# Existence of solutions for multi-point boundary value problem of fractional $q$-difference equation ${ }^{\star}$ 

Junchi Ma ${ }^{1, *} \quad$ Jun Yang ${ }^{\mathbf{1 , 2}}$<br>${ }^{1}$ College of Science, Yanshan University, Qinhuangdao Hebei 066004, China<br>${ }^{2}$ Mathematics Research Center in Hebei Province, Shijiazhuang 050000, China


#### Abstract

This paper is mainly concerned with the existence of solutions for a multi-point boundary value problem of nonlinear fractional q-difference equations by means of the Banach contraction principle and Krasnoselskii's fixed point theorem. Further, an example is presented to illustrate the main results.


Keywords: Fractional q-difference equations; Multi-point condition; Fixed point theorem.
2000 MR Subject Classification: 34B08, 34B18, 39A13

## 1 Introduction

Fractional differential calculus have recently been addressed by many researchers of various fields of science and engineering such as physics, chemistry, biology, economics, control theory, and biophysics, etc. [1-4]. In particular, the existence of solutions to fractional boundary value problems is under strong research recently, see $[5-7]$ and references therein.

The fractional q-difference calculus had its origin in the works by Al-Salam [8] and Agarwal [9]. More recently, perhaps due to the explosion in research within the fractional differential calculus setting, new developments in this theory of fractional q-difference calculus were made, specifically, $q$-analogues of the integral and differential fractional operators properties such as the q-Laplace transform, q-Taylor's formula $[10,11]$, just to mention some.

The question of the existence of solutions for fractional q-difference boundary value problems is in its infancy, being few results available in the literature.

Ferreira [12] considered the existence of positive solutions to nonlinear q-difference boundary value problem:

$$
\begin{aligned}
& \left(D_{q}^{\alpha} u\right)(t)=-f(t, u(t)), \quad 0<t<1,1<\alpha \leq 2 \\
& u(0)=u(1)=0 .
\end{aligned}
$$

In other paper, Ferreira [13] studied the existence of positive solutions to nonlinear q-difference boundary value problem:

$$
\begin{aligned}
& \left(D_{q}^{\alpha} u\right)(t)=-f(t, u(t)), \quad 0<t<1,2<\alpha \leq 3 \\
& u(0)=\left(D_{q} u\right)(0)=0,\left(D_{q} u\right)(1)=\beta \geq 0 .
\end{aligned}
$$

M.El-Shahed and Farah M.Al-Askar [15] studied the existence of positive solutions to nonlinear q-difference equation:

$$
\begin{aligned}
& \left({ }_{c} D_{q}^{\alpha} u\right)(t)+a(t) f(u(t))=0, \quad 0 \leq t \leq 1,2<\alpha \leq 3 \\
& u(0)=\left(D_{q}^{2} u\right)(0)=0, \gamma D_{q} u(1)+\beta D_{q}^{2} u(1)=0 .
\end{aligned}
$$

[^0]In this paper, we investigate the existence of solutions for nonlinear q-difference boundary value problem of the form

$$
\begin{align*}
& \left({ }_{c} D_{q}^{\alpha} u\right)(t)=-f(t, u(t),(\phi u)(t),(\psi u)(t)), \quad 1<t<2,1<\alpha \leq 2 \\
& u(0)=u_{0}+g(u), D_{q} u(1)=u_{1}+\sum_{i=1}^{m-2} b_{i} D_{q} u\left(\xi_{i}\right) \tag{1.1}
\end{align*}
$$

where $0<\xi_{i}<1(i=1,2, \ldots, m-2), b_{i} \geq 0$ with $\rho=\sum_{i=1}^{m-2} b_{i}<1$ and ( ${ }_{C} D_{q}^{\alpha}$ represents the standard Caputo fractional q-derivative), $f:[0,1] \times X \times X \times X \rightarrow X$ is continuous, for $\gamma, \delta:[0,1] \times[0,1] \rightarrow[0, \infty)$,

$$
(\phi u)(t)=\int_{0}^{t} \gamma(t, s) u(s) d_{q} s, \quad(\psi u)(t)=\int_{0}^{t} \delta(t, s) u(s) d_{q} s
$$

Here, $(X,\|\cdot\|)$ is a Banach space and $C=C([0,1], X)$ denotes the Banach space of all continuous functions from $[0,1] \rightarrow X$ endowed with a topology of uniform convergence with the norm denoted by $\|\cdot\|$.

## 2 Preliminaries on fractional q-calculus

Let $q \in(0,1)$ and define

$$
[a]_{q}=\frac{1-q^{a}}{1-q}, a \in \mathbb{R} .
$$

The q-analogue of the power function $(a-b)^{n}$ with $n \in \mathbb{N}_{0}$ is

$$
(a-b)^{0}=1,(a-b)^{n}=\prod_{k=0}^{n-1}\left(a-b q^{k}\right), n \in \mathbb{N}, a, b \in \mathbb{R}
$$

More generally, if $\alpha \in \mathbb{R}$, then

$$
(a-b)^{(\alpha)}=a^{\alpha} \prod_{i=0}^{\infty} \frac{a-b q^{i}}{a-b q^{\alpha+i}}
$$

