# Infinite memory effects on the stabilization of a biharmonic Schrödinger equation 

Roberto A. Capistrano-Filho ${ }^{1}$, Isadora Maria de Jesus ${ }^{1,2}$ and Victor Hugo Gonzalez Martinez ${ }^{\boxtimes 1}$<br>${ }^{1}$ Departamento de Matemática, Universidade Federal de Pernambuco (UFPE), 50740-545, Recife (PE), Brazil<br>${ }^{2}$ Instituto de Matemática, Universidade Federal de Alagoas (UFAL), Maceió (AL), Brazil

Received 2 May 2023, appeared 21 August 2023
Communicated by Vilmos Komornik


#### Abstract

This paper deals with the stabilization of the linear biharmonic Schrödinger equation in an $n$-dimensional open bounded domain under Dirichlet-Neumann boundary conditions considering three infinite memory terms as damping mechanisms. We show that depending on the smoothness of initial data and the arbitrary growth at infinity of the kernel function, this class of solution goes to zero with a polynomial decay rate like $t^{-n}$ depending on assumptions about the kernel function associated with the infinite memory terms.


Keywords: Biharmonic Schrödinger equation, well-posedness, infinite memory, stabilization.

2020 Mathematics Subject Classification: 35B40, 35B45.

## 1 Introduction

### 1.1 Problem setting

The fourth-order nonlinear Schrödinger equation (4NLS) or biharmonic cubic nonlinear Schrödinger equation

$$
\begin{equation*}
i \partial_{t} y+\Delta y-\Delta^{2} y=\lambda|y|^{2} y \tag{1.1}
\end{equation*}
$$

has been introduced by Karpman [12] and Karpman and Shagalov [13] to take into account the role of small fourth-order dispersion terms in the propagation of intense laser beams in a bulk medium with Kerr nonlinearity. Equation (1.1) arises in many scientific fields such as quantum mechanics, nonlinear optics, and plasma physics, and has been intensively studied with fruitful references (see $[2,12,16]$ and references therein).

Over the past twenty years, equation (1.1) has been deeply studied from a different mathematical viewpoint, including linear settings which can be written generically as

$$
\begin{equation*}
i \partial_{t} y+\alpha \Delta y-\beta \Delta^{2} y=f \tag{1.2}
\end{equation*}
$$

[^0]with $\alpha, \beta \geq 0$ and different types of boundary conditions. For example, considering the problem (1.2) several authors treated this equation, see, for instance, $[1,10,17,19,20,22]$ and the references therein. Inspired by these results for the linear problem associated with the 4NLS, a mathematical viewpoint problem is to study the well-posedness and stabilization for solutions of the system (1.2) in an appropriate framework.

So, consider the equation (1.2) when $\alpha=\beta=1$ in a $n$-dimensional open bounded subset of $\mathbb{R}^{n}$. Our goal is to consider an initial boundary value problem (IBVP) associated with (1.2) when the source term $f$ is viewed as an infinite memory term:

$$
f=-(-1)^{j} i \int_{0}^{\infty} f(s) \Delta^{j} y(x, t-s) d s
$$

Thus, the goal of this manuscript is to deal with the following system

$$
\begin{cases}i \partial_{t} y(x, t)+\Delta y(x, t)-\Delta^{2} y(x, t)+(-1)^{j} i \int_{0}^{\infty} f(s) \Delta^{j} y(x, t-s) d s=0, & (x, t) \in \Omega \times \mathbb{R}_{+},  \tag{1.3}\\ y(x, t)=\nabla y(x, t)=0, & (x, t) \in \Gamma \times \mathbb{R}_{+}^{*} \\ y(x,-t)=y_{0}(x, t), & (x, t) \in \Omega \times \mathbb{R}_{+},\end{cases}
$$

where $j \in\{0,1,2\}, \Omega \subset \mathbb{R}^{n}$ is a $n$-dimensional open bounded domain with a smooth boundary $\Gamma$, and $f: \mathbb{R}_{+}:=[0, \infty) \rightarrow \mathbb{R}$ is the kernel (or relaxation) function. We point out that for each $j$ the memory term present in (1.3) is modified.

In (1.3), the memory kernel $f$ satisfies the following assumptions:
Assumption 1. Consider $f \in C^{2}\left(\mathbb{R}_{+}\right)$. For some positive constant $c_{0}$, we have the following conditions

$$
\begin{equation*}
f^{\prime}<0, \quad 0 \leq f^{\prime \prime} \leq-c_{0} f^{\prime}, \quad f(0)>0 \quad \text { and } \quad \lim _{s \rightarrow \infty} f(s)=0 . \tag{1.4}
\end{equation*}
$$

Under the Assumption 1, let us introduce the following energy functionals associated with the solutions of (1.3)

$$
\begin{equation*}
E_{j}(t)=\frac{1}{2}\left(\|y\|^{2}+\int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta^{t}\right\|^{2} d s\right) \tag{1.5}
\end{equation*}
$$

with $j \in\{0,1,2\}$ and $g=-f^{\prime}$, so $g \in C^{1}\left(\mathbb{R}_{+}\right), g$ is non-negative and

$$
g_{0}:=\int_{0}^{\infty} g(s) d s=f(0) \in \mathbb{R}_{+}^{*} .
$$

It is worth mentioning that the abuse of notation $\Delta^{\frac{j}{2}}$ in (1.5) means the identity operator for $j=0$, the $\nabla$ operator for $j=1$ and the Laplacian operator for $j=2$.

Therefore, taking into account the action of the infinite memory term in (1.3), the following issue will be addressed in this article:

Problem 1.1. Does $E(t) \longrightarrow 0$, as $t \rightarrow \infty$ ? If so, can we provide a decay rate?
It should be noted that the answer to the above question is crucial in the understanding of the behavior of the solutions to the fourth-order Schrödinger system when it is subject to an infinite memory term. In other words:

Problem 1.2. Are the solutions to our problem stable despite the action of the memory term? If yes, then how robust is the stabilization property of the solutions?

### 1.2 Historical background

Distributed systems with memory have a long history and have been first introduced in viscoelasticity by Maxwell, Boltzmann, and Volterra [3,4,15,18]. In the context of heat processes with finite dimension speed, these systems have been introduced by Cattaneo [7] (a previous work of Maxwell had been forgotten).

In our context, to our knowledge, there is no result considering the system (1.3) in $n-$ dimensional case. However, considering the fourth-order Schrödinger system

$$
\begin{equation*}
i \partial_{t} u+\Delta^{2} u=0 \tag{1.6}
\end{equation*}
$$

there are interesting results in the sense of control problems in a bounded domain of $\mathbb{R}$ or $\mathbb{R}^{n}$ and, more recently, on a periodic domain $\mathbb{T}$ and manifolds, which we will summarize below.

The first result about the exact controllability of the linearized fourth order Schrödinger equation (1.6) on a bounded domain $\Omega$ of $\mathbb{R}^{n}$ is due to Zheng and Zhou in [21]. In this work, using an $L^{2}$-Neumann boundary control, the authors proved that the solution is exactly controllable in $H^{s}(\Omega)$, $s=-2$, for an arbitrarily small time. They used Hilbert Uniqueness Method (HUM) (see, for instance, $[9,14]$ ) combined with the multiplier techniques to get the main result of the article. More recently, in [22], Zheng proved a global Carleman estimate for the fourth-order Schrödinger equation posed on a finite domain. The Carleman estimate is used to prove the Lipschitz stability for an inverse problem associated with the fourth-order Schrödinger system.

Still, on control theory Wen et al. in two works [19,20], studied well-posedness and control problems related to the equation (1.6) on a bounded domain of $\mathbb{R}^{n}$, for $n \geq 2$. In [19], they considered the Neumann boundary controllability with collocated observation. With this result in hand, the stabilization of the closed-loop system under proportional output feedback control holds. Recently, the same authors, in [20], gave positive answers when considering the equation with hinged boundary by either moment or Dirichlet boundary control and collocated observation, respectively.

To get a general outline of the control theory already done for the system (1.6), two interesting problems were studied recently by Aksas and Rebiai [1] and Gao [10]: Uniform stabilization and stochastic control problem, in a smooth bounded domain $\Omega$ of $\mathbb{R}^{n}$ and on the interval $I=(0,1)$ of $\mathbb{R}$, respectively. In the first work, by introducing suitable dissipative boundary conditions, the authors proved that the solution decays exponentially in $L^{2}(\Omega)$ when the damping term is effective on a neighborhood of a part of the boundary. The results are established by using multiplier techniques and compactness/uniqueness arguments. Regarding the second work, the author showed Carleman estimates for forward and backward stochastic fourth order Schrödinger equations which provided the proof of the observability inequality, unique continuation property, and, consequently, the exact controllability for the forward and backward stochastic system associated with (1.6).

Recently, the first author [5] showed the global stabilization and exact controllability properties of the 4NLS

$$
\begin{cases}i \partial_{t} u+\partial_{x}^{2} u-\partial_{x}^{4} u=\lambda|u|^{2} u+f(x, t), & (x, t) \in \mathbb{T} \times \mathbb{R},  \tag{1.7}\\ u(x, 0)=u_{0}(x), & x \in \mathbb{T},\end{cases}
$$

on a periodic domain $\mathbb{T}$ with internal control supported on an arbitrary sub-domain of $\mathbb{T}$. More precisely, by certain properties of propagation of compactness and regularity in

Bourgain spaces, for the solution of the associated linear system, the authors proved that system (1.7) is globally exponentially stabilizable, considering $f(x, t)=-i a^{2}(x) u$. This property together with the local exact controllability ensures that 4NLS is globally exactly controllable on $\mathbb{T}$.

Lastly, the first author showed in [6] the global controllability and stabilization properties for the fractional Schrödinger equation on $d$-dimensional compact Riemannian manifolds without boundary $(M, g)$,

$$
\begin{cases}i \partial_{t} u+\Lambda_{g}^{\sigma} u+P^{\prime}\left(|u|^{2}\right) u-a(x)\left(1-\Delta_{g}\right)^{-\frac{\sigma}{2}} a(x) \partial_{t} u=0, & \text { on } M \times \mathbb{R}_{+},  \tag{1.8}\\ u(x, 0)=u_{0}(x), & x \in M .\end{cases}
$$

Under the suitable assumption of the damping term $a(x)$ they proved their result using microlocal analysis, being precise, they can prove propagation of regularity which together with the so-called Geometric Control Condition and Unique Continuation Property, shows the main results of the article. Is important to mention that when $\sigma=4$ they have the equation (1.6).

