# Multiple subharmonic solutions with prescribed minimal periods for a class of second order impulsive differential systems 

Huaxin $\mathbf{O u}^{\boxtimes}$<br>School of Mathematics and Statistics, Southwest University, Chongqing, 400715, P. R. China

Received 16 January 2023, appeared 27 December 2023
Communicated by Gabriele Bonanno


#### Abstract

In this paper, we obtain three subharmonic solutions with different prescribed minimal periods for a class of second order impulsive differential systems. Our proof is based on level estimates and the least action principle in critical point theory.


Keywords: subharmonic solution, impulsive system, minimal period, variational method.
2020 Mathematics Subject Classification: 34B37, 58E30.

## 1 Introduction and main result

In many evolution processes, the states of systems are changed abruptly at certain instants, which leads to impulsive behaviors in dynamical systems [2,11,13]. In recent years, the investigation of differential equations with impulses got particular attention by a lot of scholars, because of the widespread application of these impulsive differential systems in biology, mechanics, engineering and chaos theory, etc. [5,6,13,21,22].

Some classical approaches, such as the method of upper and lower solutions with the monotone iterative technique, the coincidence degree theory of Mawhin and the fixed point theory, were used to study impulsive problems [2,11]. Especially, in the remarkable work of Nieto and O'Regan [13], by constructing a variational structure, they converted the problem of finding solutions for a second order impulsive equation to that of the existence of critical points for the corresponding energy functional [19]. After that, the variational methods and critical point theory were applied to prove the existence and multiplicity of solutions for second order, fourth order and fractional order impulsive differential equations by more and more researchers, see [1-4,7-11,13,14,16-20].

[^0]Our purpose is to investigate the existence of multiple subharmonic solutions for the following second order impulsive systems

$$
\left\{\begin{array}{l}
\ddot{x}(t)+\nabla V(t, x(t))=0,  \tag{1.1}\\
\Delta\left(\dot{x}^{i}\left(t_{j}\right)\right)=\dot{x}^{i}\left(t_{j}^{+}\right)-\dot{x}^{i}\left(t_{j}^{-}\right)=I_{i j}\left(x^{i}\left(t_{j}\right)\right), i=1,2, \ldots, N, j=1,2, \ldots, l, \\
x(0)=x(p T), \dot{x}(0)=\dot{x}(p T),
\end{array}\right.
$$

where $x \in \mathbb{R}^{N}, \nabla V \in C\left([0, T] \times \mathbb{R}^{N}, \mathbb{R}^{N}\right)$ denotes the gradient of $V$ in $x, I_{i j} \in C\left(\mathbb{R}^{N}, \mathbb{R}\right)$ and impulses occur at instants $t_{j}$ with $j \in \mathbb{Z}^{*}=\mathbb{Z} \backslash\{0\}, 0<t_{1}<\cdots<t_{l}<T$ and $t_{j+l}=t_{j}$.

In [11], Luo, Xiao and $X u$ studied the existence of subharmonic solutions for the equation with non-negative impulses as follows

$$
\left\{\begin{array}{l}
\ddot{x}(t)+f(t, x(t))=0, \quad \text { a.e. } t \in \mathbb{R} \backslash\left\{t_{k} \mid k \in \mathbb{Z}^{*}\right\}, \\
\Delta \dot{x}\left(t_{k}\right)=x\left(t_{k}^{+}\right)-x\left(t_{k}^{-}\right)=I_{k}\left(x\left(t_{k}\right)\right), \quad k \in \mathbb{Z}^{*},
\end{array}\right.
$$

where $f \in C(\mathbb{R} \times \mathbb{R}, \mathbb{R})$ and $I_{k} \geq 0$ are impulses that happen at instants $t_{k}$. Bai and Wang [2] generalized the results in [11] to allow a negative impulse term. Here, motivated by [2,11], we investigate the existence of multiple subharmonic solutions for system (1.1).

By a classical solution of (1.1), we mean a function

$$
x \in\left\{w \in C\left([0, p T], \mathbb{R}^{N}\right):\left.w\right|_{\left[j_{j}, t_{j+1}\right]} \in H^{2}\left(\left[t_{j}, t_{j+1}\right], \mathbb{R}^{N}\right), j=1,2, \ldots, l\right\},
$$

which satisfies the differential equation in (1.1) and the boundary conditions $x(0)=x(p T)$, $\dot{x}(0)=\dot{x}(p T)$, the limits $\dot{x}^{i}\left(t_{j}^{+}\right), \dot{x}^{i}\left(t_{j}^{-}\right), i=1,2, \ldots, N, j=1,2, \ldots, l$, exist and verify the impulsive conditions in (1.1).

Now we state our main result.
Theorem 1.1. Suppose that $V(t, x)$ and $I_{i j}(x)$ satisfy the following conditions.
(H1) $V(t, x)=V(-t, x)=V(t,-x)=V\left(t+\frac{T}{2}, x\right)$ for every $(t, x) \in[0, T] \times \mathbb{R}^{N}$.
(H2) For every $x \in \mathbb{R}^{N}, t \in[0, T]$, there exist constants $\delta>0$ and $A>\bar{A}>0$ such that

$$
V(t, x) \geq \frac{\bar{A}}{2}|x|^{2}, \quad|x| \leq \delta
$$

and

$$
V(t, x)-(\nabla V(t, 0), x) \leq \frac{A}{2}|x|^{2}
$$

(H3) For $i=1,2, \ldots, N, j=1,2, \ldots, l$, there exist constants $d_{i j} \geq 0$ such that

$$
I_{i j}(x) \leq d_{i j}|x|, \quad x \in \mathbb{R}^{N} .
$$

(H4) There exists an integer $p>1$ such that

$$
1-2 \rho p^{2} T>0, \quad \frac{4 \omega^{2}}{\bar{A}-4 D / T}<p^{2}<\frac{\omega^{2} s_{p}^{2}}{2 \rho T \omega^{2} s_{p}^{2}+A+2 \rho / T}
$$

and

$$
\left(\frac{\omega^{2}}{2 p^{2}}-\rho T \omega^{2}-\frac{\rho}{T}\right)|x|^{2}-V(t, x) \rightarrow+\infty, \quad \text { as }|x| \rightarrow \infty
$$