Note that, if $b=0$ then $a^{(\alpha)}=a^{\alpha}$. The q-gamma function is defined by

$$
\Gamma_{q}(x)=\frac{(1-q)^{(x-1)}}{(1-q)^{x-1}}, x \in \mathbb{R} \backslash\{0,-1,-2 \ldots\}, 0<q<1
$$

and satisfies $\Gamma_{q}(x+1)=[x]_{q} \Gamma_{q}(x)$.
The q-derivative of a function $f(x)$ is here defined by

$$
\left(D_{q} f\right)(x)=\frac{f(q x)-f(x)}{(q-1) x}(x \neq 0),\left(D_{q} f\right)(0)=\lim _{x \rightarrow 0}\left(D_{q} f\right)(x)
$$

and q-derivatives of higher order by

$$
\left(D_{q}^{n} f\right)(x)= \begin{cases}f(x) & \text { if } n=0 \\ D_{q} D_{q}^{n-1} f(x) & \text { if } n \in \mathbb{N}\end{cases}
$$

The q-integral of a function $f(x)$ defined in the interval $[0, b]$ is given by

$$
\left(I_{q} f\right)(x)=\int_{0}^{x} f(t) d_{q} t=x(1-q) \sum_{n=0}^{\infty} f\left(x q^{n}\right) q^{n}, 0 \leq|q|<1, x \in[0, b]
$$

If $a \in[0, b]$ and $f$ is defined in the interval $[0, b]$, its integral from $a$ to $b$ is defined by

$$
\int_{a}^{b} f(t) d_{q} t=\int_{0}^{b} f(t) d_{q} t-\int_{0}^{a} f(t) d_{q} t
$$

If $c_{j}=b q^{j}$, for $j \in\{0,1, \ldots, n\}, a=c_{n}=b q^{n}, 0<q<1$.
The restricted q -integral of a function $f(x)$ defined by

$$
\int_{a}^{b} f(t) d_{q} t=\int_{b q^{n}}^{b} f(t) d_{q} t=(1-q) b \sum_{j=0}^{n-1} q^{j} f\left(b q^{j}\right)=(1-q) \sum_{j=0}^{n-1} c_{j} f\left(c_{j}\right), 0<q<1, b>0, n \in \mathbb{Z}^{+}
$$

Note that the restricted integral $\int_{a}^{b} f(t) d_{q} t$ is just a finite sum, so no questions about convergence arise.
Obviously, if $f(x) \geq g(x)$ on $[a, b]$, then $\int_{a}^{b} f(t) d_{q} t \geq \int_{a}^{b} g(t) d_{q} t$. If $0<k<n$, then

$$
\int_{a}^{b} f(t) d_{q} t=\int_{a}^{c_{k}} f(t) d_{q} t+\int_{c_{k}}^{b} f(t) d_{q} t
$$

The usual Riemann integral can be considered as a limit of the restricted definite q-integral in the following way. Since $a=b q^{n}, q=\left(\frac{a}{b}\right)^{\frac{1}{n}}$. Fix $a$ and $b$ and let $n \rightarrow \infty$ (hence, $q \rightarrow 1$ ). Then, $\int_{a}^{b} f(t) d_{q} t \rightarrow \int_{a}^{b} f(t) d t$ assuming that $f(t)$ is Riemann integrable on $[a, b]$. The above formulas were proved by the author [17].

Similarly as done for derivatives, it can be defined an operator $I_{q}^{n}$, namely,

$$
\left(I_{q}^{n} f\right)(x)= \begin{cases}f(x) & \text { if } n=0 \\ I_{q} I_{q}^{n-1} f(x) & \text { if } n \in \mathbb{N}\end{cases}
$$

The fundamental theorem of calculus applies to these operators $I_{q}$ and $D_{q}$, i.e.,

$$
\left(D_{q} I_{q} f\right)(x)=f(x),
$$

and if $f$ is continuous at $x=0$, then

$$
\left(I_{q} D_{q} f\right)(x)=f(x)-f(0) .
$$

and, more generally

$$
\begin{aligned}
& \left(D_{q}^{n} I_{q}^{n} f\right)(x)=f(x), n \in \mathbb{N}, \\
& \left(I_{q}^{n} D_{q}^{n} f\right)(x)=f(x)-\sum_{k=0}^{n-1} \frac{x^{k}}{\Gamma_{q}(k+1)}\left(D_{q}^{k} f\right)(0), n \in \mathbb{N} .
\end{aligned}
$$

Basic properties of the two operators can be found in the book [14]. We point out here five formulas that will be used later, namely, the integration by parts formula

$$
\int_{0}^{x} f(t)\left(D_{q} g\right) t d_{q} t=[f(t) g(t)]_{t=0}^{t=x}-\int_{0}^{x}\left(D_{q} f\right) g(q t) t d_{q} t
$$

and $\left({ }_{i} D_{q}\right.$ denotes the derivative with respect to variable $\left.i\right)$

$$
\begin{aligned}
& {[a(t-s)]^{(\alpha)}=a^{\alpha}(t-s)^{(\alpha)},} \\
& { }_{t} D_{q}(t-s)^{(\alpha)}=[\alpha]_{q}(t-s)^{(\alpha-1)}, \\
& { }_{s} D_{q}(t-s)^{(\alpha)}=-[\alpha]_{q}(t-q s)^{(\alpha-1)}, \\
& \left.{ }_{{ }_{x} D_{q}} \int_{0}^{x} f(x, t) d_{q} t\right)(x)=\int_{0}^{x}{ }_{x} D_{q} f(x, t) d_{q} t+f(q x, x) .
\end{aligned}
$$

Remark 2.1. We note that if $\alpha>0$ and $a \leq b \leq t$, then $(t-a)^{(\alpha)} \geq(t-b)^{(\alpha)}[12]$.
The following definition was considered first in [9].