### 1.3 Notations

Before presenting the main result let us give some notations and definitions. In what follows, the variables $x, t$, and $s$ will be suppressed, except when there is ambiguity and, throughout this article, $C$ will denote a constant that can be different from one step to the next in the proofs presented here. We will use the notations $\langle\cdot, \cdot\rangle$ and $\|\cdot\|$ to denote, respectively, the complex inner product in $L^{2}(\Omega)$ and its associated standard norm, namely

$$
\langle u, v\rangle=\operatorname{Re}\left(\int_{\Omega} u(x) \bar{v}(x) d x\right) \quad \text { and } \quad\|u\|=\left(\int_{\Omega}|u(x)|^{2} d x\right)^{\frac{1}{2}} .
$$

Now, consider the following approximation

$$
\eta^{t}(x, s)=\int_{t-s}^{t} y(x, \tau) d \tau \quad \text { and } \quad \eta^{0}(x, s)=\int_{0}^{s} y_{0}(x, \tau) d \tau, \quad x \in \Omega, s, t \in \mathbb{R}_{+}
$$

This approximation ensures that $\eta^{t}$ satisfies

$$
\begin{cases}\partial_{t} \eta^{t}(x, s)+\partial_{s} \eta^{t}(x, s)=y(x, t), & x \in \Omega, s, t \in \mathbb{R}_{+}  \tag{1.9}\\ \eta^{t}(x, s)=0, & x \in \Gamma, s, t \in \mathbb{R}_{+} \\ \eta^{t}(x, 0)=0, & x \in \Omega, t \in \mathbb{R}_{+}\end{cases}
$$

To express the memory integral in (1.3) in terms of $\eta^{t}$, we will denote $g:=-f^{\prime}$. Thus, according to (1.4), we have $g \in C^{1}\left(\mathbb{R}_{+}\right)$and

$$
\begin{equation*}
g>0, \quad 0 \leq-g^{\prime} \leq c_{0} g, \quad g_{0}=\int_{0}^{\infty} g(s) d s=f(0)>0 \tag{1.10}
\end{equation*}
$$

and

$$
\begin{equation*}
\lim _{s \rightarrow \infty} g(s)=0 . \tag{1.11}
\end{equation*}
$$

Now on, rewrite (1.3) into

$$
\begin{equation*}
i \partial_{t} y(x, t)+\Delta y(x, t)-\Delta^{2} y(x, t)+i(-1)^{j} \int_{0}^{\infty} g(s) \Delta^{j} \eta^{t}(x, s) d s=0 \tag{1.12}
\end{equation*}
$$

Define the following sets

$$
H_{j}= \begin{cases}L^{2}(\Omega), & \text { if } j=0, \\ H_{0}^{1}(\Omega), & \text { if } j=1, \\ H_{0}^{2}(\Omega), & \text { if } j=2,\end{cases}
$$

with natural inner product

$$
\langle v, w\rangle_{H_{j}}= \begin{cases}\langle v(s), w(s)\rangle, & \text { if } j=0, \\ \langle\nabla v(s), \nabla w(s)\rangle, & \text { if } j=1, \\ \langle\Delta v(s), \Delta w(s)\rangle, & \text { if } j=2\end{cases}
$$

and norm

$$
\|v\|_{H_{j}}= \begin{cases}\|v(s)\|, & \text { if } j=0 \\ \|\nabla v(s)\|, & \text { if } j=1 \\ \|\Delta v(s)\|, & \text { if } j=2\end{cases}
$$

respectively ${ }^{1}$. Consider

$$
U=\left(y, \eta^{t}\right)^{T} \quad \text { and } \quad U_{0}(x, s)=\left(y_{0}(x, 0), \eta^{0}(x, s)\right)^{T}
$$

where

$$
y \in L^{2}(\Omega) \quad \text { and } \quad \eta^{t} \in L_{j}
$$

with

$$
L_{j}=L_{g}^{2}\left(\mathbb{R}_{+} ; H_{j}\right):=\left\{v: \mathbb{R}_{+} \longrightarrow H_{j} ; \int_{0}^{\infty} g(s)\|v(s)\|_{H_{j}}^{2} d s<+\infty\right\} .
$$

Define the energy space as follows

$$
\mathcal{H}_{j}=L^{2}(\Omega) \times L_{j}, \quad j \in\{0,1,2\},
$$

with inner product and norm

$$
\left\langle\left(v_{1}, v_{2}\right),\left(w_{1}, w_{2}\right)\right\rangle_{\mathcal{H}_{j}}=\left\langle v_{1}, w_{1}\right\rangle+\left\langle v_{2}, w_{2}\right\rangle_{L_{j}}
$$

and

$$
\|(v(s), w(s))\|_{\mathcal{H}_{j}}=\left(\|v(s)\|^{2}+\|w(s)\|_{L_{j}}^{2}\right)^{\frac{1}{2}}
$$

respectively. Therefore, the systems (1.3) and (1.9) can be seen as the following initial value problem (IVP)

$$
\left\{\begin{array}{l}
\partial_{t} U(t)=\mathcal{A}_{j} U  \tag{1.13}\\
U(0)=U_{0} .
\end{array}\right.
$$

Here, the operator $\mathcal{A}_{j}$ is defined by

$$
\begin{equation*}
\mathcal{A}_{j}(U)=\binom{i \Delta y-i \Delta^{2} y+(-1)^{j+1} \int_{0}^{\infty} g(s) \Delta^{j} \eta^{t}(\cdot, s) d s}{y-\eta_{s}^{t}} \tag{1.14}
\end{equation*}
$$

with domain

$$
\begin{equation*}
D\left(\mathcal{A}_{j}\right)=\left\{U \in \mathcal{H}_{j} ; \mathcal{A}_{j}(U) \in \mathcal{H}_{j}, y \in H_{0}^{2}(\Omega), \eta^{t}(x, 0)=0\right\} . \tag{1.15}
\end{equation*}
$$

[^1]Remark 1.3. Observe that for the fourth-order Schrödinger equation, the natural domain to be considered is $H_{0}^{2}(\Omega) \cap H^{4}(\Omega)$. However, since we are working with a more general operator, namely operator defined in (1.14) and (1.15), we need to impose $\mathcal{A}_{j}(U) \in \mathcal{H}_{j}$. However, note that the inclusion below

$$
H_{0}^{2}(\Omega) \cap H^{4}(\Omega) \times\left\{\eta^{t} \in L_{j}:(-1)^{j+1} \int_{0}^{\infty} g(s) \Delta^{j} \eta^{t}(\cdot, s) d s \in L^{2}(\Omega), \eta^{t}(x, 0)=0\right\} \subset D\left(\mathcal{A}_{j}\right)
$$

is verified. So, the operator $\mathcal{A}_{j}(U)$ is well-defined.

### 1.4 Main result

As mentioned, some valuable efforts in the last years focus on the well-posedness and stabilization problem for the fourth-order Schrödinger system. So, in this article, we present a new way to ensure that, in some sense, the Problems 1.1 and 1.2 can be solved for the system (1.3) in $n$-dimensional case. To do that, we use the ideas contained in [11], so additionally to the Assumption 1 we have also assumed the memory kernel satisfying the following:

Assumption 2. Assume there is a positive constant $\alpha_{0}$ and a strictly convex increasing function $G: \mathbb{R}_{+} \longrightarrow \mathbb{R}_{+}$of class $C^{1}\left(\mathbb{R}_{+}\right) \cap C^{2}\left(\mathbb{R}_{+}^{*}\right)$ satisfying

$$
\begin{equation*}
G(0)=G^{\prime}(0)=0 \text { and } \lim _{t \rightarrow \infty} G^{\prime}(t)=\infty \tag{1.16}
\end{equation*}
$$

such that

$$
\begin{equation*}
g^{\prime} \leq-\alpha_{0} g \tag{1.17}
\end{equation*}
$$

or

$$
\begin{equation*}
\int_{0}^{\infty} \frac{s^{2} g(s)}{G^{-1}\left(-g^{\prime}(s)\right)} d s+\sup _{s \in \mathbb{R}^{+}} \frac{g(s)}{G^{-1}\left(-g^{\prime}(s)\right)}<\infty . \tag{1.18}
\end{equation*}
$$

Additionally, when (1.17) is not verified, we will assume that $y_{0}$ satisfies,

$$
\begin{equation*}
\sup _{t \in \mathbb{R}_{+}} \max _{k \in\{0, \ldots, n+1\}} \int_{t}^{\infty} \frac{g(s)}{G^{-1}\left(-g^{\prime}(s)\right)}\left\|\int_{0}^{s-t} \Delta^{\frac{j}{2}} \partial_{s}^{k} y_{0}(\cdot, \tau) d \tau\right\|^{2} d s<\infty . \tag{1.19}
\end{equation*}
$$

for $j \in\{0,1,2\}$.
The next theorem is the main result of the article.
Theorem 1.4. Assume (1.10) and that the Assumption 2 holds. Let $n \in \mathbb{N}^{*}, U_{0} \in D\left(\mathcal{A}_{j}^{2 n}\right)$ when $j=0$, and $U_{0} \in D\left(\mathcal{A}_{j}^{2 n+2}\right)$ when $j \in\{1,2\}$. Thus, there exists positive constants $\alpha_{j, n}$ such that the energy (1.5) associated with (1.13) satisfies

$$
\begin{equation*}
E_{j}(t) \leq \alpha_{j, n} G_{n}\left(\frac{\alpha_{j, n}}{t}\right), \quad t \in \mathbb{R}_{+}^{*}, j \in\{0,1,2\} . \tag{1.20}
\end{equation*}
$$

Here, $G_{n}$ is defined, recursively, as follows:

$$
\begin{equation*}
G_{m}(s)=G_{1}\left(s G_{m-1}(s)\right), \quad m=2,3, \ldots, n, G_{1}=G_{0}^{-1} \tag{1.21}
\end{equation*}
$$

where $G_{0}(s)=s$ if (1.17) is verified, and $G_{0}(s)=s G^{\prime}(s)$ if (1.18) holds.

Remark 1.5. Let us give some remarks about the Assumption 2.
i. Thanks to the relation (1.18), we have that (1.19) is valid, for example, if

$$
\left\|\Delta^{\frac{j}{2}} \partial_{s}^{k} y_{0}\right\|^{2}, \quad k=0,1, \ldots, n+1,
$$

is bounded with respect to $s$.
ii. There are many class of function $g$ satisfying (1.10), (1.11), (1.16), (1.17), (1.18), and (1.19). For example, those that converge exponentially to zero as

$$
\begin{equation*}
g_{1}(s):=d_{1} e^{-q_{1} s} \tag{1.22}
\end{equation*}
$$

or those that converge at a slower rate, like

$$
\begin{equation*}
g_{2}(s):=d_{2}(1+s)^{-q_{2}} \tag{1.23}
\end{equation*}
$$

with $d_{1}, q_{1}, d_{2}>0$, and $q_{2}>3$. Additionally, we point out that conditions (1.10) and (1.17) are satisfied for $g_{1}$ defined by (1.22) with $c_{0}=\alpha_{0}=q_{1}$, since

$$
g_{1}^{\prime}(s)=-q_{1} d_{1} e^{-q_{1} s}=-q_{1} g_{1}(s)
$$

However, the conditions (1.10) and (1.18) are satisfied for $g_{2}$ given by (1.23) with $c_{0}=q_{2}$ and $G(s)=s^{p}$, for $p>\frac{q_{2}+1}{q_{2}-3}$.
Remark 1.6. Now, we will present the following remarks related to the main result of the article.
i. When (1.17) is verified, note that $G_{n}(0)=0$, so (1.20) implies

$$
\begin{equation*}
\lim _{t \rightarrow \infty} E_{j}(t) \leq \alpha_{j, 1} G_{1}\left(\frac{\alpha_{j, 1}}{t}\right)=0 \tag{1.24}
\end{equation*}
$$

Since we have that $D\left(\mathcal{A}_{j}^{2}\right)$ is dense in $\mathcal{H}_{j}$, when $j=0$, and $D\left(\mathcal{A}_{j}^{4}\right)$ is dense in $\mathcal{H}_{j}$ when $j=1,2$ (see Lemma A. 1 in A), we have that (1.24) is valid for any $U_{0} \in \mathcal{H}$. Therefore, in this case, (1.21) gives $G_{n}(s)=s^{n}$ and from (1.20) we get

$$
\begin{equation*}
E_{j}(t) \leq \alpha_{j, n}\left(\frac{\alpha_{j, n}}{t}\right)^{n}=\frac{\left(\alpha_{j, n}\right)^{n+1}}{t^{n}}=\beta_{j, n} t^{-n}, \tag{1.25}
\end{equation*}
$$

showing that the energy (1.5) associated with the solutions of the system (1.13) have a polynomial decay rate.
ii. Given (1.18) verified, the relation of (1.20) is weaker than the previous case. For example, when $g=g_{2}$ defined by (1.23), we see that $G(s)=s^{p}$ with $p>\frac{q_{2}+1}{q_{2}-3}$ satisfies the Assumption 2. Moreover,

$$
\begin{gathered}
G_{0}(s)=s G^{\prime}(s)=p s^{p}, G_{1}(s)=\sqrt[p]{\frac{s}{p}}, \\
G_{2}(s)=G_{1}\left(s G_{1}(s)\right)=\sqrt[p]{\frac{s \sqrt[p]{\frac{s}{p}}}{p}}=\left(\frac{s}{p}\right)^{\frac{1}{p}+\frac{1}{p^{2}}},
\end{gathered}
$$

$$
G_{3}(s)=G_{1}\left(s G_{2}(s)\right)=\sqrt[p]{\frac{s}{p}\left(\frac{s}{p}\right)^{\frac{1}{p}+\frac{1}{p^{2}}}}=\left(\frac{s}{p}\right)^{\frac{1}{p}+\frac{1}{p^{2}}+\frac{1}{p^{3}}}
$$

and so,

$$
G_{n}(s)=\left(\frac{s}{p}\right)^{\frac{1}{p}+\frac{1}{p^{2}}+\cdots+\frac{1}{p^{n}}}=\left(\frac{s}{p}\right)^{p_{n}},
$$

where $p_{n}=\sum_{m=1}^{n} p^{-m}=\frac{1}{p}+\frac{1}{p^{2}}+\cdots+\frac{1}{p^{n}}$. Therefore, the energy (1.5) associated with the solutions of the system (1.13) satisfies

$$
E_{j}(t) \leq \alpha_{j, n}\left(\frac{1}{p} \frac{\alpha_{j, n}}{t}\right)^{p_{n}}=\beta_{j, n} t^{-p_{n}}
$$

with $\beta_{j, n}=\alpha_{j, n}\left(\frac{\alpha_{j, n}}{p}\right)^{p_{n}}>0$, showing that the decay rate of (1.20) is arbitrarily near of $t^{-n}$, when $p \rightarrow 1$, that is, $p_{n} \rightarrow n$ when $q_{2} \rightarrow \infty$.