where $\omega=\frac{2 \pi}{T}, \rho=\sum_{j=1}^{l} \sum_{j=1}^{N} d_{i j}, D=\sum_{j=1}^{l}\left(\sum_{i=1}^{N} d_{i j}^{2}\right)^{\frac{1}{2}}$ and $s_{p}$ is the smallest prime factor of $p$.
(H5) $\nabla V$ satisfies

$$
\begin{aligned}
& \int_{0}^{T}|\nabla V(t, 0)|^{2} \mathrm{~d} t<\delta^{2} \min \left\{K_{1}\left(K_{2}-K_{3}\right),\left(K_{1}-\frac{3 \omega^{2} T}{p^{2}}\right)\left(4 K_{2}-K_{3}\right)\right\}, \\
& K_{1}=T\left(\bar{A}-\frac{\omega^{2}}{p^{2}}\right)-4 D, \quad K_{2}=\frac{\omega^{2} s_{p}^{2}}{2 p^{2}}\left(1-2 \rho p^{2} T\right), \quad K_{3}=\frac{A}{2}+\frac{\rho}{T} .
\end{aligned}
$$

(H6) Suppose that $q_{0}$ is rational. If both $x(t)$ and $\nabla V(t, x)$ have minimal period $\frac{q_{0} T}{2}$, then $q_{0}$ is an integer.

Then the impulsive system (1.1) possesses at least three periodic solutions. Two of them have minimal period $p T$ and the other one has minimal period $\frac{p T}{2}$.
Remark 1.2. In [11], Luo, Xiao and Xu investigated second order impulsive differential equations with a non-negative impulse term and obtained the existence of at least one solution with minimal period $p T$. Bai and Wang [2] generalized the results of [11] by proving the existence of at least one solution with prescribed minimal period for second order impulsive systems allowing negative impulse terms. Here, we also do not have to assume that the impulse term is non-negative. Giving a suitable range of $p$ and $\int_{0}^{T}|\nabla V(t, 0)|^{2} \mathrm{~d} t$, we find three solutions with prescribed minimal periods for system (1.1).

## 2 Proof of the theorem

In the first place, we recall some basic notations. Let $p>1$ is an integer, $T>0$. We denote the inner product on $\mathbb{R}^{N}$ by $(\cdot, \cdot) . H_{p T}^{1}\left(\mathbb{R}^{N}\right)$ is a Hilbert space, which defined as

$$
H_{p T}^{1}=\left\{x:[0, p T] \rightarrow \mathbb{R}^{N} \mid x \text { is absolutely continuous, } x(0)=x(p T), \dot{x} \in L^{2}\left(0, p T ; \mathbb{R}^{N}\right)\right\} .
$$

Let $\langle\cdot, \cdot\rangle$ be the inner product on $H_{p T}^{1}$, i.e.

$$
\langle x, y\rangle=\int_{0}^{p T}(\dot{x}, \dot{y}) \mathrm{d} t+\int_{0}^{p T}(x, y) \mathrm{d} t, \quad x, y \in H_{p T}^{1}
$$

which induces the norm $\|x\|=\langle x, x\rangle$. Additionally, the energy functional corresponds to system (1.1) is

$$
\varphi(x)=\int_{0}^{p T}\left[\frac{1}{2}|\dot{x}|^{2}-V(t, x)\right] \mathrm{d} t+\sum_{j=1}^{p l} \sum_{i=1}^{N} \int_{0}^{x^{i}\left(t_{j}\right)} I_{i j}(s) \mathrm{d} s, \quad x \in H_{p T}^{1} .
$$

It follows that

$$
\begin{align*}
\left\langle\varphi^{\prime}(x), y\right\rangle= & \int_{0}^{p T}(\dot{x}, \dot{y}) \mathrm{d} t-\int_{0}^{p T}(\nabla V(t, x), y) \mathrm{d} t \\
& +\sum_{j=1}^{p l} \sum_{j=1}^{N} I_{i j}\left(x^{i}\left(t_{j}\right)\right) y^{i}\left(t_{j}\right), \quad x, y \in H_{p T}^{1} . \tag{2.1}
\end{align*}
$$

Definition 2.1. A function $x$ is called a weak $p T$-periodic solution of (1.1) if and only if the following equation holds

$$
\int_{0}^{p T}(\dot{x}, \dot{y}) \mathrm{d} t+\sum_{j=1}^{p l} \sum_{j=1}^{N} I_{i j}\left(x^{i}\left(t_{j}\right)\right) y^{i}\left(t_{j}\right)=\int_{0}^{p T}(\nabla V(t, x), y) \mathrm{d} t, \quad \forall y \in H_{p T}^{1} .
$$

The critical points of $\varphi$ correspond to periodic solutions of impulsive system (1.1). Indeed, suppose $x$ is a critical point of $\varphi$, by (2.1) and the Definition 2.1, $x$ is a weak $p T$-periodic solution of (1.1). Moreover, for every $y \in H_{p T}^{1}$, we have

$$
\begin{align*}
\left\langle\varphi^{\prime}(x), y\right\rangle & =\int_{0}^{p T}(\dot{x}, \dot{y}) \mathrm{d} t-\int_{0}^{p T}(\nabla V(t, x), y) \mathrm{d} t+\sum_{j=1}^{p l} \sum_{j=1}^{N} I_{i j}\left(x^{i}\left(t_{j}\right)\right) y^{i}\left(t_{j}\right)  \tag{2.2}\\
& =-\int_{0}^{p T}(\ddot{x}, y) \mathrm{d} t-\int_{0}^{p T}(\nabla V(t, x), y) \mathrm{d} t .
\end{align*}
$$

It follows from (2.2) that

$$
\ddot{x}(t)+\nabla V(t, x)=0, \quad \text { a.e. } t \in\left[t_{j}, t_{j+1}\right] .
$$

Then we get $x \in H^{2}\left(\left[t_{j}, t_{j+1}\right], \mathbb{R}^{N}\right)$ and

$$
\ddot{x}(t)+\nabla V(t, x)=0, \quad \text { a.e. } t \in[0, p T] .
$$

Multiplying the above equation by $y \in H_{p T}^{1}$ and integrating over [ $0, p T$, we obtain

$$
\sum_{j=1}^{p l} \sum_{j=1}^{N} \Delta\left(\dot{x}^{i}\left(t_{j}\right)\right) y^{i}\left(t_{j}\right)=\sum_{j=1}^{p l} \sum_{j=1}^{N} I_{i j}\left(x^{i}\left(t_{j}\right)\right) y^{i}\left(t_{j}\right) .
$$

Thus, $\Delta\left(\dot{x}^{i}\left(t_{j}\right)\right)=I_{i j}\left(x^{i}\left(t_{j}\right)\right)$ for $i=1,2, \ldots, N, j=1,2, \ldots, l$, and the impulsive conditions in (1.1) are verified.