Definition 2.2. Let $\alpha \geq 0$ and $f$ be a function defined on $[0,1]$. The fractional q-integral of the RiemannLiouville type is $\left(I_{q}^{0} f\right)(x)=f(x)$ and

$$
\left(I_{q}^{\alpha} f\right)(x)=\frac{1}{\Gamma_{q}(\alpha)} \int_{0}^{x}(x-q t)^{(\alpha-1)} f(t) d_{q} t, \alpha>0, x \in[0,1]
$$

Definition 2.3. The fractional q-derivative of the Riemann-Liouville type of order $\alpha \geq 0$ is defined by $\left(D_{q}^{0} f\right)(x)=f(x)$ and

$$
\left(D_{q}^{\alpha} f\right)(x)=\left(D_{q}^{m} I_{q}^{m-\alpha} f\right)(x), \alpha>0
$$

where $m$ is the smallest integer greater than or equal to $\alpha$.
Definition 2.4. [16] The fractional q-derivative of the Caputo type of order $\alpha \geq 0$ is defined by

$$
\left({ }_{C} D_{q}^{\alpha} f\right)(x)=\left(I_{q}^{m-\alpha} D_{q}^{m} f\right)(x), \alpha>0
$$

where $m$ is the smallest integer greater than or equal to $\alpha$.
Next, let us list some properties that are already know in the literature.
Lemma 2.5. Let $\alpha, \beta \geq 0$ and $f$ be a function defined on $[0,1]$. Then, the next formulas hold:

$$
\begin{aligned}
& \text { 1. }\left(I_{q}^{\beta} I_{q}^{\alpha} f\right)(x)=\left(I_{q}^{\alpha+\beta} f\right)(x), \\
& \text { 2. }\left(D_{q}^{\alpha} I_{q}^{\alpha} f\right)(x)=f(x)
\end{aligned}
$$

The next result is important in the sequel. It was proved in a recent work by the author [12].
Theorem 2.1. [12] Let $\alpha>0$ and $n \in \mathbb{N}$. Then, the following equality holds:

$$
\left(I_{q}^{\alpha} D_{q}^{n} f\right)(x)=D_{q}^{n} I_{q}^{\alpha} f(x)-\sum_{k=0}^{n-1} \frac{x^{\alpha-n+k}}{\Gamma_{q}(\alpha+k-n+1)}\left(D_{q}^{k} f\right)(0)
$$

Theorem 2.2. [16] Let $\alpha \in \mathbb{R}^{+} \backslash \mathbb{N}$. Then, the following equality holds:

$$
\left(I_{q}^{\alpha} D_{q}^{\alpha} f\right)(x)=f(x)-\sum_{k=0}^{m-1} \frac{x^{k}}{\Gamma_{q}(k+1)}\left(D_{q}^{k} f\right)(0)
$$

where $m$ is the smallest integer greater than or equal to $\alpha$.
Lemma 2.6. For a given $\sigma \in C[0,1]$ and $1<\alpha \leq 2$, the unique solution of

$$
\begin{align*}
& \left({ }_{C} D_{q}^{\alpha} u\right)(t)=-\sigma(t) \\
& u(0)=u_{0}+g(u), D_{q} u(1)=u_{1}+\sum_{i=1}^{m-2} b_{i} D_{q} u\left(\xi_{i}\right), \tag{2.1}
\end{align*}
$$

is given by

$$
\begin{aligned}
u(t)= & -\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)} \sigma(s) d_{q} s+\frac{1}{1-\rho} \int_{0}^{1} \frac{(1-q s)^{(\alpha-2)} t}{\Gamma_{q}(\alpha-1)} \sigma(s) d_{q} s \\
& -\frac{1}{1-\rho} \sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)} t}{\Gamma_{q}(\alpha-1)} \sigma(s) d_{q} s+u_{0}+g(u)+\frac{1}{1-\rho} u_{1} t .
\end{aligned}
$$

Proof. Let us put $m=2$. In view of Lemma 2.5 and Theorem 2.2, we have

$$
\begin{align*}
\left({ }_{C} D_{q}^{\alpha} u\right)(t)=-\sigma(t) & \Longleftrightarrow\left(I_{q}^{\alpha} I_{q}^{2-\alpha}{ }_{C} D_{q}^{2} u\right)(t)=-I_{q}^{\alpha} \sigma(t) \\
& \Longleftrightarrow u(t)=-\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)} \sigma(s) d_{q} s+c_{0}+c_{1} t \tag{2.2}
\end{align*}
$$

for some constants $c_{0}, c_{1} \in \mathbb{R}$. Using the boundary condition $u(0)=u_{0}+g(u)$, gives $c_{0}=u_{0}+g(u)$.
Furthermore, differentiation of (2.2) with respect to $t$ produces

$$
D_{q} u(x)=-\int_{0}^{t} \frac{[\alpha-1]_{q}(t-q s)^{(\alpha-2)}}{\Gamma_{q}(\alpha)} \sigma(s) d_{q} s+c_{1}
$$

Using the boundary conditions $D_{q} u(1)=\sum_{i=1}^{m-2} b_{i} D_{q} u\left(\xi_{i}\right)$, we get

$$
c_{1}=\frac{1}{1-\rho} \int_{0}^{1} \frac{(1-q s)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)} \sigma(s) d_{q} s-\frac{1}{1-\rho} \sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)} \sigma(s) d_{q} s+\frac{u_{1}}{1-\rho}
$$

Now, substitution of $c_{0}$ and $c_{1}$ into (2.1) gives

$$
\begin{aligned}
u(t)= & -\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)} \sigma(s) d_{q} s+\frac{1}{1-\rho} \int_{0}^{1} \frac{(1-q s)^{(\alpha-2)} t}{\Gamma_{q}(\alpha-1)} \sigma(s) d_{q} s \\
& -\frac{1}{1-\rho} \sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)} t}{\Gamma_{q}(\alpha-1)} \sigma(s) d_{q} s+\frac{u_{1} t}{1-\rho}+u_{0}+g(u) .
\end{aligned}
$$

The proof is complete.