### 1.5 Novelty and structure of the work

Among the main novelties introduced in this article, we give an affirmative answer to the Problems 1.1 and 1.2, providing a further step toward a better understanding of the stabilization problem for the linear system associated with (1.1) in the $n$-dimensional case. Here, we have used the multipliers method and some arguments devised in [11].

Since we are working with a mixed dispersion we can consider three different memory kernels acting as damping control to stabilize equation (1.3) in contrast to [5], for example, where interior damping is required and no memory is taken into consideration, in a onedimensional case. Moreover, if we also compare with the linear Schrödinger equation (see e.g. [8]) we have more kernels acting to decay the solution of the equation (1.3) since we have more regularity with the mixed dispersion, which is a gain due the bi-Laplacian operator.

In addition to this, recently, using another approach, the authors in [6] showed that the system (1.8) is stable, however considering a damping mechanism and some important assumptions such as the Geometric Control Condition (GCC) and Unique Continuation Property (UCP). Here, we are not able to prove that the solutions decay exponentially, however, with the approach of this article, the (GCC) and (UCP) are not required. The drawback is that we only provide that the energy of the system (1.3), with memory terms, decays in some sense as explained in the Remark 1.6.

A natural issue is how to deal with the 4 NLS system given in (1.1). The main point is that we are not able to use Strichartz estimates or Bourgain spaces to obtain more regularity for the solution of the problem with memory terms, therefore, Theorem 1.4 for the system (1.1) with memory terms remains open.

Now, let us present the outline of our paper. In Section 2 we prove a series of lemmas that are paramount to prove the main result of the article. With the previous section in hand, Theorem 1.4 is shown in Section 3. Finally, for the sake of completeness, in Appendix A, we present the existence of a solution for the system (1.13) in the energy space $\mathcal{H}_{j}$.

## 2 Auxiliary results

In this section, we will give some auxiliary lemmas that help us to prove the main result of the article. In this way, the first result shows identities for the derivatives of $E_{j}$ given by (1.5).

Lemma 2.1. Suppose the Assumption 1. Then, the energy functional satisfies

$$
\begin{equation*}
E_{j}^{\prime}(t)=\frac{1}{2} \int_{0}^{\infty} g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \eta^{t}\right\|^{2} d s, \quad j \in\{0,1,2\} . \tag{2.1}
\end{equation*}
$$

Proof. Observe that (2.1) is a direct consequence of (A.3), and the result follows.
Next, we will give a $H^{1}$-estimate for the solution of (1.12).
Lemma 2.2. There exist positive constants $c_{k, j}, j \in\{0,1,2\}$ and $k \in\{1,2\}$ such that the following inequality

$$
\begin{equation*}
\|\nabla y\|^{2} \leq c_{1, j}\left\|\eta^{t}\right\|_{L_{j}}^{2}+c_{2, j} \int_{\Omega}\left[\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Im}\left(y_{t}\right) \operatorname{Re}(y)\right] d x \tag{2.2}
\end{equation*}
$$

holds.
Proof. We use the multipliers method to prove (2.2). First, multiplying the equation (1.12) by $\bar{y}$, integrating over $\Omega$ and taking the real part we get

$$
\begin{equation*}
-\operatorname{Im}\left(\int_{\Omega} y_{t} \bar{y} d x\right)-\|\nabla y\|^{2}-\|\Delta y\|^{2}+\operatorname{Re}\left((-1)^{j} i \int_{0}^{\infty} g(s) \int_{\Omega} \Delta^{j} \eta^{t} \bar{y} d x d s\right)=0 \tag{2.3}
\end{equation*}
$$

taking into account the boundary conditions in (1.3) and (1.9), for $y(t, \cdot) \in H_{0}^{2}(\Omega)$, for all $t \in \mathbb{R}^{+}$.

Note that the last term of the left-hand side of (2.3) can be bounded using the generalized Young's inequality giving

$$
\begin{align*}
\left|(-1)^{j} i \int_{0}^{\infty} g(s) \int_{\Omega} \Delta^{j} \eta^{t} \bar{y} d x d s\right| & =\left|i\left\langle\eta^{t}, y\right\rangle_{L_{j}}\right| \leq\left\|\eta^{t}\right\|_{L_{j}}\|y\|_{L_{j}} \leq \epsilon\|y\|_{L_{j}}^{2}+C(\epsilon)\left\|\eta^{t}\right\|_{L_{j}}^{2} \\
& =\underbrace{g_{1} \epsilon}_{=: \delta}\left\|\Delta^{\frac{j}{2}} y\right\|^{2}+C(\epsilon)\left\|\eta^{t}\right\|_{L_{j}}^{2}=\delta\left\|\Delta^{\frac{j}{2}} y\right\|^{2}+C(\delta)\left\|\eta^{t}\right\|_{L_{j^{\prime}}}^{2} \tag{2.4}
\end{align*}
$$

for any $\delta>0$. In addition to that, the first term of the left-hand side of (2.3) can be viewed as

$$
\begin{equation*}
\operatorname{Im}\left(\int_{\Omega} y_{t} \bar{y} d x\right)=\int_{\Omega}\left(\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)-\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)\right) d x \tag{2.5}
\end{equation*}
$$

So, replacing (2.4) and (2.5) in (2.3), yields

$$
\begin{align*}
\|\nabla y\|^{2} & \leq \int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x-\|\Delta y\|^{2}+\delta\left\|\Delta^{\frac{j}{2}} y\right\|^{2}+C(\delta)\left\|\eta^{t}\right\|_{L_{j}}^{2}  \tag{2.6}\\
& \leq \int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x+\delta\left\|\Delta^{\frac{j}{2}} y\right\|^{2}+C(\delta)\left\|\eta^{t}\right\|_{L_{j}}^{2}
\end{align*}
$$

We now split the remainder of the proof into three cases.
Case 1. $j=0$
Poincaré's inequality in (2.6) gives

$$
\begin{equation*}
\|\nabla y\|^{2} \leq \int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x+\delta c_{*}\|\nabla y\|^{2}+C(\delta)\left\|\eta^{t}\right\|_{L_{j}}^{2} \tag{2.7}
\end{equation*}
$$

Picking $\delta=\frac{1}{2 c_{*}}>0$ in (2.7) yields

$$
\frac{1}{2}\|\nabla y\|^{2} \leq \int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x+C(\delta)\left\|\eta^{t}\right\|_{L_{j^{\prime}}}^{2}
$$

showing (2.2) with $c_{1,0}=2 C(\delta)$ and $c_{2,0}=2$.
Case 2. $j=1$
In this case (2.6) is giving by

$$
\|\nabla y\|^{2} \leq \int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x+\delta\|\nabla y\|^{2}+C(\delta)\left\|\eta^{t}\right\|_{L_{j}}^{2}
$$

and taking $\delta=\frac{1}{2}>0$, the inequality (2.2) holds with $c_{1,1}=2 C(\delta)$ and $c_{2,1}=2$.
Case 3. $j=2$
Finally, just take any $\delta>0$ such that $\delta<1$. Therefore, using (2.6) we get (2.2) for $c_{1,2}=C(\delta)$ and $c_{2,2}=1$, achieving the result.

We need now define the following higher-order energy functionals

$$
\begin{equation*}
E_{j, k}(t)=\frac{1}{2}\left\|\partial_{t}^{k} U\right\|_{\mathcal{H}_{j}}^{2}, \tag{2.8}
\end{equation*}
$$

for $U_{0} \in D\left(\mathcal{A}_{j}^{2 n+2}\right)$ in the case when $j=1,2$, and $U_{0} \in D\left(\mathcal{A}_{0}^{2 n}\right)$ with $n \in \mathbb{N}^{*}$. This is possible thanks to the Theorem A. 2 in A that guarantees $U \in C^{k}\left(\mathbb{R}_{+} ; D\left(\mathcal{A}_{j}^{4-k}\right)\right)$ for $k \in\{1,2,3,4\}$ when $j \in\{1,2\}$, and that $U \in C^{k}\left(\mathbb{R}_{+} ; D\left(\mathcal{A}_{j}^{2-k}\right)\right)$ for $k \in\{1,2\}$ when $j=0$. In addition to that, the linearity of the operator $\mathcal{A}_{j}$ together with (2.1) gives

$$
\begin{equation*}
E_{j, k}^{\prime}(t)=\frac{1}{2} \int_{0}^{\infty} g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s . \tag{2.9}
\end{equation*}
$$

With this in hand, let us control the last term of the right-hand side of (2.2) in terms of the $E_{j, 1}^{\prime}$ and the $L_{j}$-norms of the $\Delta^{\frac{j}{2}} \eta_{t t}^{t}$.

Lemma 2.3. The following estimate is valid

$$
\begin{equation*}
\int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x \leq \epsilon\|\nabla y\|^{2}+c_{\epsilon} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta_{t t}^{t}\right\|^{2} d s-c_{\epsilon} E_{j, 1}^{\prime}(t) \tag{2.10}
\end{equation*}
$$

for any $\epsilon>0$.
Proof. Differentiating (1.9) with respect to $t$, multiplying the result by $g(s)$, and integrating on $[0, \infty)$ we have

$$
y_{t}=\frac{1}{g_{0}} \int_{0}^{\infty} g(s)\left(\eta_{t t}^{t}(s, x)+\eta_{s t}^{t}(s, x)\right) d s,
$$

taking into account the third relation in (1.10). So, we get

$$
\begin{align*}
\mathcal{I}:= & \int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x \\
= & \int_{\Omega} \operatorname{Re}\left(\frac{1}{g_{0}} \int_{0}^{\infty} g(s)\left(\eta_{t t}^{t}+\eta_{s t}^{t}\right) d s\right) \operatorname{Im}(y) d x  \tag{2.11}\\
& -\int_{\Omega} \operatorname{Re}(y) \operatorname{Im}\left(\frac{1}{g_{0}} \int_{0}^{\infty} g(s)\left(\eta_{t t}^{t}+\eta_{s t}^{t}\right) d s\right) d x
\end{align*}
$$