For the sake of convenience, let us define a couple of subspaces of $H_{p T}^{1}$. Set

$$
X=\left\{x \in H_{p T}^{1} \mid x(t)=-x(-t)\right\}, \quad Y=\left\{x \in H_{p T}^{1} \left\lvert\, x\left(t+\frac{p T}{2}\right)=-x(t)\right.\right\},
$$

then we can define

$$
\begin{aligned}
X_{1} & =X \cap Y, & & X_{2}=X \cap Y^{\perp}, \\
Y_{1} & =X^{\perp} \cap Y, & & Y_{2}=X^{\perp} \cap Y^{\perp} .
\end{aligned}
$$

Clearly, we have $H_{p T}^{1}=X_{1} \oplus X_{2} \oplus Y_{1} \oplus Y_{2}$. In the following, we denote the norm of $x$ on $L_{p T}^{2}$ and $L_{p T}^{\infty}$ by $\|x\|_{L^{2}}$ and $\|x\|_{\infty}$ respectively.

Lemma 2.2 ([12]). Suppose that $W$ is a reflexive Banach space, $\varphi: W \rightarrow \mathbb{R}$ is weakly lower semi-continuous and coercive on $W$, then $\varphi$ attains its minimum on $W$.

Lemma 2.3. Under condition (H1), critical points of $\varphi$ on $X_{1}$ (or $X_{2}, Y_{1}, Y_{2}$ ) are also critical points of $\varphi$ on $H_{p T}^{1}$. The minimal period of such a critical point is an integer multiple of $\frac{T}{2}$.

Proof. On the one hand, if $x$ is a critical point of $\varphi$ on $X$, then

$$
\left\langle\varphi^{\prime}(x), y\right\rangle=0, \quad \forall y \in X
$$

Let $y \in X^{\perp}$, it can be deduced from (H1) and (2.2) that

$$
\begin{aligned}
\left\langle\varphi^{\prime}(x), y\right\rangle= & -\int_{-\frac{p T}{2}}^{\frac{p T}{2}}(\ddot{x}, y) \mathrm{d} t-\int_{-\frac{p T}{2}}^{\frac{p T}{2}}(\nabla V(t, x), y) \mathrm{d} t \\
= & -\int_{0}^{\frac{p T}{2}}(\ddot{x}, y) \mathrm{d} t-\int_{0}^{\frac{p T}{2}}(\nabla V(t, x), y) \mathrm{d} t \\
& -\int_{0}^{\frac{p T}{2}}(\ddot{x}(-t), y(-t)) \mathrm{d} t-\int_{0}^{\frac{p T}{2}}(\nabla V(-t, x(-t)), y(-t)) \mathrm{d} t \\
= & -\int_{0}^{\frac{p T}{2}}(\ddot{x}, y) \mathrm{d} t-\int_{0}^{\frac{p T}{2}}(\nabla V(t, x), y) \mathrm{d} t \\
& -\int_{0}^{\frac{p T}{2}}(-\ddot{x}(t), y(t)) \mathrm{d} t-\int_{0}^{\frac{p T}{2}}(-\nabla V(t, x(t)), y(t)) \mathrm{d} t \\
= & 0 .
\end{aligned}
$$

Thus, $\left\langle\varphi^{\prime}(x), y\right\rangle=0$, for all $y \in H_{p T}^{1}$.
On the other hand, providing that $x$ is a critical point of $\varphi$ on $X_{1}$, set $y \in X_{2}$, we find

$$
\begin{aligned}
\left\langle\varphi^{\prime}(x), y\right\rangle= & -\int_{-\frac{p T}{2}}^{\frac{p T}{2}}(\ddot{x}, y) \mathrm{d} t-\int_{-\frac{p T}{2}}^{\frac{p T}{2}}(\nabla V(t, x), y) \mathrm{d} t \\
= & -\int_{0}^{\frac{p T}{2}}(\ddot{x}, y) \mathrm{d} t-\int_{0}^{\frac{p T}{2}}(\nabla V(t, x), y) \mathrm{d} t \\
& -\int_{0}^{\frac{p T}{2}}\left(\ddot{x}\left(t-\frac{p T}{2}\right), y\left(t-\frac{p T}{2}\right)\right) \mathrm{d} t \\
& -\int_{0}^{\frac{p T}{2}}\left(\nabla V\left(t-\frac{p T}{2}, x\left(t-\frac{p T}{2}\right)\right), y\left(t-\frac{p T}{2}\right)\right) \mathrm{d} t \\
= & -\int_{0}^{\frac{p T}{2}}(\ddot{x}, y) \mathrm{d} t-\int_{0}^{\frac{p T}{2}}(\nabla V(t, x), y) \mathrm{d} t \\
& -\int_{0}^{\frac{p T}{2}}(-\ddot{x}(t), y(t)) \mathrm{d} t-\int_{0}^{\frac{p T}{2}}(\nabla V(t,-x(t)), y(t)) \mathrm{d} t \\
= & 0 .
\end{aligned}
$$

It follows that $x$ is a critical point of $\varphi$ on $X$. From (2.3) we know that $x$ is a critical point of $\varphi$ on $H_{p T}^{1}$.

