define the following sequences of operators $\rho_{i j}: C\left(I ; \mathbb{R}^{n}\right) \rightarrow C(I ; \mathbb{R}):$

$$
\begin{gathered}
\rho_{i 0}\left(u_{1}, \ldots, u_{n}\right)(t) \stackrel{\text { def }}{=} u_{i}(t) \\
\rho_{i j}\left(u_{1}, \ldots, u_{n}\right)(t) \stackrel{\text { def }}{=} \sum_{k=1}^{n}\left|\int_{t_{0}}^{t} \bar{\ell}_{i k}\left(\rho_{k j-1}\left(u_{1}, \ldots, u_{n}\right)\right)(s) d s\right| \quad(j=1,2, \ldots)
\end{gathered}
$$

Then for any $\left(u_{i}\right)_{i=1}^{n} \in C\left(I ; \mathbb{R}^{n}\right)$,

$$
\begin{align*}
& \rho_{i j}\left(u_{1}, \ldots, u_{n}\right)(t)=\rho_{i j-j_{0}}\left(\rho_{1 j_{0}}\left(u_{1}, \ldots, u_{n}\right), \ldots, \rho_{n j_{0}}\left(u_{1}, \ldots, u_{n}\right)\right)(t)  \tag{33}\\
&\left(i=1, \ldots, n ; j \geq j_{0} ; j, j_{0}=0,1,2, \ldots\right)
\end{align*}
$$

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and

$$
\begin{equation*}
\rho_{i j}(1, \ldots, 1)(t)=\rho_{i j}(t) \quad(i=1, \ldots, n ; j=0,1,2, \ldots) . \tag{34}
\end{equation*}
$$

Now let $\left(y_{i}\right)_{i=1}^{n}$ be a solution of $\left(1_{0}\right)$ satisfying the initial conditions

$$
y_{i}\left(t_{0}\right)=0 \quad(i=1, \ldots, n)
$$

Then for every nonnegative integer $j$,

$$
\begin{equation*}
\left|y_{i}(t)\right| \leq \rho_{i j}\left(\left|y_{1}\right|, \ldots,\left|y_{n}\right|\right)(t) \quad(i=1, \ldots, n) . \tag{j}
\end{equation*}
$$

By (34) from ( $35_{m_{0}}$ ) we find

$$
\begin{equation*}
\left|y_{i}(t)\right| \leq \rho_{i m_{0}}(t) \sum_{k=1}^{n}\left\|y_{k}\right\|_{C} \quad(i=1, \ldots, n) \tag{36}
\end{equation*}
$$

Let for every $i \in\{1, \ldots, n\}$,

$$
v_{i}(t)= \begin{cases}0 & \text { if } \rho_{i m_{0}}(t)=0 \\ \frac{\left|y_{i}(t)\right|}{\rho_{i m_{0}}(t)} & \text { if } \rho_{i m_{0}}(t) \neq 0\end{cases}
$$

Then (36) yields

$$
\gamma_{i}=\operatorname{ess} \sup \left\{v_{i}(t): t \in I\right\}<+\infty \quad(i=1, \ldots, n)
$$

and

$$
\left|y_{i}(t)\right| \leq \gamma_{i} \rho_{i m_{0}}(t)=\gamma_{i} \rho_{i m_{0}}(1)(t) \quad(i=1, \ldots, n)
$$

whence by (32), (33) and ( $35_{m-m_{0}}$ ) for every $i \in\{1, \ldots, n\}$ we get

$$
\begin{aligned}
\left|y_{i}(t)\right| & \leq \rho_{i m-m_{0}}\left(\left|y_{1}\right|, \ldots,\left|y_{n}\right|\right)(t) \leq \\
& \leq \gamma \rho_{i m-m_{0}}\left(\rho_{1 m_{0}}(1), \ldots, \rho_{n m_{0}}(1)\right)(t)= \\
& =\gamma \rho_{i m}(1)(t)=\gamma \rho_{i m}(t) \leq \gamma \alpha \rho_{i m_{0}}(t),
\end{aligned}
$$

where $\gamma=\max \left\{\gamma_{1}, \ldots, \gamma_{n}\right\}$. Hence we obtain

$$
v_{i}(t) \leq \alpha \gamma \quad(i=1, \ldots, n)
$$

and, consequently,

$$
\gamma \leq \alpha \gamma
$$

Since $\alpha \in] 0,1\left[\right.$, we have $\gamma=0$, which implies $y_{i}(t) \equiv 0(i=1, \ldots, n)$. Consequently, the problem $(1),(5)$ has a unique solution.