Now, let us bound the right-hand side of (2.11). To do that, reorganize the terms of the (RHS) and note that

$$
\begin{align*}
(R H S)= & \frac{1}{g_{0}} \int_{0}^{\infty} g(s) \int_{\Omega}\left(\operatorname{Re}\left(\eta_{t t}^{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(\eta_{t t}^{t}\right)\right) d x d s \\
& +\frac{1}{g_{0}} \int_{0}^{\infty}\left(-g^{\prime}(s)\right) \int_{\Omega}\left(\operatorname{Re}\left(\eta_{t}^{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(\eta_{t}^{t}\right)\right) d x d s \\
\leq & \frac{1}{g_{0}} \int_{0}^{\infty} g(s) \int_{\Omega}\left|y\left\|\eta_{t t}^{t}\left|d x d s+\frac{1}{g_{0}} \int_{0}^{\infty}\left(-g^{\prime}(s)\right) \int_{\Omega}\right| y\right\| \eta_{t}^{t}\right| d x d s  \tag{2.12}\\
\leq & \frac{1}{g_{0}} \int_{0}^{\infty} g(s)\|y\|\left\|\eta_{t t}^{t}\right\| d s+\frac{1}{g_{0}} \int_{0}^{\infty}\left(-g^{\prime}(s)\right)\|y\|\left\|\eta_{t}^{t}\right\| d s .
\end{align*}
$$

The generalized Young inequality gives for any $\delta>0$ that

$$
\|y\|\left\|\eta_{t}^{t}\right\| \leq \delta\|y\|^{2}+C_{\delta}\left\|\eta_{t}^{t}\right\|^{2}
$$

and

$$
\|y\|\left\|\eta_{t t}^{t}\right\| \leq \delta\|y\|^{2}+C_{\delta}\left\|\eta_{t t}^{t}\right\|^{2}
$$

Substituting both inequalities into (2.12) yields

$$
\begin{align*}
(R H S) \leq & \delta \frac{1}{g_{0}} \int_{0}^{\infty} g(s)\|y\|^{2} d s+C_{\delta} \frac{1}{g_{0}} \int_{0}^{\infty} g(s)\left\|\eta_{t t}^{t}\right\|^{2} d s \\
& +\delta \frac{1}{g_{0}} \int_{0}^{\infty}\left(-g^{\prime}(s)\right)\|y\|^{2} d s+C_{\delta} \frac{1}{g_{0}} \int_{0}^{\infty}\left(-g^{\prime}(s)\right)\left\|\eta_{t}^{t}\right\|^{2} d s \tag{2.13}
\end{align*}
$$

Now replacing (2.13) into (2.11) we have

$$
\begin{align*}
\mathcal{I} \leq & \delta \frac{1}{g_{0}} \int_{0}^{\infty} g(s)\|y\|^{2} d s+C_{\delta} \frac{1}{g_{0}} \int_{0}^{\infty} g(s)\left\|\eta_{t t}^{t}\right\|^{2} d s \\
& +\delta \frac{1}{g_{0}} \int_{0}^{\infty}\left(-g^{\prime}(s)\right)\|y\|^{2} d s+C_{\delta} \frac{1}{g_{0}} \int_{0}^{\infty}\left(-g^{\prime}(s)\right)\left\|\eta_{t}^{t}\right\|^{2} d s \\
= & \delta\left(1+\frac{1}{g_{0}}\left(\int_{0}^{\infty}\left(-g^{\prime}(s)\right) d s\right)\right)\|y\|^{2}+C_{\delta} \frac{1}{g_{0}} \int_{0}^{\infty} g(s)\left\|\eta_{t t}^{t}\right\|^{2} d s \\
& +C_{\delta} \frac{1}{g_{0}} \int_{0}^{\infty}\left(-g^{\prime}(s)\right)\left\|\eta_{t}^{t}\right\|^{2} d s  \tag{2.14}\\
\leq & c_{*} \delta\left(1+\frac{1}{g_{0}}\left(\int_{0}^{\infty}\left(-g^{\prime}(s)\right) d s\right)\right)\|\nabla y\|^{2}+c_{* *} C_{\delta} \frac{1}{g_{0}} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta_{t t}^{t}\right\|^{2} d s \\
& +c_{* *} C_{\delta} \frac{1}{g_{0}} \int_{0}^{\infty}\left(-g^{\prime}(s)\right)\left\|\Delta^{\frac{j}{2}} \eta_{t}^{t}\right\|^{2} d s
\end{align*}
$$

thanks to Poincaré inequality. Here,

$$
c_{* *}= \begin{cases}1, & \text { if } j=0  \tag{2.15}\\ c_{* \prime}, & \text { if } j=1 \\ c_{*,}^{2} & \text { if } j=2\end{cases}
$$

and $c_{*}>0$ is the Poincaré constant. Finally, taking $k=1$ in (2.9), we see that (2.14) leads to (2.10) with $\epsilon=c_{*} \delta\left(1+\frac{1}{g_{0}}\left(\int_{0}^{\infty}\left(-g^{\prime}(s)\right) d s\right)\right)$ and $c_{\epsilon}=c_{* *} C_{\delta} \frac{1}{g_{0}}$.

Now, just in the case $j=2$, we need an estimate $H^{2}$-for the solution of (1.12) similar to the estimate (2.2). This estimate is reported in the following lemma.

Lemma 2.4. When $j=2$, there exist positive constants $c_{k, 2}, k \in\{1,2\}$, such that the following inequality

$$
\begin{equation*}
\|\Delta y\|^{2} \leq c_{1,2}\left\|\eta^{t}\right\|_{L_{2}}^{2}+c_{2,2} \int_{\Omega}\left[\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Im}\left(y_{t}\right) \operatorname{Re}(y)\right] d x \tag{2.16}
\end{equation*}
$$

holds.
Proof. Multiplying equation (1.12) by $\bar{y}$, integrating over we have

$$
0=i \int_{\Omega} y_{t} \bar{y} d x-\|\nabla y\|^{2}-\|\Delta y\|^{2}+i \int_{0}^{\infty} g(s) \int_{\Omega} \Delta^{2} \eta^{t} \bar{y} d x d s
$$

since the boundary conditions (1.3) and (1.9) are verified and $y(t, \cdot) \in H_{0}^{2}(\Omega)$ for all $t \in \mathbb{R}^{+}$. Now, taking the real part in the previous equality give us

$$
\begin{equation*}
-\operatorname{Im}\left(\int_{\Omega} y_{t} \bar{y} d x\right)-\|\nabla y\|^{2}-\|\Delta y\|^{2}+\operatorname{Re}\left(i \int_{0}^{\infty} g(s) \int_{\Omega} \Delta^{2} \eta^{t} \bar{y} d x d s\right)=0 \tag{2.17}
\end{equation*}
$$

Taking into account that

$$
\begin{equation*}
\operatorname{Im}\left(\int_{\Omega} y_{t} \bar{y} d x\right)=\int_{\Omega}\left(\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)-\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)\right) d x \tag{2.18}
\end{equation*}
$$

and, thanks to the generalized Young inequality, we have that

$$
\begin{align*}
\left|i \int_{0}^{\infty} g(s) \int_{\Omega} \Delta^{2} \eta^{t} \bar{y} d x d s\right| & =\left|i\left\langle\eta^{t}, y\right\rangle_{L_{2}}\right| \leq\|y\|_{L_{2}}\left\|\eta^{t}\right\|_{L_{2}} \\
& \leq \underbrace{g_{1} \epsilon}_{=: \delta}\|\Delta y\|^{2}+C(\epsilon)\left\|\eta^{t}\right\|_{L_{2}}^{2}=\delta\|\Delta y\|^{2}+C(\delta)\left\|\eta^{t}\right\|_{L_{2}}^{2} \tag{2.19}
\end{align*}
$$

We get, putting (2.18) and (2.19) into (2.17), that

$$
\begin{equation*}
\|\Delta y\|^{2} \leq \int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x+\delta\|\Delta y\|^{2}+C(\delta)\left\|\eta^{t}\right\|_{L_{2}}^{2} \tag{2.20}
\end{equation*}
$$

Finally, pick $\delta=\frac{1}{2}>0$ in (2.20) to get

$$
\frac{1}{2}\|\Delta y\|^{2} \leq \int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x+C(\delta)\left\|\eta^{t}\right\|_{L_{2}}^{2}
$$

showing (2.16) with $c_{1,2}=2 C(\delta)$ and $c_{2,2}=2$.
As a consequence of (2.10), the last term of the right-hand side of (2.16) can be bounded as follows.

Lemma 2.5. For any $\epsilon>0$, we have the following inequality

$$
\begin{equation*}
\int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x \leq \epsilon\|\Delta y\|^{2}+c_{\epsilon} \int_{0}^{\infty} g(s)\left\|\Delta \eta_{t t}^{t}\right\|^{2} d s-c_{\epsilon} E_{2,1}^{\prime}(t) \tag{2.21}
\end{equation*}
$$

Proof. Using the Poincaré inequality in the first term of the right-hand side of (2.10), and taking $\epsilon=c^{*} \epsilon$, where $c^{*}$ is the Poincaré constant, the result follows.

The next lemma combines the previous one to get an estimate in $H_{j}$ for solutions of (1.12).
Lemma 2.6. There exist a positive constant $c=c(j)>0$, with $j \in\{1,2\}$ such that

$$
\begin{equation*}
\left.\left\|\Delta^{\frac{j}{2}} y\right\|^{2} \leq c\left(E_{j}(0)\right)+E_{j, 1}(0)+E_{j, 2}(0)\right) . \tag{2.22}
\end{equation*}
$$

Proof. Pick $\epsilon=\frac{1}{2 c_{2, j}}$ in (2.10) and (2.21) when $j=1$ and $j=2$, respectively. So we have

$$
\int_{\Omega}\left(\operatorname{Re}\left(y_{t}\right) \operatorname{Im}(y)-\operatorname{Re}(y) \operatorname{Im}\left(y_{t}\right)\right) d x \leq \frac{1}{2 c_{2, j}}\left\|\Delta^{\frac{j}{2}} y\right\|^{2}+c_{\epsilon} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta_{t t}^{t}\right\|^{2} d s-c_{\epsilon} E_{j, 1}^{\prime}(t) .
$$

Replacing the previous inequality in (2.2) and in (2.16) for $j=1$ and $j=2$, respectively, we get that

$$
\begin{equation*}
\left\|\Delta^{\frac{j}{2}} y\right\|^{2} \leq c_{1, j}\left\|\eta^{t}\right\|_{L_{j}}^{2}+\frac{1}{2}\left\|\Delta^{\frac{j}{2}} y\right\|^{2}+c_{2, j} c_{\epsilon} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta_{t t}^{t}\right\|^{2} d s-c_{2, j} c_{\epsilon} E_{j, 1}^{\prime}(t) . \tag{2.23}
\end{equation*}
$$

Therefore, the properties (1.10) for the function $g$, together to the fact that $E_{j, k}$, given in (2.8), is non-increasing and (2.9) give us

$$
\begin{aligned}
\left\|\Delta^{\frac{j}{2}} y\right\|^{2} & \leq 2 c_{1, j}\left\|\eta^{t}\right\|_{L_{j}}^{2}+2 c_{2, j} c_{\epsilon} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta_{t t}^{t}\right\|^{2} d s-2 c_{2, j} c_{\epsilon} E_{j, 1}^{\prime}(t) \\
& \leq c_{j, 4}\left(E_{j}(t)+E_{j, 1}(t)+E_{j, 2}(t)\right) \\
& \leq c\left(E_{j}(0)+E_{j, 1}(0)+E_{j, 2}(0)\right)
\end{aligned}
$$

where $c=c(j):=c_{j, 4}=\max \left\{4 c_{1, j}, 4 c_{2, j} c_{\varepsilon}, 2 c_{0} c_{2, j} c_{\epsilon}\right\}$, for $j \in\{1,2\}$, proving the lemma.
Before presenting the main result of this section, the next result ensures that the following norms $\left\|\Delta^{\frac{1}{2}} \eta^{t}\right\|,\left\|\eta^{t}\right\|$, and $\left\|\eta_{t t}^{t}\right\|$ can be controlled by the generalized energies $E_{k, j}(0)$ and the initial condition $y_{0}$, for $t \geq s \geq 0$. The result is the following one.
Lemma 2.7. Considering the hypothesis of the Lemma 2.6, the following inequality holds

$$
\begin{equation*}
\left\|\Delta^{\frac{j}{2}} \eta^{t}\right\|^{2} \leq M_{j, 0}(t, s), \tag{2.24}
\end{equation*}
$$

where

$$
M_{j, 0}(t, s):=\left\{\begin{array}{l}
c\left(E_{j}(0)+E_{j, 1}(0)+E_{j, 2}(0)\right), \text { if } 0 \leq s \leq t  \tag{2.25}\\
\left\|\int_{0}^{s-t} \Delta^{\frac{j}{2}} y_{0}(\cdot, \tau) d \tau\right\|^{2}+2 s^{2} c\left(E_{j}(0)+E_{j, 1}(0)+E_{j, 2}(0)\right), \text { if } s>t \geq 0 .
\end{array}\right.
$$