By a similar discussion, one can prove the cases of $X_{2}, Y_{1}, Y_{2}$ alike.
If the minimal period of $x(t)$ is $\frac{p T}{2 q}$, where $q$ is an integer. From (1.1) we have

$$
\begin{equation*}
\ddot{x}\left(t+\frac{p T}{2 q}\right)+\nabla V\left(t+\frac{p T}{2 q}, x\left(t+\frac{p T}{2 q}\right)\right)=0 . \tag{2.4}
\end{equation*}
$$

It follows from (2.4) that $\nabla V(t, x(t))$ has minimal period $\frac{p T}{2 q}$. Then by (H6), $\frac{p}{q}$ is an integer, which means that the minimal period of $x(t)$ is an integer multiple of $\frac{T}{2}$.
Lemma 2.4 ([15]). Suppose that $H(t, x) \in C^{1}\left([0, T] \times \mathbb{R}^{N}, \mathbb{R}\right)$ with $H(t, x) \rightarrow+\infty$ as $|x| \rightarrow \infty$ uniformly in $t \in[0, T]$, then there exist a real function $\gamma \in L^{1}([0, T], \mathbb{R})$ and a subadditive function $G: \mathbb{R}^{N} \rightarrow \mathbb{R}$, i.e.

$$
\begin{equation*}
G(x+y) \leq G(x)+G(y), \quad x, y \in \mathbb{R}^{N} \tag{2.5}
\end{equation*}
$$

such that

$$
\begin{gather*}
H(t, x) \geq G(x)+\gamma(t), \quad x \in \mathbb{R}^{N}  \tag{2.6}\\
G(x) \rightarrow+\infty \text { as }|x| \rightarrow \infty  \tag{2.7}\\
0 \leq G(x) \leq|x|+1, \quad x \in \mathbb{R}^{N} \tag{2.8}
\end{gather*}
$$

Lemma 2.5. Under condition (H4), $\varphi$ is coercive on $X_{1}$ (or $X_{2}, Y_{1}$ ).
Proof. From Lemma 2.4 and (H4), there exist $G(x)$ and $\gamma(t) \in L^{1}([0, T], \mathbb{R})$ such that

$$
\begin{equation*}
\left(\frac{\omega^{2}}{2 p^{2}}-\rho T \omega^{2}-\frac{\rho}{T}\right)|x|^{2}-V(t, x) \geq G(x)+\gamma(t) \tag{2.9}
\end{equation*}
$$

To begin with, we claim that $\int_{0}^{p T} G(x) \mathrm{d} t$ is coercive on

$$
X_{1}^{1}=\left\{\left.r \sin \frac{\omega t}{p} \right\rvert\, r \in \mathbb{R}^{N}\right\} \subset X_{1} .
$$

Providing that $\left\{x_{n}\right\}$ is a sequence in $X_{1}^{1}$ with $\left\|x_{n}\right\| \rightarrow \infty$ as $n \rightarrow \infty$, we can set $x_{n}(t)=r_{n} \sin \frac{\omega t}{p}$, where $r_{n} \in \mathbb{R}^{N}$ and $\left|r_{n}\right| \rightarrow+\infty$ as $n \rightarrow \infty$. By (2.7), for every $L>0$, there exists $M>0$ such that

$$
\begin{equation*}
G(x) \geq L, \quad|x| \geq M . \tag{2.10}
\end{equation*}
$$

Since $\left|r_{n}\right| \rightarrow+\infty$ as $n \rightarrow \infty$, there exists $N_{0}>0$ such that $\left|r_{n}\right|>2 M$ for $n>N_{0}$. Furthermore, it is clear that

$$
\begin{equation*}
\left|x_{n}(t)\right|>M, \quad \forall t \in\left[\frac{p T}{12}, \frac{5 p T}{12}\right] \cup\left[\frac{7 p T}{12}, \frac{11 p T}{12}\right], \quad n>N_{0} . \tag{2.11}
\end{equation*}
$$

From (2.10) and (2.11) we have

$$
\int_{0}^{p T} G\left(x_{n}\right) \mathrm{d} t>\frac{2 p L T}{3}, \quad n>N_{0} .
$$

The coercivity of $\int_{0}^{p T} G(x) \mathrm{d} t$ follows from the arbitrariness of $L$ and $\left\{x_{n}\right\}$.
Let $x \in X_{1}$ and $x=x_{1}+x_{2}$, where $x_{1} \in X_{1}^{1}, x_{2} \in\left(X_{1}^{1}\right)^{\perp} \cap X_{1}$. By the Parseval equality,

$$
\begin{equation*}
\left\|\dot{x}_{1}\right\|_{L^{2}}^{2}=\frac{\omega^{2}}{p^{2}}\left\|x_{1}\right\|_{L^{2}}^{2}, \quad\left\|\dot{x}_{2}\right\|_{L^{2}}^{2} \geq \frac{9 \omega^{2}}{p^{2}}\left\|x_{2}\right\|_{L^{2}}^{2}, \quad\left\|\dot{x}_{2}\right\|_{L^{2}}^{2} \geq \frac{9 \omega^{2}}{9 \omega^{2}+p^{2}}\left\|x_{2}\right\|^{2} \tag{2.12}
\end{equation*}
$$

Additionally, (2.5) implies that

$$
\begin{equation*}
G\left(x_{1}\right)=G\left(x-x_{2}\right) \leq G(x)+G\left(-x_{2}\right) . \tag{2.13}
\end{equation*}
$$

It can be deduced from (H3) that

$$
\begin{align*}
\left|\sum_{j=1}^{p l} \sum_{i=1}^{N} \int_{0}^{y^{i}\left(t_{j}\right)} I_{i j}(s) \mathrm{d} s\right| & \leq \sum_{j=1}^{p l} \sum_{i=1}^{N} \frac{1}{2} d_{i j}\left|y\left(t_{j}\right)\right|^{2} \\
& \leq \sum_{j=1}^{p l} \sum_{i=1}^{N} d_{i j}\left(\frac{\|y\|_{L^{2}}^{2}}{p T}+p T\|\dot{y}\|_{L^{2}}^{2}\right)  \tag{2.14}\\
& \leq \frac{\rho}{T}\|y\|_{L^{2}}^{2}+\rho p^{2} T\|\dot{y}\|_{L^{2}}^{2}, \quad y \in H_{p T}^{1} .
\end{align*}
$$