## 3 Main results

Define an operator $T: C \rightarrow C$ by

$$
\begin{align*}
(T u)(t)= & u_{0}+g(u)+\frac{u_{1} t}{1-\rho}-\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s \\
& +\frac{t}{1-\rho} \int_{0}^{1} \frac{(1-q s)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s  \tag{3.1}\\
& -\frac{t}{1-\rho} \sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s, \quad t \in[0,1] .
\end{align*}
$$

Clearly, the fixed points of the operator $T$ are solutions of problem (1.1).
To establish the main results, we need the following assumptions:
$\left(H_{1}\right)$ There exist positive functions $L_{1}(t), L_{2}(t), L_{3}(t)$ such that

$$
\begin{aligned}
& \|f(t, u(t),(\phi u)(t),(\psi u)(t))-f(t, v(t),(\phi v)(t),(\psi v)(t))\| \\
& \quad \leq L_{1}(t)\|u-v\|+L_{2}(t)\|\phi u-\phi v\|+L_{3}(t)\|\psi u-\psi v\|, \quad t \in[0,1], u, v \in X
\end{aligned}
$$

$\left(H_{2}\right) g: C \rightarrow X$ is continuous and there exists a constant $b$ such that

$$
\|g(u)-g(v)\| \leq b\|u-v\|, u, v \in C
$$

Further,

$$
\begin{aligned}
& \gamma_{0}=\sup _{t \in[0,1]}\left|\int_{0}^{t} \gamma(t, s) d_{q} s\right|, \quad \delta_{0}=\sup _{t \in[0,1]}\left|\int_{0}^{t} \delta(t, s) d_{q} s\right| \\
& I_{q}^{\alpha} L=\max \left\{\sup _{t \in[0,1]}\left|I_{q}^{\alpha} L_{1}(t)\right|, \sup _{t \in[0,1]}\left|I_{q}^{\alpha} L_{2}(t)\right|, \sup _{t \in[0,1]}\left|I_{q}^{\alpha} L_{3}(t)\right|\right\} \\
& I_{q}^{\alpha-1} L(1)=\max \left\{\left|I_{q}^{\alpha-1} L_{1}(1)\right|,\left|I_{q}^{\alpha-1} L_{2}(1)\right|,\left|I_{q}^{\alpha-1} L_{3}(1)\right|\right\} \\
& I_{q}^{\alpha-1} L\left(\xi_{i}\right)=\max \left\{\left|I_{q}^{\alpha-1} L_{1}\left(\xi_{i}\right)\right|,\left|I_{q}^{\alpha-1} L_{2}\left(\xi_{i}\right)\right|,\left|I_{q}^{\alpha-1} L_{3}\left(\xi_{i}\right)\right|\right\}, \xi_{i}=1,2, \ldots, m-2 .
\end{aligned}
$$

$\left(H_{3}\right)$ There exists a number $\wedge \leq \kappa<1$, where

$$
\wedge=\left(1+\gamma_{0}+\delta_{0}\right)\left\{I_{q}^{\alpha} L+\frac{1}{1-\rho}\left(I_{q}^{\alpha-1} L(1)+\sum_{i=1}^{m-2} b_{i} I_{q}^{\alpha-1} L\left(\xi_{i}\right)\right)\right\}
$$

$\left(H_{4}\right)$ There exists a number $\Delta$, where

$$
\begin{aligned}
& \Delta=b+\left(1+\gamma_{0}+\delta_{0}\right)\left\{I_{q}^{\alpha} L+\frac{1}{1-\rho}\left(I_{q}^{\alpha-1} L(1)+\sum_{i=1}^{m-2} b_{i} I_{q}^{\alpha-1} L\left(\xi_{i}\right)\right)\right\} . \\
& \left(H_{5}\right)\|f(t, u(t),(\phi u)(t),(\psi u)(t))\| \leq \mu(t), \forall(t, u(t),(\phi u),(\psi u)) \in[0,1] \times X \times X \times X, \mu \in L^{1}\left([0,1], R^{+}\right) .
\end{aligned}
$$

Theorem 3.1. Assume that $f:[0,1] \times X \times X \times X \rightarrow X$ is jointly continuous function and satisfies the assumptions $\left(H_{1}\right)-\left(H_{4}\right)$, then problem (1.1) has a unique solution provided $\wedge<1$, where $\wedge$ is given in the assumption $\left(H_{3}\right)$.