Additionally, for $j=0$, we have

$$
\left\|\eta^{t}\right\|^{2} \leq M_{0,0}(t, s):=\left\{\begin{array}{l}
2 s^{2} E_{0}(0), \text { if } 0 \leq s \leq t  \tag{2.26}\\
2\left\|\int_{0}^{s-t} y_{0}(\cdot, \tau) d \tau\right\|^{2}+4 s^{2} E_{0}(0), \text { if } s>t \geq 0
\end{array}\right.
$$

and

$$
\left\|\eta_{t t}^{t}\right\|^{2} \leq M_{0,2}(t, s):=\left\{\begin{array}{l}
2 s^{2} E_{0,2}(0), \text { if } 0 \leq s \leq t  \tag{2.27}\\
2\left\|\int_{0}^{s-t} \partial_{\tau}^{2} y_{0}(\cdot, \tau) d \tau\right\|^{2}+4 s^{2} E_{0,2}(0), \text { if } s>t \geq 0
\end{array}\right.
$$

Proof. Let us first prove (2.24). Hölder inequality and (2.22), for $j \in\{1,2\}$, gives that

$$
\begin{aligned}
\left\|\Delta^{\frac{j}{2}} \eta^{t}\right\|^{2} & =\left\|\int_{t-s}^{t} \Delta^{\frac{j}{2}} y(\cdot, \tau) d \tau\right\|^{2} \leq\left(\int_{t-s}^{t} 1 \cdot\left\|\Delta^{\frac{j}{2}} y(\cdot, \tau)\right\| d \tau\right)^{2} \leq s\left(\int_{t-s}^{t}\left\|\Delta^{\frac{j}{2}} y(\cdot, \tau)\right\|^{2} d \tau\right) \\
& \leq s^{2} c\left(E_{j}(0)+E_{j, 1}(0)+E_{j, 2}(0)\right)
\end{aligned}
$$

for $t \geq s \geq 0$. Analogously,

$$
\left\|\Delta^{\frac{j}{2}} \eta^{t}\right\|^{2}=\left\|\int_{t-s}^{t} \Delta^{\frac{j}{2}} y(\cdot, \tau) d \tau\right\|^{2} \leq 2\left\|\int_{0}^{s-t} \Delta^{\frac{j}{2}} y_{0}(\cdot, \tau) d \tau\right\|^{2}+2 s^{2} c\left(E_{j}(0)+E_{j, 1}(0)+E_{j, 2}(0)\right),
$$

when $s>t \geq 0$. Consequently, (2.24) is verified.
Now, for $j=0$, since $\|y\|^{2}$ is part of $E_{0}$ (see (1.5)), and the energy $E_{0}$ is non-increasing, we observe, using Hölder inequality, that

$$
\begin{aligned}
\left\|\eta^{t}\right\|^{2} & =\left\|\int_{t-s}^{t} y(\cdot, \tau) d \tau\right\|^{2} \leq\left(\int_{t-s}^{t} 1 \cdot\|y(\cdot, \tau)\| d \tau\right)^{2} \leq s \int_{t-s}^{t}\|y(\cdot, \tau)\|^{2} d \tau \\
& \leq s \int_{t-s}^{t} 2 E_{0}(\tau) d \tau \leq s \int_{t-s}^{t} 2 E_{0}(0) d \tau=2 s^{2} E_{0}(0),
\end{aligned}
$$

for $t \geq s \geq 0$. On the other hand,

$$
\begin{aligned}
\left\|\eta^{t}\right\|^{2} & =\left\|\int_{0}^{s-t} y_{0}(\cdot, \tau) d \tau+\int_{0}^{t} y(\cdot, \tau) d \tau\right\|^{2} \leq 2\left\|\int_{0}^{s-t} y_{0}(\cdot, \tau) d \tau\right\|^{2}+2\left\|\int_{0}^{t} y(\cdot, \tau) d \tau\right\|^{2} \\
& \leq 2\left\|\int_{0}^{s-t} y_{0}(\cdot, \tau) d \tau\right\|^{2}+4 E_{0}(0) s^{2}
\end{aligned}
$$

for $s>t \geq 0$. Thus, (2.26) follows.
Finally, let us prove (2.27). To do that, observe that (1.13) is linear and $V=\partial_{t}^{2} U$ is solution for (1.13) with initial condition $V(0)(x, s)=\left(\partial_{t}^{2} y_{0}(x, 0), \zeta^{0}(x, s)\right)$, where

$$
\zeta^{0}(x, s)=\int_{0}^{s} \partial_{\tau}^{2} y_{0}(x, \tau) d \tau
$$

Thanks to relation (2.25), for $j \in\{1,2\}$, we get that

$$
M_{j, 2}(t, s):=\left\{\begin{array}{l}
c_{j, 5}\left(E_{j, 2}(0)+E_{j, 3}(0)+E_{j, 4}(0)\right), \text { if } 0 \leq s \leq t  \tag{2.28}\\
2\left\|\int_{0}^{s-t} \Delta^{\frac{j}{2}} \partial_{\tau}^{2} y_{0}(\cdot, \tau) d \tau\right\|^{2} \\
\quad+2 s^{2} c_{j, 5}\left(E_{j, 2}(0)+E_{j, 3}(0)+E_{j, 4}(0)\right), \text { if } s>t \geq 0
\end{array}\right.
$$

and so,

$$
\left\|\eta_{t t}^{t}\right\|^{2} \leq M_{j, 2}(t, s)
$$

Therefore, inequality (2.27) follows using the previous inequality with $j=0$, and thanks to the relation (2.26), the result is proved.

The next result is the key lemma to establish the stabilization result for the biharmonic Schrödinger system (1.3).

Lemma 2.8. There exist positive constants $d_{j, k}$, for each $j \in\{0,1,2\}$ and each $k \in\{0,2\}$ such that the following inequality holds

$$
\begin{equation*}
\frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s \leq-d_{j, k} E_{j, k}^{\prime}(t)+d_{j, k} G_{0}\left(\epsilon_{0} E_{j}(t)\right), \tag{2.29}
\end{equation*}
$$

for any $\epsilon_{0}>0$. Here, $E_{j, 0}=E_{j}, E_{j, 0}^{\prime}=E_{j}^{\prime}(0)$ and $G_{0}$ defined as in Theorem 1.4.
Proof. Suppose, first, that the relation (1.17) is satisfied. So, thanks to the relation (2.9), we have

$$
E_{j, k}^{\prime}=\frac{1}{2} \int_{0}^{\infty} g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s \leq-\frac{1}{2} \alpha_{0} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s,
$$

for each $j \in\{0,1,2\}$ and each $k \in\{0,2\}$, that is,

$$
\int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s \leq-\frac{2}{\alpha_{0}} E_{j, k}^{\prime}
$$

showing (2.29) for each $d_{j, k}=\frac{2}{\alpha_{0}}$ and $G_{0}(s)=s$.
On the other hand, suppose now that (1.18) and (1.11) are verified. Let us assume, without loss of generality, that $E_{j}(t)>0$ and $g^{\prime}<0$ in $\mathbb{R}_{+}$. Let $\tau_{j, k}(t, s), \theta_{j}(t, s), j \in\{0,1,2\}, k \in\{0,2\}$ and $\epsilon_{0}$ be a positive real number which will be fixed later on, and $K(s)=\frac{s}{G^{-1}(s)}$, for $s>0$. Assumption 2 implies that

$$
\lim _{s \rightarrow 0^{+}} K(s)=\lim _{s \rightarrow 0^{+}} \frac{s}{G^{-1}(s)}=\lim _{\tau=G^{-1}(s) \rightarrow 0^{+}} \frac{G(\tau)}{\tau}=G^{\prime}(0)=0 .
$$

Additionally, thanks to the continuity of $K$ we have $K(0)=0$.
We claim that the function $K$ is non-decreasing. Indeed, since $G$ is convex we have that $G^{-1}$ is concave and $G^{-1}(0)=0$, implying that

$$
K\left(s_{1}\right)=\frac{s_{1}}{G^{-1}\left(\frac{s_{1}}{s_{2}} s_{2}+\left(1-\frac{s_{1}}{s_{2}}\right) \cdot 0\right)} \leq \frac{s_{1}}{\frac{s_{1}}{s_{2}} G^{-1}\left(s_{2}\right)}=\frac{s_{2}}{G^{-1}\left(s_{2}\right)}=K\left(s_{2}\right),
$$

for $0 \leq s_{1}<s_{2}$, proving the claim.
Now, note that thanks to the fact that $K$ is non-decreasing and by (2.24), (2.26), (2.28), and (2.27), we get

$$
\begin{equation*}
K\left(-\theta_{j, k}(t, s) g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) \leq K\left(-\theta_{j, k}(t, s) g^{\prime}(s) M_{j, k}(t, s)\right) . \tag{2.30}
\end{equation*}
$$

Inequality (2.30) yields that

$$
\begin{align*}
\int_{0}^{\infty} g(s)\left\|\Delta^{\frac{1}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s= & \frac{1}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)} \int_{0}^{\infty} \frac{1}{\tau_{j, k}(t, s)} G^{-1}\left(-\theta_{j, k} g^{\prime}(s)\left\|\Delta^{\frac{1}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) \\
& \times \frac{\tau_{j, k}(t, s) G^{\prime}\left(\epsilon_{0} E_{j}(t)\right) g(s)}{-\theta_{j, k} g^{\prime}(s)} K\left(-\theta_{j, k} g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) d s \\
\leq & \frac{1}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)} \int_{0}^{\infty} \frac{1}{\tau_{j, k}(t, s)} G^{-1}\left(-\theta_{j, k} g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) \\
& \times \frac{\tau_{j, k}(t, s) G^{\prime}\left(\epsilon_{0} E_{j}(t)\right) g(s)}{-\theta_{j, k} g^{\prime}(s)} K\left(-M_{j, k} \theta_{j, k} g^{\prime}(s)\right) d s  \tag{2.31}\\
\leq & \frac{1}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)} \int_{0}^{\infty} \frac{1}{\tau_{j, k}(t, s)} G^{-1}\left(-\theta_{j, k} g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) \\
& \times \frac{M_{j, k}(t, s) \tau_{j, k}(t, s) G^{\prime}\left(\epsilon_{0} E_{j}(t)\right) g(s)}{G^{-1}\left(-M_{j, k} \theta_{j, k} g^{\prime}(s)\right)} d s .
\end{align*}
$$

Denote the dual function of $G$ by $G^{*}(s)=\sup _{\tau \in \mathbb{R}_{+}}\{s \tau-G(\tau)\}$, for $s \in \mathbb{R}_{+}$. From the Assumption 2 we have

$$
G^{*}(s)=s\left(G^{\prime}\right)^{-1}(s)-G\left(\left(G^{\prime}\right)^{-1}(s)\right), \quad s \in \mathbb{R}_{+} .
$$

Observe also that

$$
s_{1} s_{2} \leq G\left(s_{1}\right)+G^{*}\left(s_{2}\right), \quad \forall s_{1}, s_{2} \in \mathbb{R}_{+},
$$

in particular

$$
s_{1}=G^{-1}\left(-\theta_{j, k}(t, s) g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right)
$$

and

$$
s_{2}=\frac{M_{j, k} \tau_{j, k} G^{\prime}\left(\epsilon_{0} E_{j}(t)\right) g(s)}{-M_{j, k}(t, s) g^{\prime}(s) \theta_{j, k}} .
$$