To the best of our knowledge, the formula (2.14) was first proved in [2]. For more details, please refer to (2.9) in [2]. From (H4), (2.9), (2.12), (2.13) and (2.14), we have

$$
\begin{align*}
\varphi(x)= & \frac{1}{2} \int_{0}^{p T}|\dot{x}|^{2} \mathrm{~d} t-\int_{0}^{p T} V(t, x) \mathrm{d} t+\sum_{j=1}^{p l} \sum_{i=1}^{N} \int_{0}^{x^{i}\left(t_{j}\right)} I_{i j}(s) \mathrm{d} s \\
\geq & \left(\frac{1}{2}-\rho p^{2} T\right) \int_{0}^{p T}|\dot{x}|^{2} \mathrm{~d} t-\frac{\rho}{T} \int_{0}^{p T}|x|^{2} \mathrm{~d} t-\int_{0}^{p T} V(t, x) \mathrm{d} t \\
= & \left(\frac{1}{2}-\rho p^{2} T\right) \int_{0}^{p T}\left(\left|\dot{x}_{1}\right|^{2}+\left|\dot{x}_{2}\right|^{2}-\frac{\omega^{2}}{p^{2}}\left|x_{1}\right|^{2}-\frac{\omega^{2}}{p^{2}}\left|x_{2}\right|^{2}\right) \mathrm{d} t \\
& +\int_{0}^{p T}\left[\left(\frac{\omega^{2}}{2 p^{2}}-\rho \omega^{2} T-\frac{\rho}{T}\right)|x|^{2}-V(t, x)\right] \mathrm{d} t  \tag{2.15}\\
\geq & \frac{8}{9}\left(\frac{1}{2}-\rho p^{2} T\right) \int_{0}^{p T}\left|\dot{x}_{2}\right|^{2} \mathrm{~d} t+\int_{0}^{p T}[G(x)+\gamma(t)] \mathrm{d} t \\
\geq & \frac{8}{9}\left(\frac{1}{2}-\rho p^{2} T\right)\left\|\dot{x}_{2}\right\|_{L^{2}}^{2}+\int_{0}^{p T} G\left(x_{1}\right) \mathrm{d} t-\int_{0}^{p T} G\left(-x_{2}\right) \mathrm{d} t+\int_{0}^{p T} \gamma(t) \mathrm{d} t \\
\geq & \frac{8}{9}\left(\frac{1}{2}-\rho p^{2} T\right)\left\|\dot{x}_{2}\right\|_{L_{2}}^{2}+\int_{0}^{p T} G\left(x_{1}\right) \mathrm{d} t-p T\left(1+\left\|x_{2}\right\|_{\infty}+\|\gamma\|_{\infty}\right) \\
\geq & \frac{8 \omega^{2}}{9 \omega^{2}+p^{2}}\left(\frac{1}{2}-\rho p^{2} T\right)\left\|x_{2}\right\|^{2}+\int_{0}^{p T} G\left(x_{1}\right) \mathrm{d} t-C_{1}\left\|x_{2}\right\|-C_{2}
\end{align*}
$$

where $C_{1}$ and $C_{2}$ are positive constants. With $\int_{0}^{p T} G\left(x_{1}\right) \mathrm{d} t$ being coercive on $X_{1}$ and

$$
\|x\| \rightarrow \infty \quad \text { if and only if } \quad\left(\left\|x_{1}\right\|^{2}+\left\|x_{2}\right\|^{2}\right)^{\frac{1}{2}} \rightarrow \infty
$$

it follows from (2.15) that $\varphi(x)$ is coercive on $X_{1}$.
Through replacing $X_{1}^{1}$ with

$$
\begin{aligned}
& X_{2}^{1}=\left\{\left.b \sin \frac{2 \omega t}{p} \right\rvert\, b \in \mathbb{R}^{N}\right\}, \\
& Y_{1}^{1}=\left\{\left.c \cos \frac{\omega t}{p} \right\rvert\, c \in \mathbb{R}^{N}\right\},
\end{aligned}
$$

repeating the above arguments with a small modification, one can prove the coercivity of $\varphi$ on $X_{2}$ and $Y_{1}$.

Proof of Theorem 1.1. According to Lemma 2.2, Lemma 2.3 and Lemma 2.5, there exists $x_{1}^{*} \in X_{1}$ such that

$$
\begin{equation*}
\left\langle\varphi^{\prime}\left(x_{1}^{*}\right), y\right\rangle=0, \quad \forall y \in H_{p T}^{1} . \tag{2.16}
\end{equation*}
$$

In what follows, we show that the minimal period of $x_{1}^{*}$ is $p T$ by contradiction. Suppose that $x_{1}^{*}$ has minimal period $\frac{p T}{q_{1}}$, where $q_{1}>1$ is an integer. From Lemma 2.3, the minimal period of $x_{1}^{*}$ is multiple of $\frac{T}{2}$, which means that $q_{1}=2$ or $q_{1} \geq s_{p}$.

If $q_{1}=2$, by Fourier expansion,

$$
x_{1}^{*}=\sum_{k=1}^{+\infty} a_{k}^{*} \sin \frac{2 k \omega t}{p}, \quad a_{k}^{*} \in \mathbb{R}^{N}
$$

However, for every $x \in X_{1}$, we have

$$
x=\sum_{k=1}^{+\infty} a_{k} \sin \frac{(2 k-1) \omega t}{p}, \quad a_{k} \in \mathbb{R}^{N}
$$

which implies $x_{1}^{*}=0$. It contradicts that $x_{1}^{*}$ has minimal period $\frac{p T}{2}$. So we get $q_{1} \geq s_{p}$ and

$$
\begin{equation*}
x_{1}^{*}=\sum_{k=1}^{+\infty} a_{k}^{*} \sin \frac{k q_{1} \omega t}{p}, \quad a_{k}^{*} \in \mathbb{R}^{N} . \tag{2.17}
\end{equation*}
$$

It can be deduced from Parseval's equality and (2.17) that

$$
\begin{equation*}
\left\|\dot{x}_{1}^{*}\right\|_{L^{2}} \geq \frac{q_{1} \omega}{p}\left\|x_{1}^{*}\right\|_{L^{2}} . \tag{2.18}
\end{equation*}
$$