If $m=2, m_{0}=1$, then Corollary 6 yields the following result for the problem ( $1^{\prime}$ ), (5):

Corollary $\mathbf{6}^{\prime}$. Let $t_{0} \in I$ and $\left.\alpha \in\right] 0,1[$ be such that

$$
\begin{array}{r}
\sum_{k=1}^{n}\left|\int_{t_{0}}^{t}\right| p_{i k}(s)\left|\sum_{j=1}^{n}\right| \int_{t_{0}}^{\tau_{i k}(s)}\left|p_{k j}(\xi)\right| d \xi|d s| \leq \alpha \sum_{k=1}^{n}\left|\int_{t_{0}}^{t}\right| p_{i k}(s)|d s|_{(i=1, \ldots, n)} \quad \text { for } t \in I \\
\end{array}
$$

Then the problem (1'), (5) has a unique solution.
At the end of this subsection we give the examples verifying the optimality of the above formulated conditions in the existence and uniqueness theorems.

Example 1. Let $n=2, \lambda_{1} \in\left[-1,1\left[, \lambda_{2} \in\right]-\infty,-1[\cup] 1,+\infty[\right.$. On the segment $I=[0,1]$ consider the system ( $1^{\prime}$ ) with the boundary conditions (3), where

$$
\begin{gathered}
p_{1 k}(t)=\left\{\begin{array}{ll}
\delta_{1 k}\left(\lambda_{1}-1\right) & \text { for } 0 \leq t \leq \frac{1}{2} \\
\left(1-\delta_{1 k}\right)\left(\lambda_{1}-1\right) & \text { for } \frac{1}{2}<t \leq 1
\end{array} \quad(k=1,2),\right. \\
p_{2 k}(t)=\left\{\begin{array}{ll}
\delta_{2 k}\left(\frac{\lambda_{2}-1}{\lambda_{2}}\right) & \text { for } 0 \leq t \leq \frac{1}{2} \\
\left(1-\delta_{2 k}\right)\left(\frac{\lambda_{2}-1}{\lambda_{2}}\right) & \text { for } \frac{1}{2}<t \leq 1
\end{array} \quad(k=1,2),\right. \\
\tau_{11}(t) \equiv \tau_{21}(t) \equiv 0,
\end{gathered} \tau_{12}(t) \equiv \tau_{22}(t) \equiv 1, \quad, ~
$$

$q_{i} \in L(I ; \mathbb{R})$, and $c_{i} \in \mathbb{R}(i=1,2)$. Then all the assumptions of Corollary $3^{\prime}$ with $\mu_{1}=1, \mu_{2}=\left|\lambda_{2}\right|$,

$$
A=\left(\begin{array}{ll}
1 / 2 & 1 / 2 \\
1 / 2 & 1 / 2
\end{array}\right)
$$

are fulfilled except the condition (10) instead of which we have

$$
\begin{equation*}
r(A)=1 \tag{37}
\end{equation*}
$$

On the other hand, the homogeneous problem

$$
\begin{gather*}
x_{i}^{\prime}(t)=\sum_{k=1}^{2} p_{i k}(t) x_{k}\left(\tau_{i k}(t)\right) \quad(i=1,2),  \tag{38}\\
x_{1}(1)=\lambda_{1} x_{1}(0), \quad x_{2}(1)=\lambda_{2} x_{2}(0) \tag{39}
\end{gather*}
$$

has the nontrivial solution

$$
x_{1}(t)=\left(\lambda_{1}-1\right) t+1, \quad x_{2}(t)=\frac{\lambda_{2}-1}{\lambda_{2}} t+\frac{1}{\lambda_{2}} .
$$

This example shows that the strict inequality (10) in Corollaries 3 and $3^{\prime}$ cannot be replaced by the nonstrict one.