Therefore, we obtain, by using the previous equality in (2.31), that

$$
\begin{aligned}
\int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s \leq & \frac{1}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)} \int_{0}^{\infty} \frac{1}{\tau_{j, k}(t, s)}\left(-\theta_{j, k} g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) d s \\
& +\frac{1}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)} \int_{0}^{\infty} \frac{1}{\tau_{j, k}} G^{*}\left(\frac{M_{j, k} \tau_{j, k} G^{\prime}\left(\epsilon_{0} E_{j}(t)\right) g(s)}{G^{-1}\left(-M_{j, k} \theta_{j, k} g^{\prime}(s)\right)}\right) d s .
\end{aligned}
$$

Using that $G^{*}(s) \leq s\left(G^{\prime}\right)^{-1}(s)$, we get

$$
\begin{aligned}
\int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s \leq & \frac{1}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)}\left[\int_{0}^{\infty} \frac{1}{\tau_{j, k}}\left(-\theta_{j, k} g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) d s\right. \\
& \left.+\int_{0}^{\infty} \frac{1}{\tau_{j, k}} \frac{M_{j, k} \tau_{j, k} G^{\prime}\left(\epsilon_{0} E_{j}(t)\right) g(s)}{G^{-1}\left(-M_{j, k} \theta_{j, k} g^{\prime}(s)\right)}\left(G^{\prime}\right)^{-1}\left(\frac{M_{j, k} \tau_{j, k} G^{\prime}\left(\epsilon_{0} E_{j}(t)\right) g(s)}{G^{-1}\left(-M_{j, k} \theta_{j, k} g^{\prime}(s)\right)}\right) d s\right] .
\end{aligned}
$$

Pick $\theta_{j, k}=\frac{1}{M_{j, k}}$, to ensure that

$$
\begin{aligned}
\int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s \leq & \frac{1}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)} \int_{0}^{\infty} \frac{1}{\tau_{j, k} M_{j, k}}\left(-g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) d s \\
& +\int_{0}^{\infty} \frac{M_{j, k} g(s)}{G^{-1}\left(-g^{\prime}(s)\right)}\left(G^{\prime}\right)^{-1}\left(\frac{M_{j, k} \tau_{j, k} G^{\prime}\left(\epsilon_{0} E_{j}(t)\right) g(s)}{G^{-1}\left(-g^{\prime}(s)\right)}\right) d s .
\end{aligned}
$$

Thanks to the fact that $\left(G^{\prime}\right)^{-1}$ is non-decreasing we get,

$$
\begin{aligned}
\int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s \leq & \frac{1}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)} \int_{0}^{\infty} \frac{1}{\tau_{j, k} M_{j, k}}\left(-g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) d s \\
& +\int_{0}^{\infty} \frac{M_{j, k} g(s)}{G^{-1}\left(-g^{\prime}(s)\right)}\left(G^{\prime}\right)^{-1}\left(m_{0} M_{j, k} \tau_{j, k} G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)\right) d s,
\end{aligned}
$$

where $m_{0}=\sup _{s \in \mathbb{R}_{+}} \frac{g(s)}{G^{-1}\left(-g^{\prime}(s)\right)}$. Note that (1.18) and (1.19), yields that

$$
m_{1}=\sup _{s \in \mathbb{R}_{+}} \int_{0}^{\infty} \frac{M_{j, k}(s, t) g(s)}{G^{-1}\left(-g^{\prime}(s)\right)} d s<\infty .
$$

Thus, using that $\tau_{j, k}(t, s)=\frac{1}{m_{0} M_{j, k}(t, s)}$ and relation (2.1), we have that

$$
\begin{aligned}
\int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s \leq & -\frac{m_{0}}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)} \int_{0}^{\infty}\left(g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2}\right) d s \\
& +\left(\epsilon_{0} E_{j}(t)\right) \int_{0}^{\infty} \frac{M_{j, k} g(s)}{G^{-1}\left(-g^{\prime}(s)\right)} d s \\
= & -\frac{2 m_{0}}{G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)} E_{j, k}^{\prime}(t)+\epsilon_{0} m_{1} E_{j}(t) .
\end{aligned}
$$

Finally, multiplying the previous inequality by $G^{\prime}\left(\epsilon_{0} E_{j}(t)\right)=\frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)}$ gives

$$
\frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \partial_{t}^{k} \eta^{t}\right\|^{2} d s \leq-2 m_{0} E_{j, k}^{\prime}(t)+m_{1} G_{0}\left(\epsilon_{0} E_{j}(t)\right),
$$

which taking $d_{j, k}=\max \left\{2 m_{0}, m_{1}\right\}$, ensures (2.29), showing the lemma.

## 3 Proof of Theorem 1.4

Let us split the proof into two cases: a) $n=1$ and b) $n>1$.
a) $n=1$

Poincaré's inequality gives us

$$
\|y\|^{2} \leq c_{*}\|\nabla y\|^{2} \leq c_{*}^{2}\|\Delta y\|^{2},
$$

where $c_{*}>0$ is the Poincaré constant. Summarizing,

$$
\|y\|^{2} \leq c_{* *}\left\|\Delta^{\frac{j}{2}} y\right\|^{2}
$$

for $c_{* *}$ defined by (2.15). From the definition of $E_{j}$ given by (1.5) we found that

$$
\frac{2}{\epsilon_{0} c_{* *}} G_{0}\left(\epsilon_{0} E_{j}(t)\right) \leq \frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)}\left\|\Delta^{\frac{j}{2}} y\right\|^{2}+\frac{1}{c_{* *}} \frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta^{t}\right\|^{2} d s .
$$

Thanks to the inequality (2.23), we have

$$
\begin{align*}
\frac{2}{\epsilon_{0} c_{* *}} G_{0}\left(\epsilon_{0} E_{j}(t) \leq\right. & \frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)}\left(2 c_{1, j}\left\|\eta^{t}\right\|_{L_{j}}^{2}+2 c_{2, j} c_{\epsilon} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta_{t t}^{t}\right\|^{2} d s-2 c_{2, j} c_{\epsilon} E_{j, 1}^{\prime}(t)\right) \\
& +\frac{1}{c_{* *}} \frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta^{t}\right\|^{2} d s \\
= & \frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)}\left(2 c_{2, j} c_{\epsilon} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta_{t t}^{t}\right\|^{2} d s-2 c_{2, j} c_{\epsilon} E_{j, 1}^{\prime}(t)\right) \\
& +\left(2 c_{1, j}+\frac{1}{c_{* *}}\right) \frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)} \int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} \eta^{t}\right\|^{2} d s . \tag{3.1}
\end{align*}
$$

Combining (3.1) with (2.29), gives

$$
\begin{aligned}
\frac{2}{\epsilon_{0} c_{* *}} G_{0}\left(\epsilon_{0} E_{j}(t)\right) \leq & -2 c_{2, j} c_{\epsilon} d_{j, 2} E_{j, 2}^{\prime}(t)+2 c_{2, j} c_{\epsilon} d_{j, 2} G_{0}\left(\epsilon_{0} E_{j}(t)\right)-2 c_{2, j} \frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)} c_{\epsilon} E_{j, 1}^{\prime}(t) \\
& -d_{j, 0}\left(2 c_{1, j}+\frac{1}{c_{* *}}\right) E_{j}^{\prime}(t)+d_{j, 0}\left(2 c_{1, j}+\frac{1}{c_{* *}}\right) G_{0}\left(\epsilon_{0} E_{j}(t)\right) .
\end{aligned}
$$

So,

$$
\begin{align*}
& \left(\frac{2}{\epsilon_{0} c_{* *}}-2 c_{2, j} c_{\epsilon} d_{j, 2}-d_{j, 0}\left(2 c_{1, j}+\frac{1}{c_{* *}}\right)\right) G_{0}\left(\epsilon_{0} E_{j}(t)\right)  \tag{3.2}\\
& \quad \leq-2 c_{2, j} c_{\epsilon} d_{j, 2} E_{j, 2}^{\prime}(t)-2 c_{2, j} \frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)} c_{\epsilon} E_{j, 1}^{\prime}(t)-d_{j, 0}\left(2 c_{1, j}+\frac{1}{c_{* *}}\right) E_{j}^{\prime}(t) .
\end{align*}
$$

Observe that $H_{0}(s)=\frac{G_{0}(s)}{s}$ is non-decreasing and $E_{j}$ is non-increasing for each $j$, thus $\frac{G_{0}\left(\epsilon_{0} E_{j}(t)\right)}{\epsilon_{0} E_{j}(t)}$ is non-increasing for each $j$, and therefore by (3.2) we get

$$
\begin{align*}
& \left(\frac{2}{\epsilon_{0} c_{* *}}-2 c_{2, j} c_{\epsilon} d_{j, 2}-d_{j, 0}\left(2 c_{1, j}+\frac{1}{c_{* *}}\right)\right) G_{0}\left(\epsilon_{0} E_{j}(t)\right) \\
& \quad \leq-2 c_{2, j} c_{\epsilon} d_{j, 2} E_{j, 2}^{\prime}(t)-2 c_{2, j} \frac{G_{0}\left(\epsilon_{0} E_{j}(0)\right)}{\epsilon_{0} E_{j}(0)} c_{\epsilon} E_{j, 1}^{\prime}(t)-d_{j, 0}\left(2 c_{1, j}+\frac{1}{c_{* *}}\right) E_{j}^{\prime}(t) \tag{3.3}
\end{align*}
$$

For $\epsilon_{0}>0$ small enough we have

$$
c_{1}=\left(\frac{2}{\epsilon_{0} c_{* *}}-2 c_{2, j} c_{\epsilon} d_{j, 2}-d_{j, 0}\left(2 c_{1, j}+\frac{1}{c_{* *}}\right)\right)>0 .
$$

Thus, dividing (3.3) by $c_{1}>0$ yields that

$$
\begin{equation*}
G_{0}\left(\epsilon_{0} E_{j}(t)\right) \leq-c_{2}\left(E_{j}^{\prime}(t)+E_{j, 1}^{\prime}(t)+E_{j, 2}^{\prime}(t)\right) \tag{3.4}
\end{equation*}
$$

where

$$
c_{2}=\max \left\{\frac{2 c_{2, j} c_{\epsilon} d_{j, 2}}{c_{1}}, \frac{2 c_{2, j} \frac{G_{0}\left(\epsilon_{0} E_{j}(0)\right)}{\epsilon_{0} E_{j}(0)} c_{\epsilon}}{c_{1}}, \frac{d_{j, 0}\left(2 c_{1, j}+\frac{1}{c_{* *}}\right)}{c_{1}}\right\} .
$$

Now, integrating (3.4) on $[0, t], t \in \mathbb{R}_{+}^{*}$, and observing that $G_{0}\left(\epsilon_{0} E_{j}(t)\right)$ is non-increasing gives

$$
\begin{aligned}
t G_{0}\left(\epsilon_{0} E_{j}(t)\right) & =\int_{0}^{t} G_{0}\left(\epsilon_{0} E_{j}(t)\right) d s \leq \int_{0}^{t} G_{0}\left(\epsilon_{0} E_{j}(s)\right) d s \leq-c_{2} \int_{0}^{t}\left(E_{j}^{\prime}(s)+E_{j, 1}^{\prime}(s)+E_{j, 2}^{\prime}(s)\right) d s \\
& =-c_{2}\left(E_{j}(t)+E_{j, 1}(t)+E_{j, 2}(t)\right)+c_{2}\left(E_{j}(0)+E_{j, 1}(0)+E_{j, 2}(0)\right) \\
& \leq c_{2}\left(E_{j}(0)+E_{j, 1}(0)+E_{j, 2}(0)\right)=: c_{3} .
\end{aligned}
$$

Because $G_{0}$ is invertible and non-decreasing, we deduce that

$$
E_{j}(t) \leq \frac{1}{\epsilon_{0}}\left(G_{0}\right)^{-1}\left(\frac{c_{3}}{t}\right)=\frac{1}{\epsilon_{0}} G_{1}\left(\frac{c_{3}}{t}\right) \leq \alpha_{j, 1} G_{1}\left(\frac{\alpha_{j, 1}}{t}\right),
$$

for $\alpha_{j, 1}=\max \left\{\frac{1}{\epsilon_{0}}, c_{3}\right\}$, showing (1.20) when $n=1$.
a) $n>1$