Now, from (H2), (H4), (2.14) and (2.18), we have

$$
\begin{align*}
\varphi\left(x_{1}^{*}\right)= & \frac{1}{2} \int_{0}^{p T}\left|\dot{x}_{1}^{*}\right|^{2} \mathrm{~d} t-\int_{0}^{p T} V\left(t, x_{1}^{*}\right) \mathrm{d} t-\sum_{j=1}^{p l} \sum_{i=1}^{N} \int_{0}^{\left(x_{1}^{*}\right)^{i}\left(t_{j}\right)} I_{i j}(s) \mathrm{d} s \\
\geq & \frac{1}{2}\left\|\dot{x}_{1}^{*}\right\|_{L^{2}}^{2}-\int_{0}^{p T}\left[V\left(t, x_{1}^{*}\right)-\left(\nabla V(t, 0), x_{1}^{*}\right)\right] \mathrm{d} t-\int_{0}^{p T}\left(\nabla V(t, 0), x_{1}^{*}\right) \mathrm{d} t \\
& -\frac{\rho}{T}\left\|x_{1}^{*}\right\|_{L^{2}}^{2}-\rho p^{2} T\left\|\dot{x}_{1}^{*}\right\|_{L^{2}}^{2}  \tag{2.19}\\
\geq & \left(\frac{1}{2}-\rho p^{2} T\right)\left\|\dot{x}_{1}^{*}\right\|_{L^{2}}^{2}-\left(\frac{A}{2}+\frac{\rho}{T}\right)\left\|x_{1}^{*}\right\|_{L^{2}}^{2}-\|\nabla V(t, 0)\|_{L^{2}}\left\|x_{1}^{*}\right\|_{L^{2}} \\
\geq & \left(\frac{\omega^{2} q_{1}^{2}}{2 p^{2}}-\rho T \omega^{2} q_{1}^{2}-\frac{A}{2}-\frac{\rho}{T}\right)\left\|x_{1}^{*}\right\|_{L^{2}}^{2}-\|\nabla V(t, 0)\|_{L^{2}}\left\|x_{1}^{*}\right\|_{L^{2}} .
\end{align*}
$$

It follows from (H4) and $q_{1} \geq s_{p}$ that

$$
\frac{\omega^{2} q_{1}^{2}}{2 p^{2}}-\rho T \omega^{2} q_{1}^{2}-\frac{A}{2}-\frac{\rho}{T}>0,
$$

which combined with (2.19) yields to

$$
\begin{equation*}
\varphi\left(x_{1}^{*}\right) \geq-\frac{1}{4}\left(\frac{\omega^{2} q_{1}^{2}}{2 p^{2}}-\rho T \omega^{2} q_{1}^{2}-\frac{A}{2}-\frac{\rho}{T}\right)^{-1}\|\nabla V(t, 0)\|_{L^{2}}^{2} \tag{2.20}
\end{equation*}
$$

Choosing $\bar{x}_{1}(t)=\left(\delta \sin \frac{\omega t}{p}, 0, \ldots, 0\right) \in X_{1}$, where $\delta$ defined in (H2), the minimal period of $\bar{x}_{1}(t)$ is $p T$. According to mean value theorem, the Cauchy-Schwarz inequality and (H3), we have

$$
\begin{equation*}
\sum_{j=1}^{p l} \sum_{i=1}^{N} \int_{0}^{\left(\bar{x}_{1}\right)^{i}\left(t_{j}\right)} I_{i j}(s) \mathrm{d} s \leq \sum_{j=1}^{p l} \sum_{i=1}^{N} d_{i j}|\theta|\left|\delta \sin \frac{\omega t_{j}}{p}\right| \leq p \delta^{2} \sum_{j=1}^{l}\left(\sum_{i=1}^{N} d_{i j}^{2}\right)^{\frac{1}{2}} \tag{2.21}
\end{equation*}
$$

where $\theta \in\left(0, \delta \sin \frac{\omega t_{j}}{p}\right)$. In view of (2.21) and (H2), we get

$$
\begin{align*}
\varphi\left(\bar{x}_{1}\right) & =\frac{1}{2} \int_{0}^{p T}\left|\dot{\bar{x}}_{1}\right|^{2} \mathrm{~d} t-\int_{0}^{p T} V\left(t, \bar{x}_{1}\right) \mathrm{d} t+\sum_{j=1}^{p l} \sum_{i=1}^{N} \int_{0}^{\left(\bar{x}_{1}\right)^{i}\left(t_{j}\right)} I_{i j}(s) \mathrm{d} s \\
& \leq \frac{1}{2} \int_{0}^{p T} \delta^{2} \frac{\omega^{2}}{p^{2}} \cos ^{2} \frac{\omega t}{p} \mathrm{~d} t-\int_{0}^{p T} V\left(t, \delta \sin \frac{\omega t}{p}\right) \mathrm{d} t+p \delta^{2} \sum_{j=1}^{l}\left(\sum_{i=1}^{N} d_{i j}^{2}\right)^{\frac{1}{2}} \\
& \leq \frac{1}{4} \delta^{2} \frac{\omega^{2}}{p} T-\int_{0}^{p T} \frac{\bar{A}}{2} \delta^{2} \sin ^{2} \frac{\omega t}{p} \mathrm{~d} t+p \delta^{2} \sum_{j=1}^{l}\left(\sum_{i=1}^{N} d_{i j}^{2}\right)^{\frac{1}{2}}  \tag{2.22}\\
& =\frac{1}{4} \delta^{2} \frac{\omega^{2}}{p} T-\frac{\bar{A}}{4} \delta^{2} p T+p \delta^{2} \sum_{j=1}^{l}\left(\sum_{j=1}^{N} d_{i j}^{2}\right)^{\frac{1}{2}} \\
& =-\frac{1}{4}\left[\delta^{2} p T\left(\bar{A}-\frac{\omega^{2}}{p^{2}}\right)-4 p \delta^{2} \sum_{j=1}^{l}\left(\sum_{i=1}^{N} d_{i j}^{2}\right)^{\frac{1}{2}}\right]
\end{align*}
$$

By (H4), (H5), (2.16), (2.20) and (2.22), we find

$$
\inf _{x \in X_{1}} \varphi(x)=\varphi\left(x_{1}^{*}\right)>\varphi\left(\bar{x}_{1}\right)
$$

That is a contradiction. Hence, there exists a critical point $x_{1}^{*} \in X_{1}$ of $\varphi$ with minimal period $p T$.