Proof. Let us set $\sup _{t \in[0,1]}|f(t, 0,0,0)|=M$, and choose

$$
r \geq \frac{1}{1-\wedge}\left\{\left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho}+M\left[\frac{1}{\Gamma_{q}(\alpha+1)}+\frac{1}{(1-\rho) \Gamma_{q}(\alpha)}\left(1+\sum_{i=1}^{m-2} b_{i} \xi_{i}^{(\alpha-1)}\right)\right]\right\}
$$

where $\lambda$ is such that $\wedge \leq \lambda<1$. We show that $T B_{r} \subset B_{r}$, where $B_{r}=\{x \in C:\|u\| \leq r\}$. So let $u \in B_{r}$ and set $G=\sup _{u \in C}\|g(u)\|$. Then we have
$\|(T u)(t)\|$

$$
\begin{aligned}
& \leq\left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho}+\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)}\|f(s, u(s),(\phi u)(s),(\psi u)(s))\| d_{q} s \\
&+\frac{1}{1-\rho}\left\{\int_{0}^{1} \frac{(1-q s)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\|f(s, u(s),(\phi u)(s),(\psi u)(s))\| d_{q} s\right. \\
&\left.+\sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\|f(s, u(s),(\phi u)(s),(\psi u)(s))\| d_{q} s\right\} \\
& \leq\left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho} \\
&+\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)}(\|f(s, u(s),(\phi u)(s),(\psi u)(s))-f(s, 0,0,0)\|+\|f(s, 0,0,0)\|) d_{q} s \\
&+\frac{1}{1-\rho}\left\{\int_{0}^{1} \frac{(1-q s)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}(\|f(s, u(s),(\phi u)(s),(\psi u)(s))-f(s, 0,0,0)\|+\|f(s, 0,0,0)\|) d_{q} s\right. \\
&\left.+\sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}(\|f(s, u(s),(\phi u)(s),(\psi u)(s))-f(s, 0,0,0)\|+\|f(s, 0,0,0)\|) d_{q} s\right\} \\
& \leq\left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho} \\
&+\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)}\left(L_{1}(s)\|u(s)\|+L_{2}(s)\|(\phi u)(s)\|+L_{3}(s)\|(\psi u)(s)\|+M\right) d_{q} s \\
&+\frac{1}{1-\rho}\left\{\int_{0}^{1} \frac{(1-q s)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\left(L_{1}(s)\|u(s)\|+L_{2}(s)\|(\phi u)(s)\|+L_{3}(s)\|(\psi u)(s)\|+M\right) d_{q} s\right. \\
&\left.+\sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\left(L_{1}(s)\|u(s)\|+L_{2}(s)\|(\phi u)(s)\|+L_{3}(s)\|(\psi u)(s)\|+M\right) d_{q} s\right\} \\
& \mathrm{EJQTDE}, 2011 \mathrm{No.}
\end{aligned}
$$

$$
\begin{aligned}
\leq & \left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho}+\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)}\left(L_{1}(s)\|u(s)\|+\gamma_{0} L_{2}(s)\|u(s)\|+\delta_{0} L_{3}(s)\|u(s)\|+M\right) d_{q} s \\
& +\frac{1}{1-\rho}\left\{\int_{0}^{1} \frac{(1-q s)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\left(L_{1}(s)\|u(s)\|+\gamma_{0} L_{2}(s)\|u(s)\|+\delta_{0} L_{3}(s)\|u(s)\|+M\right) d_{q} s\right. \\
& \left.+\sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\left(L_{1}(s)\|u(s)\|+\gamma_{0} L_{2}(s)\|u(s)\|+\delta_{0} L_{3}(s)\|u(s)\|+M\right) d_{q} s\right\} \\
\leq & \left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho}+\left(I_{q}^{\alpha} L_{1}(t)+\gamma_{0} I_{q}^{\alpha} L_{2}(t)+\delta_{0} I_{q}^{\alpha} L_{3}(t)\right) r+\frac{M t^{(\alpha)}}{\Gamma_{q}(\alpha+1)} \\
& +\frac{1}{1-\rho}\left\{\left(I_{q}^{\alpha-1} L_{1}(1)+\gamma_{0} I_{q}^{\alpha-1} L_{2}(1)+\delta_{0} I_{q}^{\alpha-1} L_{3}(1)\right) r+\frac{M}{\Gamma_{q}(\alpha)}\right. \\
& \left.+\sum_{i=1}^{m-2} b_{i}\left(\left(I_{q}^{\alpha-1} L_{1}\left(\xi_{i}\right)+\gamma_{0} I_{q}^{\alpha-1} L_{2}\left(\xi_{i}\right)+\delta_{0} I_{q}^{\alpha-1} L_{3}\left(\xi_{i}\right)\right) r+\frac{M \xi_{i}^{(\alpha-1)}}{\Gamma_{q}(\alpha)}\right)\right\} \\
\leq & \left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho}+I_{q}^{\alpha} L\left(1+\gamma_{0}+\delta_{0}\right) r+\frac{M}{\Gamma_{q}(\alpha+1)} \\
& +\frac{1}{1-\rho}\left\{I_{q}^{\alpha-1} L(1)\left(1+\gamma_{0}+\delta_{0}\right) r+\frac{M}{\Gamma_{q}(\alpha)}\right. \\
& \left.+\sum_{i=1}^{m-2} b_{i}\left(I_{q}^{\alpha-1} L\left(\xi_{i}\right)\left(1+\gamma_{0}+\delta_{0}\right) r+\frac{M \xi_{i}^{(\alpha-1)}}{\Gamma_{q}(\alpha)}\right)\right\} \\
\leq & \left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho}+\left(1+\gamma_{0}+\delta_{0}\right)\left\{I_{q}^{\alpha} L+\frac{1}{1-\rho}\left(I_{q}^{\alpha-1} L(1)+\sum_{i=1}^{m-2} b_{i} I_{q}^{\alpha-1} L\left(\xi_{i}\right)\right)\right\} r \\
& +M\left\{\frac{1}{\Gamma_{q}(\alpha+1)}+\frac{1}{1-\rho}\left(\frac{1}{\Gamma_{q}(\alpha)}+\frac{\sum_{i=1}^{m-2} b_{i} \xi_{i}^{(\alpha-1)}}{\Gamma_{q}(\alpha)}\right)\right\} \\
\leq & \left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho}+\wedge r+M\left\{\frac{1}{\Gamma_{q}(\alpha+1)}+\frac{1}{(1-\rho) \Gamma_{q}(\alpha)}\left(1+\sum_{i=1}^{m-2} b_{i} \xi_{i}^{(\alpha-1)}\right)\right\} \leq r
\end{aligned}
$$