Suppose, for induction hypothesis, that for some $n \in \mathbb{N}^{*}$, we have that (1.20) is verified when $U_{0} \in D\left(\mathcal{A}_{j}^{2 n+2}\right)$ for $j \in\{1,2\}$ and $U_{0} \in D\left(\mathcal{A}_{j}^{2 n}\right)$ for $j=0$. For $j \in\{1,2\}$, let us take $U_{0} \in D\left(\mathcal{A}_{j}^{2(n+1)+2}\right)$ and for $j=0$, take $U_{0} \in D\left(\mathcal{A}_{j}^{2(n+1)}\right)$. So when $j \in\{1,2\}$ we have

$$
\begin{gathered}
U_{0} \in D\left(\mathcal{A}_{j}^{2(n+1)+2}\right) \subset D\left(\mathcal{A}_{j}^{2 n+2}\right), \quad U_{t}(0) \in D\left(\mathcal{A}_{j}^{2(n+1)+1}\right) \subset D\left(\mathcal{A}_{j}^{2 n+2}\right), \\
\text { and } \quad U_{t t}(0) \in D\left(\mathcal{A}_{j}^{2 n+2}\right) .
\end{gathered}
$$

Now, for $j=0$, we found

$$
U_{0} \in D\left(\mathcal{A}_{j}^{2(n+1)}\right) \subset D\left(\mathcal{A}_{j}^{2 n}\right), \quad U_{t}(0) \in D\left(\mathcal{A}_{j}^{2 n+1}\right) \subset D\left(\mathcal{A}_{j}^{2 n}\right) \quad \text { and } \quad U_{t t}(0) \in D\left(\mathcal{A}_{j}^{2 n}\right)
$$

So, it follows from the induction hypothesis that: there exists $\alpha_{j, n}$ such that

$$
E_{j}(t) \leq \alpha_{j, n} G_{n}\left(\frac{\alpha_{j, n}}{t}\right), \quad \forall t \in \mathbb{R}_{+}^{*}
$$

Now, since $U_{t}$ and $U_{t t}$ are solution of (1.13) with initial conditions $U_{t}(0) \in D\left(\mathcal{A}_{j}^{2 n+2}\right)$ and $U_{t t}(0) \in D\left(\mathcal{A}_{j}^{2 n+2}\right)$, respectively, the induction hypothesis guarantees the existence of $\beta_{n, t}>0$ and $\gamma_{n, t}>0$, such that

$$
E_{j, 1}(t) \leq \beta_{j, n} G_{n}\left(\frac{\beta_{j, n}}{t}\right), \quad \forall t \in \mathbb{R}_{+}^{*} \quad \text { and } \quad E_{j, 2}(t) \leq \gamma_{j, n} G_{n}\left(\frac{\gamma_{j, n}}{t}\right), \quad \forall t \in \mathbb{R}_{+}^{*},
$$

respectively. Thus, as $G_{n}^{\prime} s$ are non-decreasing for $\tilde{d}_{j, n}=\max \left\{3 \alpha_{j, n}, 3 \beta_{j, n}, 3 \gamma_{j, n}\right\}$, we get

$$
E_{j}(t)+E_{j, 1}(t)+E_{j, 2}(t) \leq \tilde{d}_{j, n} G_{n}\left(\frac{\tilde{d}_{j, n}}{t}\right)
$$

Finally, how $t \in[T, 2 T]$, we have

$$
G_{0}\left(\epsilon_{0} E_{j}(2 T)\right) \leq G_{0}\left(\epsilon_{0} E_{j}(t)\right)
$$

and from (3.4) we found the following

$$
\begin{aligned}
T G_{0}\left(\epsilon_{0} E_{j}(2 T)\right) & \leq \int_{T}^{2 T} G_{0}\left(\epsilon_{0} E_{j}(t)\right) d t \leq-c_{2} \int_{T}^{2 T}\left(E_{j}^{\prime}(t)+E_{j, 1}^{\prime}(t)+E_{j, 2}^{\prime}(t)\right) d t \\
& =-c_{2}\left(E_{j}(2 T)+E_{j, 1}(2 T)+E_{j, 2}(2 T)\right)+c_{2}\left(E_{j}(T)+E_{j, 1}(T)+E_{j, 2}(T)\right) \\
& \leq c_{2}\left(E_{j}(T)+E_{j, 1}(T)+E_{j, 2}(T)\right) \leq c_{2} \tilde{d}_{j, n} G_{n}\left(\frac{\tilde{d}_{j, n}}{T}\right) \leq d_{j, n} G_{n}\left(\frac{d_{j, n}}{T}\right),
\end{aligned}
$$

where $d_{j, n}=\max \left\{c_{2} \tilde{d}_{j, n}, \tilde{d}_{j, n}\right\}$. Moreover, as $G_{0}$ is non-decreasing, $G_{1}=G_{0}^{-1}$ is also nondecreasing. Therefore,

$$
E_{j}(2 T) \leq \frac{1}{\epsilon_{0}} G_{0}^{-1}\left(\frac{2 d_{j, n}}{2 T} G_{n}\left(\frac{2 d_{j, n}}{2 T}\right)\right)=\frac{1}{\epsilon_{0}} G_{1}\left(\tilde{s} G_{n}(\tilde{s})\right)=\frac{1}{\epsilon_{0}} G_{n+1}(\tilde{s})=\alpha_{j, n+1} G_{n+1}\left(\frac{\alpha_{j, n+1}}{2 T}\right),
$$

where $\alpha_{j, n+1}:=\max \left\{\frac{1}{\epsilon_{0}}, 2 d_{j, n}\right\}$. In other words, there is $\alpha_{j, n+1}>0$ such that (1.20) holds for $n+1$. By the principle of induction we have that (1.20) is verified for all $n \in \mathbb{N}^{*}$, showing Theorem 1.4.

## Acknowledgments

This work is part of the Ph.D. thesis of de Jesus at the Department of Mathematics of the Federal University of Pernambuco. Capistrano-Filho was supported by grants numbers CNPq 307808/2021-1, 401003/2022-1 and 200386/2022-0, CAPES 88881.311964/2018-01 and 88881.520205/2020-01, and MATHAMSUD 21-MATH-03.

## A Well-posedness via semigroup theory

This section is devoted to proving that the system (1.13) is well-posed in the energy space $\mathcal{H}_{j}$. To do that, first, let us present some properties of $\mathcal{A}_{j}$, defined by (1.14)-(1.15) and its adjoin $\mathcal{A}_{j}^{*}$ defined by

$$
\begin{equation*}
\mathcal{A}_{j}^{*}(V)=\binom{-i \Delta v+i \Delta^{2} v+(-1)^{j} \int_{0}^{\infty} g(s) \Delta^{j} \zeta^{t}(\cdot, s) d s}{\zeta_{s}^{t}+\frac{g^{\prime}(s)}{g(s)} \zeta^{t}-v} \tag{A.1}
\end{equation*}
$$

with

$$
\begin{equation*}
D\left(\mathcal{A}_{j}^{*}\right)=\left\{V=\left(v, \zeta^{t}\right) \in \mathcal{H}_{j} ; \mathcal{A}^{*}{ }_{j}(V) \in \mathcal{H}_{j}, v \in H_{0}^{2}(\Omega), \zeta^{t}(x, 0)=0\right\}, \tag{A.2}
\end{equation*}
$$

for $j \in\{0,1,2\}$. So, our first result in this section ensures that $\mathcal{A}_{j}$ (resp. $\mathcal{A}_{j}^{*}$ ) is dissipative, and $D\left(\mathcal{A}_{j}\right)$ (resp. $\left.D\left(\mathcal{A}_{j}^{*}\right)\right)$ is dense in the energy space ${ }^{2}$.
Lemma A.1. $\mathcal{A}_{j}$ and $\mathcal{A}_{j}^{*}$ are dissipative. Moreover, $D\left(\mathcal{A}_{j}\right)$ and $D\left(\mathcal{A}_{j}^{*}\right)$ are dense in $\mathcal{H}_{j}$, for $j \in$ $\{0,1,2\}$.

Proof. Indeed, let $\left(y, \eta^{t}\right) \in D\left(\mathcal{A}_{j}\right)$ so

$$
\left\langle\mathcal{A}_{j}\left(y, \eta^{t}\right),\left(y, \eta^{t}\right)\right\rangle=-\operatorname{Re}\left(\int_{0}^{\infty} g(s) \int_{\Omega} \Delta^{\frac{j}{2}} \eta_{s}^{t} \Delta^{j} \frac{\overline{\eta^{t}}}{} d x d s\right) .
$$

As

$$
\Delta^{\frac{j}{2}} \eta_{s}^{t} \Delta^{\frac{j}{2}} \overline{\eta^{t}}=\frac{1}{2}\left(\left|\Delta^{\frac{j}{2}} \eta^{t}\right|^{2}\right)_{s}+i \operatorname{Im}\left(\Delta^{\frac{j}{2}} \eta_{s}^{t} \Delta^{\frac{j}{2}} \overline{\eta^{t}}\right),
$$

integration by parts over variable $s$, ensures that

$$
\begin{align*}
\left\langle\mathcal{A}_{j}\left(y, \eta^{t}\right),\left(y, \eta^{t}\right)\right\rangle & =-\operatorname{Re}\left(\int_{0}^{\infty} g(s) \int_{\Omega}\left(\frac{1}{2}\left(\left|\Delta^{\frac{j}{2}} \eta^{t}\right|^{2}\right)_{s}+i \operatorname{Im}\left(\Delta^{\frac{j}{2}} \eta_{s}^{t} \Delta^{\frac{j}{2}} \overline{\eta^{t}}\right)\right) d x d s\right) \\
& =\frac{1}{2} \operatorname{Re}\left(\int_{0}^{\infty} g^{\prime}(s) \int_{\Omega}\left|\Delta^{\frac{j}{2}} \eta^{t}\right|^{2} d x d s\right)  \tag{A.3}\\
& =\frac{1}{2} \int_{0}^{\infty} g^{\prime}(s)\left\|\Delta^{\frac{j}{2}} \eta^{t}\right\|^{2} d s \leq 0,
\end{align*}
$$

since (1.10) is verified. So, $\mathcal{A}_{j}$ is dissipative. Similarly, $\mathcal{A}_{j}^{*}$ defined by (A.1) is dissipative.
Now, let us prove that $D\left(\mathcal{A}_{j}\right)$ is dense on $\mathcal{H}_{j}$. Since we showed that $\mathcal{A}_{j}$ is dissipative, we need to prove that the image of $I-\mathcal{A}_{j}$ is $\mathcal{H}_{j}$, since $\mathcal{H}_{j}$ is reflexive. To do that, pick $\left(f_{1}, f_{2}\right) \in \mathcal{H}_{j}=L^{2}(\Omega) \times L_{g}^{2}\left(\mathbb{R}_{+} ; H_{0}^{j}(\Omega)\right)$, we claim that there exists $\left(y, \eta^{t}\right) \in D\left(\mathcal{A}_{j}\right)$ such that

$$
\left(y, \eta^{t}\right)-\left(i \Delta y-i \Delta^{2} y+(-1)^{j+1} \int_{0}^{\infty} g(s) \Delta^{j} \eta^{t}(\cdot, s) d s, y-\eta_{s}^{t}\right)=\left(f_{1}, f_{2}\right) .
$$

Or equivalently, we claim that there exits $\left(y, \eta^{t}\right) \in D\left(\mathcal{A}_{j}\right)$ satisfying

$$
\left\{\begin{array}{l}
y-i \Delta y+i \Delta^{2} y+(-1)^{j} \int_{0}^{\infty} g(s) \Delta^{j} \eta^{t}(\cdot, s) d s=f_{1}  \tag{A.4}\\
\eta^{t}-y+\eta_{s}^{t}=f_{2}
\end{array}\right.
$$