Similarly, we can find $x_{2}^{*} \in X_{2}$ such that $\left\langle\varphi^{\prime}\left(x_{2}^{*}\right), y\right\rangle=0$, for every $y \in H_{p T}^{1}$. If the minimal period of $x_{2}^{*}$ is not equal to $\frac{p T}{2}$, then there exists $q_{2}>1$ such that $x_{2}^{*}$ has minimal period $\frac{p T}{2 q_{2}}$. Lemma 2.3 implies that $q_{2} \geq s_{p}$. Additionally, we have

$$
x_{2}^{*}=\sum_{k=1}^{+\infty} b_{k}^{*} \sin \frac{2 k q_{2} \omega t}{p}, \quad b_{k}^{*} \in \mathbb{R}^{N}
$$

and

$$
\begin{equation*}
\left\|\dot{x}_{2}^{*}\right\|_{L^{2}} \geq \frac{2 q_{2} \omega}{p}\left\|x_{2}^{*}\right\|_{L^{2}} \tag{2.23}
\end{equation*}
$$

It follows from (H2), (H4), (2.14) and (2.23) that

$$
\begin{align*}
\varphi\left(x_{2}^{*}\right) & =\frac{1}{2} \int_{0}^{p T}\left|\dot{x}_{2}^{*}\right|^{2} \mathrm{~d} t-\int_{0}^{p T} V\left(t, x_{2}^{*}\right) \mathrm{d} t-\sum_{j=1}^{p l} \sum_{i=1}^{N} \int_{0}^{\left(x_{2}^{*}\right)^{i}\left(t_{j}\right)} I_{i j}(s) \mathrm{d} s  \tag{2.24}\\
& \geq-\frac{1}{4}\left(\frac{2 \omega^{2} q^{2}}{p^{2}}-4 \rho T \omega^{2} q^{2}-\frac{A}{2}-\frac{\rho}{T}\right)^{-1}\|\nabla V(t, 0)\|_{L^{2}}^{2} .
\end{align*}
$$

Let $\bar{x}_{2}(t)=\left(\delta \sin \frac{2 \omega t}{p}, 0, \ldots, 0\right) \in X_{2}$, then $\bar{x}_{2}(t)$ has minimal period $\frac{p T}{2}$. After a computation like (2.22), we get

$$
\begin{equation*}
\varphi\left(\bar{x}_{2}\right) \leq-\frac{1}{4}\left[\delta^{2} p T\left(\bar{A}-\frac{4 \omega^{2}}{p^{2}}\right)-4 p \delta^{2} \sum_{j=1}^{l}\left(\sum_{i=1}^{N} d_{i j}^{2}\right)^{\frac{1}{2}}\right] \tag{2.25}
\end{equation*}
$$

Taking (H4), (H5), (2.24) and (2.25) into consideration, we obtain

$$
\inf _{x \in X_{2}} \varphi(x)=\varphi\left(x_{2}^{*}\right)>\varphi\left(\bar{x}_{2}\right)
$$

This contradiction leads to the fact that the minimal period of $x_{2}^{*}$ is $\frac{p T}{2}$.
Using a similar argument, a critical points $y_{1}^{*}$ of $\varphi$ with minimal period $p T$ can be found on $Y_{1}$. It is clear that $x_{1}^{*}, x_{2}^{*}$ and $y_{1}^{*}$ are nonzero, which combines with $H_{p T}^{1}=X_{1} \oplus X_{2} \oplus Y_{1} \oplus Y_{2}$ to give that three points are different.

## 3 Example

To show how our theorem applies in practice, we give the following example.
Example 3.1. Consider the impulsive system (1.1) with $T=1, N=l=p=3$,

$$
I_{i j}(s)=\frac{|s|}{3240}, \quad i, j \in\{1,2,3\}
$$

and

$$
V(t, x)= \begin{cases}\frac{7-\cos 4 \pi t}{18} \omega^{2}|x|^{2}, & |x| \leq 1, \\ \left(\frac{68 \pi^{2}-1}{162}-\frac{7-\cos 4 \pi t}{18} \omega^{2}-\frac{1}{2}\right)|x|^{2} & \\ +\left(\frac{7-\cos 4 \pi t}{9} \omega^{2}-\frac{68 \pi^{2}-1}{162}+\frac{1}{2}\right)(2|x|-1), & 1<|x| \leq 2, \\ \frac{68 \pi^{2}-1}{324}|x|^{2}-\ln |x|^{2}+\frac{7-\cos 4 \pi t}{9} \omega^{2}-\frac{68 \pi^{2}-1}{162}+2 \ln 2-\frac{1}{2}, & |x|>2\end{cases}
$$

We can take

$$
\omega=2 \pi, \quad \rho=\frac{1}{4 p^{2} s_{p}^{2}}=\frac{1}{324},
$$

then

$$
\left(1-2 \rho p^{2} T\right) \frac{\omega^{2}}{2 p^{2}}-\frac{\rho}{T}=\frac{68 \pi^{2}-1}{324} .
$$

It is easy to verify that $V(t, x)$ satisfies (H1). Let

$$
d_{i j}=\frac{\rho}{9}, \quad i, j \in\{1,2,3\},
$$

and

$$
A=\frac{8}{9} \omega^{2}, \quad \bar{A}=\frac{2}{3} \omega^{2}, \quad \delta=1,
$$

then $D=\frac{\rho}{3}$. One can easily check that (H3) is true and $V(t, x)$ satisfies (H2), (H4) and (H5). By Theorem 1.1, Example 3.1 possesses at least three periodic solutions. Two of them have minimal period 3 and the other one has minimal period 1.5.