Now, for $u, v \in C$ and for each $t \in[0,1]$, we obtain

$$
\begin{aligned}
& \|(T u)(t)-(T v)(t) \| \\
& \leq\|g(u)-g(v)\|+\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)}\|f(s, u(s),(\phi u)(s),(\psi u)(s))-f(s, v(s),(\phi v)(s),(\psi v)(s))\| d_{q} s \\
&+\frac{1}{1-\rho}\left\{\int_{0}^{1} \frac{(1-q s)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\|f(s, u(s),(\phi u)(s),(\psi u)(s))-f(s, v(s),(\phi v)(s),(\psi v)(s))\| d_{q} s\right. \\
&\left.+\sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\|f(s, u(s),(\phi u)(s),(\psi u)(s))-f(s, v(s),(\phi v)(s),(\psi v)(s))\| d_{q} s\right\} \\
& \leq\|g(u)-g(v)\|+\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)}\left(L_{1}(s)\|u-v\|+L_{2}(s)\|\phi u-\phi v\|+L_{3}(s)\|\psi u-\psi v\|\right) d_{q} s \\
&+\frac{1}{1-\rho}\left\{\int_{0}^{1} \frac{(1-q s)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\left(L_{1}(s)\|u-v\|+L_{2}(s)\|\phi u-\phi v\|+L_{3}(s)\|\psi u-\psi v\|\right) d_{q} s\right. \\
&\left.+\sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)}}{\Gamma_{q}(\alpha-1)}\left(L_{1}(s)\|u-v\|+L_{2}(s)\|\phi u-\phi v\|+L_{3}(s)\|\psi u-\psi v\|\right) d_{q} s\right\} \\
& \text { EJQTDE, 2011 No. 92, p. } 7
\end{aligned}
$$

$$
\begin{aligned}
\leq & \|g(u)-g(v)\|+\left(I_{q}^{\alpha} L_{1}(t)+\gamma_{0} I_{q}^{\alpha} L_{2}(t)+\delta_{0} I_{q}^{\alpha} L_{3}(t)\right)\|u-v\| \\
& +\frac{1}{1-\rho}\left\{I_{q}^{\alpha-1} L_{1}(1)+\gamma_{0} I_{q}^{\alpha-1} L_{2}(1)+\delta_{0} I_{q}^{\alpha-1} L_{3}(1)\right. \\
& \left.+\sum_{i=1}^{m-2} b_{i}\left(I_{q}^{\alpha-1} L_{1}\left(\xi_{i}\right)+\gamma_{0} I_{q}^{\alpha-1} L_{2}\left(\xi_{i}\right)+\delta_{0} I_{q}^{\alpha-1} L_{3}\left(\xi_{i}\right)\right)\right\}\|u-v\| \\
\leq & b\|u-v\|+\left(1+\gamma_{0}+\delta_{0}\right)\left\{I_{q}^{\alpha} L+\frac{1}{1-\rho}\left(I_{q}^{\alpha-1} L(1)+\sum_{i=1}^{m-2} b_{i} I_{q}^{\alpha-1} L\left(\xi_{i}\right)\right)\right\}\|u-v\| \\
= & \Delta\|u-v\|
\end{aligned}
$$

where $\wedge$ is given in the assumption $\left(H_{4}\right)$. As $\Delta<1$, therefore $T$ is a contraction. Thus, the conclusion of the theorem follows by the contraction mapping principle.

Now, we state Krasnoselskii's fixed point theorem which is needed to prove the existence of at least one solution of (1.1).

Theorem 3.2. Let $K$ be a closed convex and nonempty subset of a Banach space $X$. Let $T, S$ be the operators such that $(i) T u+S v \in K$ whenever $u, v \in K ;(i i) T$ is compact and continuous; (iii) $S$ is a contraction mapping. Then there exists $z \in K$ such that $z=T z+S z$.

Theorem 3.3. Suppose that $f:[0,1] \times X \times X \times X \rightarrow X$ is jointly continuous and the assumptions $\left(H_{1}\right)-\left(H_{2}\right)$ and $\left(H_{5}\right)$ hold with

$$
\wedge_{1}=b+\left(1+\gamma_{0}+\delta_{0}\right)\left\{\frac{1}{1-\rho}\left(I_{q}^{\alpha-1} L(1)+\sum_{i=1}^{m-2} b_{i} I_{q}^{\alpha-1} L\left(\xi_{i}\right)\right)\right\}<1 .
$$