[^2]Indeed, multiplying the second equation of (A.4) by $e^{s}$ and integrating over $s$, we get

$$
\begin{equation*}
\eta^{t}(x, s)=\left(1-e^{-s}\right) y+\int_{0}^{s} e^{\tau-s} f_{2}(\tau) d \tau=\left(1-e^{-s}\right) y+f_{3}(s) . \tag{A.5}
\end{equation*}
$$

Since $f_{2} \in L_{g}^{2}\left(\mathbb{R}_{+} ; H_{0}^{j}(\Omega)\right)$, taking $f_{3}=\int_{0}^{s} e^{\tau-s} f_{2}(\tau) d \tau$ we have

$$
\begin{aligned}
\int_{0}^{\infty} g(s)\left\|\Delta^{\frac{j}{2}} f_{3}(s)\right\|^{2} d s & =\int_{0}^{\infty} g(s) e^{-2 s} \int_{\Omega}\left|\int_{0}^{s} e^{\tau} \Delta^{\frac{j}{2}} f_{2}(\tau) d \tau\right|^{2} d x d s \\
& \leq \int_{0}^{\infty} g(s) e^{-s} \int_{\Omega} \int_{0}^{s} e^{\tau}\left|\Delta^{\frac{j}{2}} f_{2}(\tau)\right|^{2} d \tau d x d s \\
& \leq \int_{0}^{\infty} \int_{0}^{s} g(s) e^{-s} e^{\tau}\left\|\Delta^{\frac{j}{2}} f_{2}(\tau)\right\|^{2} d \tau d s \\
& =\int_{0}^{\infty} \int_{\tau}^{\infty} g(s) e^{-s} e^{\tau}\left\|\Delta^{\frac{j}{2}} f_{2}(\tau)\right\|^{2} d s d \tau \\
& \leq \int_{0}^{\infty} \int_{\tau}^{\infty} g(\tau) e^{-s} e^{\tau}\left\|\Delta^{\frac{j}{2}} f_{2}(\tau)\right\|^{2} d s d \tau \\
& =\left\|f_{2}\right\|_{L_{8}^{2}\left(\mathbb{R}_{+} ; H_{0}^{j}(\Omega)\right)}^{2}<+\infty,
\end{aligned}
$$

that is, $f_{3} \in L_{g}^{2}\left(\mathbb{R}_{+} ; H_{0}^{j}(\Omega)\right)$. Now, for $y \in H_{0}^{2}(\Omega)$ holds that

$$
\int_{0}^{\infty} g(s)\left\|\left(1-e^{-s}\right) \Delta^{\frac{j}{2}} y\right\|^{2} d s=\left\|\Delta^{\frac{j}{2}} y\right\|^{2} \int_{0}^{\infty} g(s)\left(1-e^{-s}\right)^{2} d s \leq\left\|\Delta^{\frac{j}{2}} y\right\|^{2} g_{1}<+\infty,
$$

since

$$
g_{1}:=\int_{0}^{\infty} g(s)\left(1-e^{-s}\right) d s \leq \int_{0}^{\infty} g(s) d s=g_{0}
$$

So $\left(1-e^{-s}\right) y \in L_{g}^{2}\left(\mathbb{R}_{+} ; H_{0}^{j}(\Omega)\right)$. Therefore, for $y \in H_{0}^{2}(\Omega)$, choosing $\eta^{t}$ as in (A.5), follows that $\eta^{t} \in L_{g}^{2}\left(\mathbb{R}_{+} ; H_{0}^{j}(\Omega)\right)$ and, so $\eta^{t}(x, 0)=0$. Thanks to (A.4) we get

$$
\eta_{s}^{t}=f_{2}-\eta^{t}+y \in L_{g}^{2}\left(\mathbb{R}_{+} ; H_{0}^{j}(\Omega)\right)
$$

Finally, let us prove that $y \in H_{0}^{2}(\Omega)$ satisfies

$$
\begin{equation*}
y-i \Delta y+i \Delta^{2} y+(-1)^{j} \int_{0}^{\infty} g(s) \Delta^{j} \eta^{t}(\cdot, s) d s=f_{1}, \tag{A.6}
\end{equation*}
$$

for $\eta^{t}=\left(1-e^{-s}\right) y+f_{3}$. This is equivalent to obtain $y \in H_{0}^{2}(\Omega)$ satisfying the following elliptic equation

$$
\begin{equation*}
y-i \Delta y+i \Delta^{2} y+(-1)^{j} g_{1} \Delta^{j} y=f_{1}-(-1)^{j} \int_{0}^{\infty} g(s) \Delta^{j} f_{3}(\cdot, s) d s \tag{A.7}
\end{equation*}
$$

which is a direct consequence of the Lax-Milgram theorem. Therefore, $\left(y, \eta^{t}\right) \in D\left(\mathcal{A}_{j}\right)$ is a strong solution of $\left(I-\mathcal{A}_{j}\right)\left(y, \eta^{t}\right)=\left(f_{1}, f_{2}\right)$ and $I-\mathcal{A}_{j}$ is surjective, showing the result. Similarly, it is shown that $D\left(\mathcal{A}_{j}^{*}\right)$ defined by (A.2) is dense in $\mathcal{H}_{j}$.

The main result of this section is a consequence of the Lemma A. 1 and can be read as follows.

Theorem A.2. Suppose that Assumption 1 and (1.9) are verified. Thus, for each $j \in\{0,1,2\}$, the linear operator $\mathcal{A}_{j}$ defined by (1.14) is the infinitesimal generator of a semigroup of class $C_{0}$ and, for each $n \in \mathbb{N}$ and $U_{0} \in D\left(\mathcal{A}_{j}^{n}\right)$, the system (1.13) has unique solution in the class $U \in$ $\bigcap_{k=0}^{n} C^{k}\left(\mathbb{R}_{+} ; D\left(\mathcal{A}_{j}^{n-k}\right)\right)$.

## References

[1] B. Aksas, S.-E. Rebiai, Uniform stabilization of the fourth order Schrödinger equation, J. Math. Anal. Appl. 446(2017), No. 2, 1794-1813. https://doi .org/10.1016/j . jmaa. 2016.09.065; MR3563060; Zbl 1354.35124
[2] Ben-Artzi, M., Косн, H., Saut, J.-C. Dispersion estimates for fourth order Schrödinger equations, C. R. Acad. Sci. Paris Sér. I Math. 330(2000), 87-92. https://doi .org/10.1016/ S0764-4442 (00)00120-8; MR1745182; Zbl 0942.35160
[3] L. Boltzmann, Zur Theorie der elastischen Nachwirkung, Wien. Ber. 70(1874), 275-306.
[4] L. Boltzmann, Zur Theorie der elastischen Nachwirkung, Ann. Phys. 5(1878), 430-432. https://doi.org/10.1002/andp. 18782411107
[5] R. A. Capistrano-Filho, M. Cavalcante, M. Stabilization and control for the biharmonic Schrödinger equation. Appl. Math. Optim. 84(2021), 103-144. https://doi.org/ 10.1007/s00245-019-09640-8; MR4283923; Zbl 1476.35229
[6] R. A. Capistrano-Filho, A. Pampu, The fractional Schrödinger equation on compact manifolds: Global controllability results, Math. Z. 301(2022), 3817-3848. https://doi. org/10.1007/s00209-022-03045-0; MR4449731; Zbl 1496.35354
[7] C. Cattaneo, Solla conduzione del calore (in Italian), Atti Sem. Mat. Fis. Univ. Modena 3(1948), 83-101. MR0032898; Zbl 0035.26203
[8] M. M. Cavalcanti, V. N. Domingos Cavalcanti, A. Guesmia, M. Sepúlveda, Wellposedness and stability for Schrödinger equations with infinite memory, Appl. Math. Optim. 85(2022), Paper No. 20, 31 pp. https://doi.org/10.1007/s00245-022-09864-1; MR4414105; Zbl 1491.35371
[9] S. Dolecki, D. L. Russell, A general theory of observation and control, SIAM J. Control Opt. 15(1977), 185-220. https://doi.org/10.1137/0315015; MR451141; Zbl 0353.93012
[10] P. Gao, Carleman estimates for forward and backward stochastic fourth order Schrödinger equations and their applications. Evol. Equ. Control Theory 7(2018), No. 3, 465-499. https://doi.org/10.3934/eect.2018023; MR3825876; Zbl 1405.35173
[11] A. Guesmia, Asymptotic stability of abstract dissipative systems with infinite memory. J. Math. Anal. Appl. 382(2011), 748-760. https://doi.org/10.1016/j.jmaa.2011.04.079; MR2810828; Zbl 1225.45005
[12] V. I. Karpman, Stabilization of soliton instabilities by higher-order dispersion: fourth order nonlinear Schrödinger-type equations. Phys. Rev. E. 53(1996), 1336-1339. https: //doi.org/10.1103/PhysRevE.53.R1336
[13] V. I. Karpman, A. G. Shagalov, Stability of soliton described by nonlinear Schrödinger type equations with higher-order dispersion. Phys. D 144(2000), 194-210. https: //doi. org/10.1016/S0167-2789(00)00078-6; MR1779828; Zbl 0962.35165
[14] J. L. Lions, Exact controllability, stabilization and perturbations for distributed systems. SIAM Rev. 30(1988), No. 1, 1-68. https://doi.org/10.1137/1030001; MR931277; Zbl 0644.49028
[15] J. C. Maxwell, On the viscosity or internal friction of air and other gases, Philos. Trans. R. Soc. London 156(1866), 249-268. https://doi.org/10.1098/rstl.1866.0013
[16] B. Pausader, The cubic fourth-order Schrödinger equation, J. Funct. Anal. 256(2009), 2473-2517. https://doi.org/10.1016/j.jfa.2008.11.009; MR2502523; Zbl 1171.35115
[17] T. Tsutsumi, Strichartz estimate for Schrödinger equation of fourth order with periodic boundary condition, Notes of the Institute of Mathematical Analysis, Kyoto University 1914(2014) pp. 104-113.
[18] V. Volterra, Equazioni integro-differenziali della elasticità nel caso della isotropia, Rend. Acc. Naz. Lincei. 18(1909), 577-586.
[19] R. Wen, S. Chai, B.-Z. Guo, Well-posedness and exact controllability of fourth order Schrödinger equation with boundary control and collocated observation. SIAM J. Control Optim. 52(2014), 365-396. https://doi.org/10.1137/120902744; MR3162397; Zbl 1292.93040
[20] R. Wen, S. Chai, B.-Z. Guo, Well-posedness and exact controllability of fourth-order Schrödinger equation with hinged boundary control and collocated observation. Math. Control Signals Systems. 28(2016), Art. 22, 28 pp. https://doi.org/10.1007/s00498-016-0175-4; MR3523659; Zbl 1346.93077
[21] C. Zheng, Z. Zhou, Exact controllability for the fourth order Schrödinger equation, Chinese Ann. Math. Ser. B 33(2012), 395-404. https ://doi .org/10.1007/s11401-012-0711-6; MR2928966; Zbl 1252.93030
[22] C. Zheng, Inverse problems for the fourth order Schrödinger equation on a finite domain, Math. Control Relat. Fields 5(2015), No. 1, 177-189. https://doi.org/10.3934/mcrf. 2015. 5.177; MR3356487; Zbl 1328.35327


[^0]:    ${ }^{\boxtimes}$ Corresponding author. Email: victor.martinez@ufpe.br

[^1]:    ${ }^{1}$ Here $\langle\nabla v(s), \nabla w(s)\rangle:=\sum_{k=1}^{n}\left\langle\partial_{x_{k}} v, \partial_{x_{k}} w\right\rangle$ and $\|\nabla v(s)\|^{2}=\sum_{k=1}^{n}\left\|\partial_{x_{k}} v(s)\right\|^{2}$.

[^2]:    ${ }^{2}$ Now on, we will use the following Poincaré inequality $\|y\|^{2} \leq c_{*}\|\nabla y\|^{2}, y \in H_{0}^{1}(\Omega)$, where $c_{*}>0$ is the Poincaré constant.