## References

[1] L. Bai, J. J. Nieto, Variational approach to differential equations with not instantaneous impulses, Appl. Math. Lett. 2017, No. 73, 44-48. https://doi.org/10.1016/j.aml. 2017. 02.019; MR3659906; Zbl 1382.34028
[2] L. Bai, X. Wang, Subharmonic solutions with prescribed minimal period for a class of second order impulsive systems, Electron. J. Qual. Theory Differ. Equ. 2017, No. 54, 1-11. https://doi.org/10.14232/ejqtde.2017.1.54; MR3680247; Zbl 1413.34149
[3] G. Bonanno, B. Di Bella, J. Henderson, Existence of solutions to second-order boundary-value problems with small perturbations of impulses, Electron. J. Differential Equations 2013, No. 126, 1-14. MR3065079; Zbl 1292.34028
[4] G. Bonanno, R. Rodríguez-López, S. Tersian, Existence of solutions to boundary value problem for impulsive fractional differential equations, Fract. Calc. Appl. Anal. 17(2014), No. 3, 717-744. https://doi.org/10.2478/s13540-014-0196-y; MR3260304; Zbl 1308.34010
[5] T. E. Carter, Necessary and sufficient conditions for optimal impulsive rendezvous with linear equations of motion, Dynam. Control 10(2000), No. 3, 219-227. https://doi.org/ 10.1023/A:1008376427023; MR1809484; Zbl 0980.93058
[6] C.-C. Chang, C. Q. Liu, R. L. Huston, Dynamics of multibody systems subjected to impulsive constraints, Multibody Syst. Dyn. 8(2002), No. 2, 161-184. https://doi.org/ 10.1023/A:1019537611060; MR1923339; Zbl 1034.70004
[7] H. Chen, Z. He, Multiplicity of solutions for second-order Hamiltonian systems with impulses, J. Appl. Math. Comput. 42(2013), No. 1-2, 69-87. https://doi.org/10.1007/ s12190-012-0621-5; MR3061815; Zbl 1300.34063
[8] F. Kong, Subharmonic solutions with prescribed minimal period of a forced pendulum equation with impulses, Acta Appl. Math. 158(2018), No. 1, 125-137. https://doi.org/ 10.1007/s10440-018-0177-y; MR3869474; Zbl 1407.34055
[9] C. Li, L. Li, H. Yang, Infinitely many solutions for non-autonomous second-order systems with impulsive effects, J. Appl. Anal. Comput. 10(2020), No. 2, 427-441. https: //doi.org/10.11948/20180131; MR4061076; Zbl 1455.34026
[10] Z. Liang, Z. Yao, Subharmonic oscillations of a forced pendulum with time-dependent damping, J. Fixed Point Theory Appl. 22(2019), No. 1, Paper No. 1, 10 pp. https://doi. org/10.1007/s11784-019-0746-3; MR4044530; Zbl 1434.31002
[11] Z. Luo, J. Xino, Y. $\mathrm{Xu}_{\mathrm{u}}$, Subharmonic solutions with prescribed minimal period for some second-order impulsive differential equations, Nonlinear Anal. 75(2012), No. 4, 2249-2255. https://doi.org/10.1016/j.na.2011.10.023; MR2870914; Zbl 1248.34011
[12] J. Mawhin, M. Willem, Critical point theory and Hamiltonian systems, Applied Mathematical Sciences, No. 74, Springer-Verlag, New York, 1989. xiv+277 pp. Springer New York, New York, 1989. https://doi.org/10.1007/978-1-4757-2061-7; MR982267; Zbl 0676.58017
[13] J. J. Nieto, D. O'Regan, Variational approach to impulsive differential equations, Nonlinear Anal. Real World Appl. 10(2009), No. 2, 680-690. https ://doi. org/10.1016/j .nonrwa. 2007.10.022; MR2474254; Zbl 1167.34318
[14] Q. Wang, D. Lu, Z. Zheng, Subharmonic solutions with prescribed minimal periodic for a class of second-order impulsive functional differential equations, Abstr. Appl. Anal. 2012, 457163. https://doi.org/10.1155/2012/457163; MR2959748; Zbl 1251.34088
[15] X.-P. Wu, C.-L. Tang, Periodic solutions of nonautonomous second-order Hamiltonian systems with even-typed potentials, Nonlinear Anal. 55(2003), No. 6, 759-769. https :// doi.org/10.1016/j.na.2003.08.009; MR2060528; Zbl 1030.37043
[16] J. Xiao, J. J. Nieto, Variational approach to some damped Dirichlet nonlinear impulsive differential equations, J. Franklin Inst. 348(2011), No. 2, 369-377. https://doi.org/10. 1016/j.jfranklin.2010.12.003; MR2771846; Zbl 1228.34048
[17] J. Xie, Z. Luo, Subharmonic solutions with prescribed minimal period of an impulsive forced pendulum equation, Appl. Math. Lett. 52(2016), 169-175. https://doi.org/10. 1016/j.aml.2015.09.006; MR3416402; Zbl 1380.34065
[18] X. Yang, Existence and multiplicity of weak solutions for a nonlinear impulsive ( $q, p$ )Laplacian dynamical system, Adv. Difference Equ. 2017, No. 1, 128. https://doi.org/10. 1186/s13662-017-1145-y; MR3646528; Zbl 1422.34234
[19] W. Yao, Variational approach to non-instantaneous impulsive differential equations with p-Laplacian operator, AIMS Math. 7(2022), No. 9, 17269-17285. https://doi.org/10. 3934/math. 2022951; MR4468475
[20] X. Zhang, Subharmonic solutions for a class of second-order impulsive Lagrangian systems with damped term, Bound. Value Probl. 2013, No. 218, 1-17. https://doi.org/10. 1186/1687-2770-2013-218; MR3341416; Zbl 1303.37019
[21] W. Zhang, M. Fan, Periodicity in a generalized ecological competition system governed by impulsive differential equations with delays, Math. Comput. Modelling 39(2004), No. 4, 479-493. https://doi.org/10.1016/S0895-7177(04)90519-5; MR2046535; Zbl 1065.92066
[22] X. Zhang, Z. Shuai, K. Wang, Optimal impulsive harvesting policy for single population, Nonlinear Anal. Real World Appl. 4(2003), No. 4, 639-651. https ://doi .org/10.1016/ S1468-1218(02)00084-6; MR1962293; Zbl 1011.92052


[^0]:    ${ }^{\boxtimes}$ Email: ouhx2020@163.com