Then there exists at least one solution of the boundary value problem (1.1) on $[0,1]$.
Proof. Choose

$$
r \geq\left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho}+\|\mu\|_{L^{1}}\left\{\frac{1}{\Gamma_{q}(\alpha+1)}+\frac{1}{(1-\rho) \Gamma_{q}(\alpha)}\left(1+\sum_{i=1}^{m-2} b_{i} \xi_{i}^{(\alpha-1)}\right)\right\}
$$

and consider $\Omega_{r}=\{u \in C:\|u\| \leq r\}$. We define the operators $T_{1}$ and $T_{2}$ on $\Omega_{r}$ as

$$
\begin{aligned}
\left(T_{1} u\right)(t)= & u_{0}-\int_{0}^{t} \frac{(t-q s)^{(\alpha-1)}}{\Gamma_{q}(\alpha)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s \\
\left(T_{2} u\right)(t)= & g(u)+\frac{u_{1} t}{1-\rho}+\frac{1}{1-\rho}\left\{\int_{0}^{1} \frac{(1-q s)^{(\alpha-2)} t}{\Gamma_{q}(\alpha-1)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s\right. \\
& \left.-\sum_{i=1}^{m-2} b_{i} \int_{0}^{\xi_{i}} \frac{\left(\xi_{i}-q s\right)^{(\alpha-2)} t}{\Gamma_{q}(\alpha-1)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s\right\} .
\end{aligned}
$$

Let's observe that if $u, v \in \Omega_{r}$ then $T_{1} u+T_{2} v \in \Omega_{r}$. Indeed it is easy to check the inequality

$$
\left\|T_{1} u+T_{2} v\right\| \leq\left\|u_{0}\right\|+G+\frac{\left\|u_{1}\right\|}{1-\rho}+\|\mu\|_{L^{1}}\left\{\frac{1}{\Gamma_{q}(\alpha+1)}+\frac{1}{(1-\rho) \Gamma_{q}(\alpha)}\left(1+\sum_{i=1}^{m-2} b_{i} \xi_{i}^{(\alpha-1)}\right)\right\} \leq r
$$

By $\left(H_{1}\right)$, it is also that $T_{2}$ is a contraction mapping for $\wedge_{1}<1$.

Since $f$ is continuous, then $\left(T_{1} u\right)(t)$ is continuous. Let's now note that $T_{1}$ is uniformly bounded on $\Omega_{r}$. This follows from the inequality

$$
\left\|\left(T_{1} u\right)(t)\right\| \leq\left\|u_{0}\right\|+\frac{\left\|u_{1}\right\|}{1-\rho}+\frac{\|\mu\|_{L^{1}}}{\Gamma_{q}(\alpha+1)}
$$

Now, we show that $T_{1}\left(\Omega_{r}\right)$ is equicontinuous. The functions $T_{1} u, u \in \Omega_{r}$ are equicontinuous at $t=0$. For $t_{1}, t_{2} \in\left\{q^{n}: n \in \mathbb{N}_{\nvdash}\right\}$, and $t_{1}<t_{2}$. Using the fact that $f$ is bounded on the compact set $[0,1] \times \Omega_{r} \times \Omega_{r} \times \Omega_{r}$, therefore, we define $\sup _{(t, u, \phi u, \psi u) \in[0,1] \times \Omega_{r} \times \Omega_{r} \times \Omega_{r}}\|f(t, u, \phi u, \psi u)\|=f_{\max }<\infty$. We have

$$
\begin{aligned}
\left\|\left(T_{1} u\right)\left(t_{2}\right)-\left(T_{1} u\right)\left(t_{1}\right)\right\|= & \| \int_{0}^{t_{2}} \frac{\left(t_{2}-q s\right)^{(\alpha-1)}}{\Gamma_{q}(\alpha)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s \\
& -\int_{0}^{t_{1}} \frac{\left(t_{1}-q s\right)^{(\alpha-1)}}{\Gamma_{q}(\alpha)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s \| \\
= & \| \int_{0}^{t_{1}} \frac{\left(t_{2}-q s\right)^{(\alpha-1)}-\left(t_{1}-q s\right)^{(\alpha-1)}}{\Gamma_{q}(\alpha)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s \\
& +\int_{t_{1}}^{t_{2}} \frac{\left(t_{2}-q s\right)^{(\alpha-1)}}{\Gamma_{q}(\alpha)} f(s, u(s),(\phi u)(s),(\psi u)(s)) d_{q} s \| \\
\leq & \frac{f_{\max }}{\Gamma_{q}(\alpha+1)}\left|t_{1}^{(\alpha)}-t_{2}^{(\alpha)}\right|
\end{aligned}
$$

which is independent of $u \in \Omega_{r}$ when $t_{1} \rightarrow t_{2}$. Indeed, let $u \in \Omega_{r}$, we have

$$
\lim _{t_{1} \rightarrow t_{2}} \frac{f_{\max }}{\Gamma_{q}(\alpha+1)}\left|t_{1}^{(\alpha)}-t_{2}^{(\alpha)}\right| \rightarrow 0
$$

Therefore, $T_{1}\left(\Omega_{r}\right)$ is relatively compact on $\Omega_{r}$. Hence, by Arzela-Ascoli's Theorem, $T_{1}$ is compact on $\Omega_{r}$. Thus all the assumptions of Theorem 3.2 are satisfied and the conclusion of Theorem 3.2 implies that the boundary value problem (1.1) has at least one solution on $[0,1]$.