Example 2. On the segment $I=[a, b]$ consider the problem (1'), (4) with $n \geq 2$, constant coefficients $p_{i i}(t) \equiv p_{i i}=-1, p_{i k}(t) \equiv p_{i k}=\frac{1}{n-1}(i \neq k ; i, k=1, \ldots, n)$, and $\tau_{i k}: I \rightarrow I(i, k=1, \ldots, n)$ arbitrary measurable functions. Then the vector $\gamma=\left(\gamma_{i}\right)_{i=1}^{n} \in \mathbb{R}^{n}$, where $\gamma_{1}=\gamma_{2}=\cdots=\gamma_{n} \neq 0$ satisfies the equality

$$
P \gamma=0,
$$

where $P=\left(p_{i k}\right)_{i, k=1}^{n}$, i.e., $P$ has a zero eigenvalue. Thus all the assumptions of Corollary $5^{\prime}$ are fulfilled with $\sigma_{i}=1, \alpha_{i}=\left|p_{i i}\right|, \alpha_{i k}=\left(1-\delta_{i k}\right) p_{i k},(i, k=1, \ldots, n)$, i.e., $A=P$, except the negativeness of real part of every eigenvalue of the matrix $A$.

On the other hand, the vector $\left(\gamma_{i}\right)_{i=1}^{n}$ is a nontrivial solution of the homogeneous problem

$$
x_{i}^{\prime}(t)=\sum_{k=1}^{n} p_{i k} x_{k}\left(\tau_{i k}(t)\right), \quad x_{i}(b)=x_{i}(a) .
$$

This example shows that in Corollaries 5 and $5^{\prime}$ the requirement on the negativeness of the real part of every eigenvalue of the matrix $A$ cannot be weakened.
Example 3. Let $I=[0,1], t_{0}=0, \tau_{i k}(t) \equiv 1(i, k=1, \ldots, n)$

$$
p_{i k}(t)= \begin{cases}1 & \text { for } t \in\left[\frac{k-1}{n}, \frac{k}{n}[ \right. \\ 0 & \text { for } t \in I \backslash\left[\frac{k-1}{n}, \frac{k}{n}[\quad(i, k=1, \ldots, n),\right.\end{cases}
$$

and consider the problem ( $1^{\prime}$ ), (5). Put

$$
\begin{aligned}
& \rho_{i 0}(t) \equiv 1, \quad \rho_{i j}(t)=\sum_{k=1}^{n} \int_{0}^{t} p_{i k}(s) \rho_{i j-1}\left(\tau_{i k}(s)\right) d s \\
& \quad(i=1, \ldots, n ; j=1,2, \ldots) .
\end{aligned}
$$

Then

$$
\rho_{i j}(t)=t \quad(i=1, \ldots, n ; j=1,2, \ldots)
$$

and for every nonnegative integer $m_{0}$ and every natural number $m>m_{0}$ we have

$$
\rho_{i m}(t) \leq \rho_{i m_{0}}(t) \quad \text { for } t \in I \quad(i=1, \ldots, n) .
$$

On the other hand,

$$
x_{i}(t)=t \quad(i=1, \ldots, n)
$$

is a nontrivial solution of the homogeneous problem

$$
x_{i}^{\prime}(t)=\sum_{k=1}^{n} p_{i k}(t) x_{k}\left(\tau_{i k}(t)\right), \quad x_{i}\left(t_{0}\right)=0 .
$$

The last example shows that in Corollaries 6 and $6^{\prime}$ we cannot choose $\alpha=1$.

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[^1]:    ${ }^{1}$ The vector function $x=\left(x_{i}\right)_{i=1}^{n}: I \rightarrow \mathbb{R}^{n}$ is said to be continuous, bounded, summable, etc., if the components $x_{i}: I \rightarrow \mathbb{R}(i=1, \ldots, n)$ have such a property.