## 4 Examples

Example 4.1. Consider the following boundary value problem

$$
\left\{\begin{array}{l}
{ }_{C} D_{0.5}^{1.5} u(t)=\frac{t}{8} \frac{|u|}{1+|u|}+\frac{1}{5} \int_{0}^{t} \frac{e^{-(s-t)}}{5} u(s) d s+\frac{1}{5} \int_{0}^{t} \frac{e^{-\frac{s-t}{2}}}{5} u(s) d s, t \in[0,1]  \tag{4.1}\\
u(0)=0, D_{0.5} u(1)=b_{1} D_{0.5} u\left(\xi_{1}\right)
\end{array}\right.
$$

Here, $\gamma(t, s)=\frac{e^{-(s-t)}}{5}, \delta(t, s)=\frac{e^{-\frac{s-t}{2}}}{5}, G=\frac{1}{10}, b_{1}=\frac{1}{10}, \xi=\frac{1}{2}$. With

$$
\begin{aligned}
& \gamma_{0}=\frac{e-1}{5}, \quad \delta_{0}=\frac{2(\sqrt{e}-1)}{5} \\
& \sup _{t \in[0,1]} I_{0.5}^{1.5} L(t) \approx 0.167983, \quad I_{0.5}^{0.5} L(1) \approx 0.217185, \quad I_{0.5}^{0.5} L(1 / 2) \approx 0.141421
\end{aligned}
$$

we find that

$$
\wedge=\frac{1}{10}+\left(1+\frac{e-1}{5}+\frac{2(\sqrt{e}-1)}{5}\right)\left[0.167983+\frac{1}{1-1 / 10}(0.217185+0.1 \times 0.141421)\right] \approx 0.781358<1
$$

Thus, by Theorem 3.1, the boundary value problem (4.1) has a unique solution on $[0,1]$.
EJQTDE, 2011 No. 92, p. 9

## References

[1] I. Podlubny, Fractional Differential Equations, Academic Press, San Diego, CA, 1999.
[2] K.S. Miller, B. Ross, An Introduction to the Fractional Calculus and Differential Equations, Wiley, New York, 1993.
[3] A.A. Kilbas, H.M. Srivastava, J.J. Trujillo, Theory and applications of fractional differential equations, NorthHolland Mathematical Studies, vol.204, Elsevier Science B.V., Amsterdam, 2006.
[4] V. Lakshmikantham, S. Leela, J. Vasundhara Devi, Theory of Fractional Dynamic systems, Cambridge Academic Publishers, Cambridge, 2009.
[5] Z. Bai, H. Lü, Positive solutions for boundary value problem of nonlinear fractional differential equation, J. Math. Anal. Appl. 311(2)(2005)495-505.
[6] K. Balachandran, J.J. Trujillo, The nonlocal Cauchy problem for nonlinear fractional integrodifferential equations in Banach spaces, Nonlinear Anal. 72(2010)4587-4593.
[7] K. Balachandran, S. Kiruthika, J.J. Trujillo, Existence results for fractional impulsive integrodifferential equations in Banach spaces, Commun. Nolinear Sci. Numer. Simulat. 16(2011)1970-1977.
[8] W.A. Al-Salam, Some fractional q-integrals and q-derivatives, Proc. Edinb. Math. Soc. (2) 15(1966-1967)135140.
[9] R.P. Agarwal, Certain fractional q-integrals and q-derivatives, Proc. Cambridge Philos. Soc. 66(1969)365-370.
[10] F.M. Atici, P.W. Eloe, Fractional q-calculus on a time scale, J. Nonlinear Math. Phys. 14(3)(2007)333-344.
[11] P.M. Rajkovic, S.D. Marinkovic, M.S. Stankovic, Fractional integrals and derivatives in q-calculus, Appl. Anal. Discrete Math. 1(1)(2007)311-323.
[12] R.A.C. Ferreira, Nontrivial solutions for fractional q-difference boundary value problems, Electron. J. Qual. Theory Differ. Equ. 2010, no.70, 1-10.
[13] R.A.C. Ferreira, Positive solutions for a class of boundary value problems with fractional q-differences, Comput. Math. Appl. 61(2011)367-373.
[14] V. Kac and P. Cheung, Quantum Calculus, Springer-Verlag, New York, 2002.
[15] M. El-Shahed, Farah M. Al-Askar, Positive solutions for boundary value problem of nonlinear fractional qdifference equation, ISRN Mathematical Analysis, vol. 2011, Article ID 385459, 12 pages, 2011. doi:10.5402/2011/385459.
[16] M. S. Stankovic, P. M. Rajkovic, S. D. Marinkovic, On q-fractional derivatives of Riemann-Liouville and Caputo type, arXiv:0909.0387 [math.CA] 2 sept. 2009.
[17] H. Gauchman, Integral Inequalities in q-Calculus, Comput. Math. Appl. 47(2004),no. 2-3, 281-300.
[18] V. Gafiychuk, B. Datsko, V. Meleshko, Mathematical modeling of different types of instabilities in time fractional reaction-diffusion systems, Comput. Math. Appl. 59(2010)1101-1107.
[19] B. Ahmad, J.J. Nieto, Existence results for a coupled system of nonlinear fractional differential equations with three-point boundary conditions, Comput. Math. Appl. 58(2009)1838-1843.
[20] B. Ahmad, S.K. Ntouyas, Boundary value problems for q-difference inclusions, Abstract and Applied Analysis, Volume 2011(2011), Article ID 292860,15 pages.
[21] B. Ahmad, S. Sivasundaram, On four-point nonlocal boundary value problems of nonlinear integro-differential equations of fractional order, Appl. Math. Comput. 217(2010)480-487.
(Received September 7, 2011)


[^0]:    $\star$ This work is supported by the NNSF of China (No. 60604004), the Special Projects in Mathematics Funded by NSF of Hebei Province (No. 07M005), the Scientific and Technological Support Project of Qinhuangdao (No. 201001A037).

    * Corresponding author.

    E-mail address: majunchi2009@163.com

